

Privacy Advisory Commission October 1, 2020 5:00 PM Online Zoom Meeting 1 Frank H. Ogawa Plaza, 1st Floor *Meeting Agenda*

Commission Members: **District 1 Representative**: Reem Suleiman, **District 2 Representative**: Chloe Brown, **District 3 Representative**: Brian Hofer, Chair, **District 4 Representative**: Lou Katz, **District 5 Representative**: Omar De La Cruz, **District 6 Representative**: Gina Tomlinson, **District 7 Representative**: Robert Oliver, **Council At-Large Representative**: Henry Gage III, Vice Chair **Mayoral Representative**: Vacant

Each person wishing to speak on items must fill out a speaker's card. Persons addressing the Privacy Advisory Commission shall state their names and the organization they are representing, if any.

Please click the link below to join the webinar:

https://us02web.zoom.us/j/87682009470

Or iPhone one-tap :

US: +16699009128, 87682009470# or +12532158782,,87682009470#

Or Telephone:

Dial (for higher quality, dial a number based on your current location):

US: +1 669 900 9128 or +1 253 215 8782 or +1 346 248 7799 or +1 301 715 8592 or +1 312 626 6799 or +1 646 558 8656

Webinar ID: 876 8200 9470

International numbers available: https://us02web.zoom.us/u/keocy586Q3

- 1. Call to Order, determination of quorum
- 2. Open Forum/Public Comment
- 3. Review and approval of the draft September meeting minutes
- 4. Surveillance Equipment Ordinance OPD Exigent Circumstances Use Report (UAV) review and take possible action.

- 5. Surveillance Equipment Ordinance OPD Live Stream Use Reports (2) review and take possible action.
- 6. Surveillance Equipment Ordinance OPD Crime Lab Biometric Technology Impact Report and proposed Use Policy -review and take possible action.
- 7. Surveillance Equipment Ordinance Amendments Hofer/Gage/De La Cruz review and take possible action.
 - a. Prohibition On Predictive Policing And Remote Biometric Surveillance Technology
 - b. Annual Report metrics and due dates
 - c. Additional cleanup language



Privacy Advisory Commission September 3, 2020 5:00 PM Zoom Online Meeting *Meeting Minutes*

Commission Members: **District 1 Representative**: Reem Suleiman, **District 2 Representative**: Chloe Brown, **District 3 Representative**: Brian Hofer, Chair, **District 4 Representative**: Lou Katz, **District 5 Representative**: Omar De La Cruz, **District 6 Representative**: Gina Tomlinson, **District 7 Representative**: Robert Oliver, **Council At-Large Representative**: Henry Gage III, Vice Chair **Mayoral Representative**: Vacant

Each person wishing to speak on items must fill out a speaker's card. Persons addressing the Privacy Advisory Commission shall state their names and the organization they are representing, if any.

1. Call to Order, determination of quorum

Members Present: Suleiman, Brown, Hofer, De La Cruz, Tomlinson, Oliver, Gage.

2. Open Forum/Public Comment

There was one public speaker: Asada Olugbala voiced concern that the oversight function of the PAC and other City bodies appears to monitor a variety of different operations in the protection of many populations but falls short in monitoring when the impacted community is African American. She also is concerned that some of the limitations the PAC supports will inadvertently protect criminals.

3. Review and approval of the draft August meeting minutes

The minutes were approved unanimously with one correction: Breonna Taylor's name was misspelled.

4. Surveillance Equipment Ordinance – OPD – Forensic Logic Impact Report and proposed Use Policy - review and take possible action.

The ad hoc committee draft Use Policy was presented for full approval and there was agreement on almost all the components of the policy after many meetings with OPD. However, DC Holmgren raised concern about the requirement that agencies outside Alameda County would not have access to Oakland data. He noted that many crime rings are Bay Area-wide and cross far into other states. Bob Batty with Forensic Logic cited an example of a human trafficking case from San Francisco was cited as an instance of where Oakland data was available to the SF DA and led to the conviction.

However, Commissioner Suleiman noted her and other commissioners discomfort with how readily available the Oakland data is to any other jurisdiction. Chairperson Hofer noted that if the restriction on sharing Oakland data outside Alameda County was proving to be problematic, during the annual review, it could be modified. Joe DeVries asked if the PAC would consider expanding to the Bay Area region and/or CA since all California jurisdictions are prohibited from data sharing with ICE through SB 54 but that suggestion did not receive support.

Other items discussed included audit trails, data security and management and predictive policing (which was restricted as per the policy).

The Use Policy was adopted with 5 yeas and 2 abstentions.

5. Surveillance Equipment Ordinance – OPD – Exigent Circumstances Use Reports – review and take possible action.

Sgt. Daza-Quiroz presented three reports of the use of UAS due to exigent circumstances. There were some questions as to whether the circumstance in the April 7th report were actually exigent and suggested that perhaps training on exigency at OPD might be worthwhile. However, it was noted that the already approved Use Policy for drones, once adopted by City Council, would eliminate the need for these reports as the circumstances would be allowable under that policy.

There was one public speaker, Asada Olugbala spoke about her concern when OPD has a "belief" that someone may be armed and dangerous, this can deadly for suspects.

The reports were adopted unanimously.

6. Surveillance Equipment Ordinance – OPD – Live Stream Use Reports – review and take possible action.

This first set of Live Stream Reports was tabled at the request of OPD so that the reports could include more information than the first drafts contained. They will come back next month.

7. Surveillance Equipment Ordinance Amendments – Hofer/Patterson/Gage – review and take possible action.

The PAC reviewed both the ad hoc and OPD's proposed edits to the ordinance, especially the language surrounding biometric technology. A center of the debate was OPD's request that Crime Lab technology that is currently in use be exempted as it does not consider the uses in the lab to qualify as surveillance.

Joe DeVries noted that he does not believe the current definition in the ordinance contemplated the oversight of the crime lab as the data it processes is taken from an active crime scene, and does not constitute the mass gathering of data as is typically the case with broad surveillance technology. He also noted concern that the Crime Labs core functions could be seriously derailed if a lengthy process of developing a Use Policy were to ensue, citing upcoming grant deadlines, supply shortages, and equipment that is at the end of its life.

Chairperson Hofer noted that the definition in the ordinance does not make that exception and that he felt the Crime Lab could easily have a Use Policy adopted by the PAC if one is submitted. He asked if any commissioner wanted to make a motion to exempt the lab as per the draft language that OPD submitted but no commissioner indicated an interest in doing so.

Further discussion is needed on other portions of the proposed ordinance revisions and the item was tabled until the following month.

There was one Public Speaker on the item: Asada Olugbala applauded the PAC for not supporting any exemptions to the ordinance.

8. Sanctuary Contracting Ordinance – CPO – Annual Report – review and take possible action.

Joe DeVries presented the first annual report and it was adopted unanimously.

ITEM 4



MEMORANDUM

 TO: Privacy Advisory Commission
 SUBJECT: Use of Unapproved Surveillance Technology Under Exigent Circumstances – August 5 and August 7, 2020 **FROM:** Susan E. Manheimer **DATE:** August 13, 2020

RECOMMENDATION

Receive an informational report regarding the use of unapproved surveillance technology under exigent circumstances in accordance with Oakland Municipal Code (OMC) 9.64.035.

EXECUTIVE SUMMARY

In accordance with OMC 9.64.035, the Oakland Police Department (OPD) used surveillance technology under exigent circumstances; the situations were a carjacking and in the context of barricaded shooting suspects. The technology is Unmanned Aerial System (UAS), commonly known as a drone.

BASIS FOR EXIGENCY

RD #20-038696 Incident: LOP200805001017 Location: 10400 Blk of Pippin Street, Oakland (Beat 33)

On August 5, 2020, at about 11:02 PM, OPD officers responded to the 10400 block of Pippin Street, in the City of Oakland, to assist the San Leandro Police Department (SLPD) on an Officer involved shooting (OIS). 10400 Block is in the City of Oakland and a residential area. Upon OPD's arrival, it was discovered the SLPD had been involved in a vehicle pursuit and foot pursuit of an armed subject, which led them to the Oakland residential neighborhood. During the incident, a SLPD officer discharged their firearm striking the suspect. The officers and medical personnel provided aid to the suspect, but the suspect succumbed to his injuries at the scene. The K-9 (dog) of the SLPD Officer ran from the scene during the OIS. The OPD Homicide and Officer Involved Shooting Team responded to the scene.

The OPD Homicide Commander requested ACSO UAS (Drone) deployment to assist with documentation of the crime scene and to locate the missing K-9 (dog). ACSO deployed (1) one UAS in the area to locate the missing SLPD's K-9 and photograph the scene and evidence. The missing SLPD K-9 was found over a mile away by a member of the public.

The utilization of the UAS was to assist the OPD Technician photograph the scene, which provided an overview for Homicide Investigators. Additionally, the UAS was utilized to locate the missing SLPD K-9 (dog). The photos obtained through the UAS were taken from a position the technician

could not get to. Furthermore, the scene was too large to get a view of all the items in the same photo.

ACSO captured numerous photographs and a video. Some of the evidence items captured were on the front driveway area of a residence as the suspect had run onto the property.

RD# 20-039029 Inc# Inc# LOP200807001206 Location 1500 92nd Av, Oakland, CA (Beat 34)

RD# 20-039029

On August 7th, 2020, at approximately 11:51PM, OPD officers responded to a report of a shooting in the area of 1500 92nd Ave, which is primarily a residential area. Officers arrived on scene and located an Oakland resident suffering from an apparent gunshot wound(s). The person succumbed to his injuries and was pronounced deceased on scene. A Homicide callout was initiated, and the investigators responded to begin the follow-up investigation into the circumstances surrounding the death. At this time, there have be no arrests made and the suspect(s) are still outstanding.

At the time of the shooting, there was no available OPD technician available to assist with photographs, scene diagrams, or evidence collection. OPD Command elected to utilize ACSO UAS to assist with photographs scene diagrams, and mapping. The scene stretched (3) three city blocks and there were over 180 pieces of evidence.

ACSO captured numerous photographs and a video. All the evidence items were captured on city streets and sidewalks. OPD collected and turned in the evidence after the ACSO UAS concluded with their assistance

DEVICE USE INFORMATION

The UAS detection equipment was provided by, and operated by the Alameda County Sheriff's Office (ACSO) – on August 5 and August 7, 2020 incidents.

Video Recorded

The UAS recorded video of the area where it was deployed. The UAS also captured photographs per the request of OPD Homicide Investigators.

Retention of Recordings

Per ACSO policy, the video recording and photographs will be maintained by ACSO for three years.

Usefulness in Homicide Investigation

The UAS was utilized in connection with the August 5, 2020 OIS incident. The UAS assisted in capturing photographs and video recording the scene. The This provided Homicide Investigators and the Officer Involving Shooting Team with an aerial view of the incident and also of photographs the OPD technician could not get to.

The UAS was utilized in connection with the August 7, 2020 homicide investigation. OPD Officers were investigating a homicide in the City of Oakland involving an Oakland resident. The UAS assisted photographing and video recording the scene. The area encompassed (3) three city blocks and over 180 pieces of evidence. There were no OPD technicians working, and the shooting scene stretched from one end of the block to the other end. The UAS assisted Homicide investigators with an aerial view and with photographs of the entire area.

COMPLIANT USE

The following information relating to helicopter and UAS is required by OMC 9.64.035, and shows that each technology was used in accordance with the OMC.

- A. The UAS detection equipment was used solely to respond to the exigency.
- B. Use of the UAS detection equipment ceased when the exigency ended.
- C. Only data related to the exigency was kept.
- D. This report is being provided to the Privacy Advisory Commission at its next meeting with a recommendation that it be forwarded to City Council.

OPD never had possession of the UAS detection equipment. ACSO maintained possession of the equipment during the entire equipment usage period.

Reviewed by: Roland Holmgren, Deputy Chief Bureau of Field Operations

Prepared by: Omar Daza-Quiroz, Lieutenant OPD, Bureau of Field Operations

Bruce Stoffmacher, Management Assistant OPD, Training Division, Research and Planning Section

ITEM 5

CITYOFOAKLAND

Memorandum

| ATTN: | Director Joe Devries |
|-------|--|
| FROM: | Captain Randell Wingate |
| DATE: | September 23, 2020 |
| RE: | Report on Video Stream Usage: August 28-29, 2020 |

This memorandum summarizes the use of Live Stream Transmitters by the Oakland Police Department (OPD), in support of the specified event.

Departmental General Order (DGO) I-23: Live Stream Transmitter Use Policy requires that for each use of live stream transmitters, OPD shall articulate the facts and circumstances surrounding the use in a written statement filed with the Chief Privacy Officer and/or Chair of the Privacy Advisory Commission within 72 hours.

RD# or Incident #: 20-042759

- Date of Incident: 28 AUG 20
- **Type of Event**: Protest
- Was EOC/DOC activated: YES
- Number of Video Streams provide to EOC/DOC: 3 video streams

RD# or Incident #: 20-042912

- Date of Incident: 29 AUG 20
- **Type of Event**: Protest
- Was EOC/DOC activated: YES
- Number of Video Streams provide to EOC/DOC: 3 video streams

Basis for Use: Video Teams were requested by Captain Wingate on 27 Aug 20, after analysis of the event (28 Aug 20). The intelligence gathered from open source social media outlets indicated a large group of people were gathering on 28 Aug 20, to commit acts of violence and vandalism. The organizer(s) posted language referring to "burning it down". The recent protests and social media displaying similar language consistently resulted in acts of violence, vandalism, and scars on our downtown community.

The use of the live stream met the DGO requirements as the EOC was placed in operation by the City Administrator and the crowd size was predicted to be large enough to render oversight and control difficult. The late evening start time reduced the Air Unit's (helicopter) flight duration. The Air Unit provides practically the only means of achieving active crowd size and activity information. Three video streams were provided by the Video Teams to the EOC. The Video teams were effectively used to monitor officer conduct, supervision, crowd size, and crowd activity. OPD could not identify political speakers nor anyone willing to communicate with OPD.

The event for 28 Aug 20, ended with social media posts calling all protesters back for the night of 29 Aug 20. This created a second request for the video teams for this event. The information gathered from public sources again justified live transmitter use for upcoming protests; crowd size was again anticipated to be large enough to make command and control very difficult. The video teams were effective in gaining real time information on the officers' posture, crowd activity, crowd size, effectiveness of the filed supervision, and need for police presence.

Randell Wingate Captain of Police Support Operations Division Oakland Police Department

Inez Ramirez III Sergeant of Police Bureau of Services Administration Oakland Police Department

CITYOFOAKLAND

Memorandum

| ATTN: | Director Joe Devries |
|-------|---|
| FROM: | Captain Randell Wingate |
| DATE: | September 23, 2020 |
| RE: | Report on Video Stream Usage: August 26, 2020 |

This memorandum summarizes the use of Live Stream Transmitters by the Oakland Police Department (OPD), in support of the specified event.

Departmental General Order (DGO) I-23: Live Stream Transmitter Use Policy requires that for each use of live stream transmitters, OPD shall articulate the facts and circumstances surrounding the use in a written statement filed with the Chief Privacy Officer and/or Chair of the Privacy Advisory Commission within 72 hours.

RD# or Incident #: 20-042337 **Date of Incident**: 26 AUG 20 **Type of Event**: Protest **Was EOC/DOC activated**: YES

Basis for Use: **Basis for Use**: Video Teams were requested by Captain Wingate on 25 Aug 20, after analysis of the upcoming protest event - intelligence gathered from open source social media indicated a large group of people were gathering for an anti-police protest in solidarity with protesters in Wisconsin. The social media posts spoke of violence on police officers and lighting fires in Oakland. Nationally, other agencies had seen days of violence starting on Aug 23, 2020 (the day of the Wisconsin shooting¹). Since the George Floyd event, OPD has noted people coming to Oakland to mirror nonpeaceful criminal behavior.

The use of the live stream transmitter met the DGO requirements as the EOC was placed in full operation by the City Administrator and the crowd size was predicted to be large enough to make command and control difficult. The California wildfires impacted the air quality and Air Unit visibility. The Air Unit is also used as a tool to give updates on crowd size and activity. The single Video Team was used to send real time images to the EOC.

The Video team was effectively used to monitor officer conduct, supervision, crowd size, crowd activity, and for real time situational awareness.

¹ In the August 23, 2020 incident, Kenosha PD officers shot Jacob Blake, an African American male seven times related to a domestic dispute call for service; the event was captured on phone video by a bystander.

Number of Video Streams provide to EOC/DOC: 1 video stream

Randell Wingate Captain of Police Support Operations Division Oakland Police Department

Inez Ramirez III Sergeant of Police Bureau of Services Administration

CITYOFOAKLAND

Memorandum

| ATTN: | Director Joe Devries |
|-------|---|
| FROM: | Captain Randell Wingate |
| DATE: | September 23, 2020 |
| RE: | Report on Video Stream Usage: July 25, 2020 |

This memorandum summarizes the use of Live Stream Transmitters by the Oakland Police Department (OPD), in support of the specified event.

Departmental General Order (DGO) I-23: Live Stream Transmitter Use Policy requires that for each use of live stream transmitters, OPD shall articulate the facts and circumstances surrounding the use in a written statement filed with the Chief Privacy Officer and/or Chair of the Privacy Advisory Commission within 72 hours.

RD# or Incident #: 20-036638 Date of Incident: 25 JUL 20 Type of Event: Protest Was EOC/DOC activated: YES

Basis for Use: Video Teams were requested by Captain Wingate on 23 JUL 20, after analysis of this event. The intelligence gathered from open source social media outlets indicated a large group of people were gathering on 25 Jul 20, to commit acts of violence and vandalism. The group planned to start the protest with shield training. This activity is indicative of known agitator groups who hijack large peaceful protests. The shield training indicates a greater expectation – if not intent - for a violent intent.

The use of the live stream transmitters met the DGO requirements as the EOC was placed in operation by the City Administrator and the crowd size was predicted to be large enough to make command and control difficult. The late starting protest also reduced the Air Unit's usefulness and flight duration capacity. The Air Unit (helicopter) provides one of the only means OPD Command possesses for real-time information regarding crowd size and activity. Two video streams were provided by the Video Teams to the EOC.

The Video teams were effectively used to monitor officer conduct, supervision, crowd size, crowd activity, and for real time situational awareness. There were no political speakers and the crowd was not willing to communicate with OPD.

Number of Video Streams provide to EOC/DOC: 2 video streams

Randell Wingate Captain of Police Support Operations Division Oakland Police Department

Inez Ramirez III Sergeant of Police Bureau of Services Administration Oakland Police Department

CITYOFOAKLAND

Memorandum

| ATTN: | Director Joe Devries |
|-------|--|
| FROM: | Captain Randell Wingate |
| DATE: | September 23, 2020 |
| RE: | Report on Video Stream Usage: May - June, 2020 |

This memorandum summarizes the use of Live Stream Transmitters by the Oakland Police Department (OPD), in support of the George Floyd event.

Departmental General Order (DGO) I-23: Live Stream Transmitter Use Policy requires that for each use of live stream transmitters, OPD shall articulate the facts and circumstances surrounding the use in a written statement filed with the Chief Privacy Officer and/or Chair of the Privacy Advisory Commission within 72 hours.

RD# or Incident #: 20-026713

- **Date of Incident:** 30 MAY 20
- **Type of Event**: Protest
- Was EOC/DOC activated: YES
- Number of Video Streams provide to EOC/DOC: 2 video streams

RD# or Incident #: 20-026817

- **Date of Incident:** 31 MAY 20
- **Type of Event:** Protest
- Was EOC/DOC activated: YES
- Number of Video Streams provide to EOC/DOC: 2 video streams

RD# or Incident #: 20-027034

- Date of Incident: 01 JUN 20
- **Type of Event**: Protest
- Was EOC/DOC activated: YES
- Number of Video Streams provide to EOC/DOC: 2 video streams

RD# or Incident #: 20-027193

- Date of Incident: 02 JUN 20
- **Type of Event:** Protest
- Was EOC/DOC activated: YES
- Number of Video Streams provide to EOC/DOC: 2 video streams

RD# or Incident #: 20-027341

- Date of Incident: 03 JUN 20
- Type of Event: Protest
- Was EOC/DOC activated: YES
- Number of Video Streams provide to EOC/DOC: 2 video streams

The nationwide protests that started on May 29, 2020 was the most devastating crowd control event in the history of Oakland. The George Floyd video created outrage with countless numbers of people locally, nationally, and globally. OPD officers and professional staff share in this outrage. OPD Command had very limited time to plan for protests once it became clear that large protests were likely to occur; OPD lacked specific intelligence signaling likely protests until late afternoon on May 28th; there is no Video Team request for the first evening of protests on 29 May 20.

The protests in late May and early June occurred somewhat continuously over several days; for this reason, the usage dates are included above and described here with one narrative. The usage continued until large protest activity ceased on 4 Jun 20. Captain Wingate requested the use of the video teams each day. The full activation of the Emergency Operations Center (EOC) was ordered by the City Administrator during this entire operational period.

The devastation which occurred on 29 May 20 justified the use of video teams on subsequent evenings. The downtown area had over 15,000 people massed in about three different clusters. The largest cluster occurred at 8th and Broadway; people in this area posted on social media the intent to burn down OPD's main Police Administration Building at 455 7th Street. Several other police department buildings nationwide had been set on fire. OPD was on a full deployment and had to call mutual aid before the sun went down.

Throughout the night Oakland was looted, burned, and destroyed by the unruly and very violent crowds. OPD and the several hundred personnel from outside police agencies were extremely outnumbered. Additionally, OPD was responding to the murder of a Federal Security Agent (which occurred at the Federal Building blocks from City Hall), burning businesses, and widespread acts of looting.

The use of the live stream video teams on the above listed nights was necessary to provide commanders with real time situational information. It is important to note the incredibly difficult task of commanding and controlling outside agencies in the field assisting OPD. When a directive is given by the Incident Commander, the most rapid way to ensure the message is clear and being executed is to see the officers in the field carrying out these directives. The average operational period would have up to 900 officers in Oakland participating in crowd management and addressing criminal activity.

The Video Teams were only used from a distance to capture the totality of the crowd size, activity, officer posture, and field supervision.

Randell Wingate Captain of Police Support Operations Division Oakland Police Department

Inez Ramirez III Sergeant of Police Bureau of Services Administration Oakland Police Department

ITEM 6

Oakland Police Department Criminalistics Laboratory DNA Instrumentation and Analysis and Software Surveillance Impact Report September 2020

1. Description

The Oakland Police Department (OPD) Criminalistics Laboratory's (Crime Lab) Forensic Biology/DNA unit utilizes specialized DNA collection and analysis instrumentation and software to perform forensic DNA testing. This is a biometric analysis which produces potentially sensitive information.

During the lengthy and complicated process to obtain a DNA profile from evidence or a reference sample, numerous steps may be necessary including, but not limited to: Digestion, Extraction, Quantitation, Normalization/Amplification, Typing, Interpretation, and Database upload.

OPD does not use Forensic DNA Analysis to surveil residents of Oakland; indeed, it is unlawful to analyze samples and upload them to Combined DNA Index System (CODIS) when no articulable nexus to a crime exists.

2. Purpose

At the end of all DNA analysis processes described previously, a determination can be made as to whether a DNA sample collected from a crime scene can be associated with a known individual through a comparison of evidentiary (crime scene) and reference DNA profiles.

3. Location

The DNA instruments and analysis software are housed in the Criminalistics Laboratory and may not be used elsewhere without disclosure to the Laboratory's accreditation agency ANAB [ANAB = American National Standards Institute (ANSI) National Accreditation Board] and revalidation.

4. Impact

The proposed biometric use policy covers how and when information is to be disseminated, as well as prohibitions against disclosures outside those listed. Civil Rights and liberties are adequately protected in that all samples are to be collected pursuant to search warrant, other legal means, or by documented consent. Nothing in the forensic DNA analysis allows for data collection to be discriminatory, viewpoint-based or biased by algorithm; in fact, the results of DNA analysis can, in a scientifically unbiased manner, include or (more importantly to privacy) exclude a person of interest. OPD recognizes that biometric analysis technology and associated data, if used in ways that violate accreditation, legal standards and uses described and referenced herein, would constitute inappropriate use.

5. Mitigations

The OPD Crime Lab mitigates against the impact of unlawful evidence submissions by requiring that all samples subject to DNA analysis are collected pursuant to search warrant, other legal means, or by documented consent.

Inappropriate uses of DNA biometric analysis technology and associated data are mitigated by:

- (1) Limiting access to the instrumentation and records.
 - a. Only staff authorized to work in the Crime Lab have access.
 - b. Sign-in and escort are required of all guests.
 - c. The laboratory is locked during business hours and locked and alarmed after hours.
- (2) Existence of written policies regarding care of data and casefiles.
 - a. Instrument software is in limited access locations and are hosted on secure servers.
 - b. DNA analytical data are kept on secure network drives.
- (3) Existence of written policies precluding wide dissemination of records.
 - a. Legal Discovery for Criminal or Civil trials is honored.
 - b. California Public Records Act (CPRA) requests are subject to limitations as specified in the Biometric Technology Use Policy.

6. Data Types and Sources

The instruments described previously collect data during one step in the process and may be passed along to another. Data generated by each instrument are stored in a proprietary format readable only by the protocol software or may be converted to tables to be used electronically or printed. The Use Policy indicates how raw data and paper casefiles are to be handled and stored.

7. Data Security

Criminalists and Forensic Technicians with duties in the Forensic Biology/DNA unit shall be the only Crime Laboratory personnel authorized to use the DNA collection and analysis software in casework, and only after completing a comprehensive training program and qualifying test, at which time, with the Supervisor's recommendation, the Crime Laboratory Manager issues a written authorization. No one else shall have the authority to grant access to use the DNA instrumentation or software in casework. Criminalists and Forensic Technicians are granted access to one another's cases only for the purpose of complying with discovery, documenting quality checks, verifications or peer review. Interns also are authorized to use the DNA collection and analysis software for special projects, not casework, and only after receiving necessary training and under the supervision of a qualified Criminalist. Data are stored on secure servers hosted in the Laboratory or by the Department.

8. Fiscal Cost

Digestion / Extraction

- Three Qiagility EZ1 Advanced XL DNA purification instruments and software are in the laboratory; the cost of one new instrument is approximately \$57,000. The current ongoing annual upkeep of the instrument is approximately \$3,100 per instrument.
- Two Versa 1100 liquid handler instruments are in the laboratory; the cost of one replacement instrument is approximately \$85,000. The annual maintenance cost is approximately \$6,800 per instrument.

DNA Quantitation

- Two Qiagility liquid handler instruments are in the laboratory; the cost of one replacement instrument is approximately \$6,000. The annual maintenance cost is approximately \$2,700 per instrument.
- Two 7500 Real-Time PCR DNA quantitation instruments are in the laboratory; the cost of two new replacement instruments is \$114,000. The current ongoing annual upkeep of both instruments is approximately \$10,200.

DNA Normalization / Amplification

- One SpeedVac concentrator is in the laboratory; the cost of one replacement instrument is approximately \$4,000. No annual maintenance cost.
- One 9700 thermal cycler is in the laboratory. Additionally, two ProFlex thermal cyclers are in the laboratory; the cost of one replacement ProFlex instrument is approximately \$14,000. No annual maintenance cost.

DNA Typing

• Two 3130 genetic analyzers are in the laboratory. Additionally, there is one 3500 genetic analyzer; the cost of which was \$135,000. The annual maintenance cost is approximately \$7,500 for one 3130 instrument and approximately \$6,000 for the 3500 instrument.

DNA Interpretation

- GMIDX: approximately \$28,000 per license. No annual maintenance costs
- STRmix upgrade cost \$66,000; annual maintenance costs run ~\$12,000 annually
- FaSTR cost approximately \$37,000.
- Armed Expert acquisition cost approximately \$15,000

Grants, Proposition 69 funds, and Operations and Maintenance budgets have historically covered these costs.

9. Third Party Dependence

Electronic data are retained indefinitely on secure server or network drives and do not require a third party. Hardcopy data present in paper casefiles are currently stored under laboratory control. In the future, if storage needs for hardcopy files exceed capacity, a Departmentallyapproved records retention facility will be used as articulated in the Biometric Use policy.

10. Alternatives

The DNA analysis instruments and software have been validated and meet or exceed both accreditation requirements and industry standards. Alternatives have either been found to be inferior or would require time-exhaustive and expensive validation to replace the current platform with other technology.

11. Track Record

STR-based DNA analysis as a technology has extensive and longstanding documentation as a standard and effective method to analyze DNA. The methods using these technologies in total are employed by many private and government (local, state, federal) forensic and clinical laboratories. There is no known adverse information extant about the technology.



February 2007

BioRobot® EZ1 DSP Workstation User Manual



Sample & Assay Technologies

Trademarks: QIAGEN[®], BioRobot[®] (QIAGEN Group); Gigasept[®], Lysetol[®], Mikrozid[®] (Schülke & Mayr GmbH); DECON-QUAT[®] (Veltek Associates, Inc.). © 2007 QIAGEN, all rights reserved.

Contents

| 1 | Safety Information | 1-1 |
|-------|---|-----|
| 1.1 | Proper use | 1-2 |
| 1.2 | Electrical safety | 1-2 |
| 1.3 | Environment | 1-4 |
| 1.4 | Biological safety | 1-5 |
| 1.5 | Chemicals | 1-6 |
| 1.6 | Waste disposal | 1-6 |
| 1.7 | Mechanical hazards | 1-7 |
| 1.8 | Heat hazard | 1-7 |
| 1.9 | Symbols on the BioRobot EZ1 DSP | 1-8 |
| 1.10 | Additional symbols in this user manual | 1-9 |
| 2 | Introduction | 2-1 |
| 2.1 | About this user manual | 2-1 |
| 2.2 | General information | 2-1 |
| 2.2.1 | Technical assistance | 2-1 |
| 2.2.2 | Policy statement | 2-2 |
| 2.2.3 | Version management | 2-2 |
| 2.3 | Intended use of the BioRobot EZ1 DSP | 2-2 |
| 2.3.1 | Requirements for BioRobot EZ1 DSP users | 2-3 |
| 3 | General Description | 3-1 |
| 3.1 | External features of the BioRobot EZ1 DSP | 3-2 |
| 3.1.1 | Workstation door | 3-2 |
| 3.1.2 | Control panel | 3-2 |
| 3.1.3 | EZ1 Card slot | 3-3 |
| 3.1.4 | Status LEDs | 3-4 |
| 3.1.5 | Connector panel | 3-5 |

Contents

| 3.2 | Internal features of the BioRobot EZ1 DSP | 3-5 |
|----------------|---|---------------|
| 3.2.1 | Worktable | 3-6 |
| 3.2.2 | Pipettor head | 3-9 |
| 4 I | nstallation Procedures | 4-1 |
| 4.1 | Requirements | 4-1 |
| 4.2 | AC power connection | 4-1 |
| 4.3 | Hardware installation | 4-3 |
| 5 (| General Operation | 5-1 |
| 5.1 | Overview | 5-1 |
| 5.2 5.2.1 | Inserting and removing the EZ1 Card Inserting the EZ1 Card | 5-2 5-2 |
| 5.2.2 | Removing the EZ1 Card | 5-3 |
| 5.3 | Switching the BioRobot EZ1 DSP on and off | 5-4 |
| 5.3.1 5.3.2 | Switching on the BioRobot EZ1 DSP Switching off the BioRobot EZ1 DSP | 5-4 5-5 |
| 5.4 | Opening and closing the workstation door | 5-5 |
| 5.4.1 5.4.2 | Opening the workstation door Closing the workstation door | 5-6 5-6 |
| 5.5 | Starting and stopping a protocol run | 5-6 |
| 5.5.1 | Starting a protocol run | 5-6 |
| 5.5.2 | Stopping a protocol run | 5-7 |
| 5.6 | Setting up the worktable | 5-8 |
| 5.6.1 | Removing and replacing the tray | 5-9 |
| 5.6.2 | Loading the reagent cartridges | 5-9 |
| 5.6.3 | Loading the elution tubes, filter-tips, and s tubes | ampie 5-11 |
| 6 F | Preventive Maintenance | 6-1 |
| 6.1 | Regular maintenance procedure | 6-2 |
| 6.2 | Daily maintenance procedure | 6-4 |

| | | Contents |
|--|------------------------------|----------|
| | | |
| 6.3 | Weekly maintenance procedure | 6-5 |
| 6.4 | Reagents for decontamination | 6-6 |
| 7 | Troubleshooting | 7-1 |
| 7.1 | Detecting an error | 7-1 |
| 7.2 | Error codes | 7-2 |
| 8 | Glossary | 8-1 |
| Арре | endix A | A-1 |
| Techr | nical data | A-1 |
| Waste Electrical and Electronic Equipment (WEEE) | | A-4 |
| Арре | endix B | B-1 |
| Warranty statement | | B-1 |
| Liabil | ity clause | B-2 |
| Index | κ | Index-1 |

This page intentionally left blank

Safety Information

1

This manual contains information and warnings that must be followed by the user to ensure safe operation of the BioRobot EZ1 DSP workstation and to maintain the instrument in a safe condition.

Possible hazards that could harm the user or result in damage to the instrument are clearly stated at the appropriate places throughout this manual.

The following safety conventions are used throughout this manual.

| The term WARNING is used to inform you about situations that could result in personal injury to you or other persons. Details about these circumstances are given in a box like this one. |
|--|
| The term CAUTION is used to inform you about situations that could result in damage to the instrument or other equipment. Details about these circumstances are given in a box like |

Before using the instrument, it is essential to read this manual carefully and to pay particular attention to any advice it contains concerning hazards that may arise from use of the instrument.

The advice given in this manual is intended to supplement, not supersede, the normal safety requirements prevailing in the user's country.

this one.

1.1 **Proper use**

| WARNING | Risk of personal injury and material damage [W1] |
|---------|---|
| | Improper use of the BioRobot EZ1 DSP may cause personal injuries or damage to the instrument. The BioRobot EZ1 DSP must only be operated by qualified personnel who have been appropriately trained. Servicing of the BioRobot EZ1 DSP must only be performed by QIAGEN Instrument Service Specialists. |

Use only QIAGEN[®] components, otherwise your right to make a claim under the guarantee may be invalidated. Carry out the maintenance regularly in accordance with the operating instructions. QIAGEN charges for repairs that prove to be required due to incorrect maintenance.



Damage to the instrument

[C1] Avoid spilling water or chemicals onto the BioRobot EZ1 DSP. Instrument damage caused by water or chemical spillage will void your warranty.

In case of an emergency, switch off the BioRobot EZ1 DSP at the power switch on the rear of the instrument and unplug the power cord from the wall power outlet.

| CAUTION | Damage to the instrument [C2] |
|---------|--|
| | Ensure that the BioRobot EZ1 DSP is switched off before you manually move the mechanical components of the instrument. |

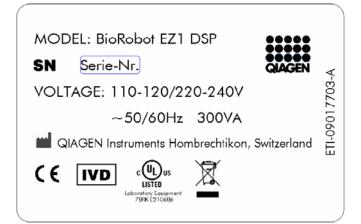
1.2 **Electrical safety**

To ensure satisfactory and safe operation of the BioRobot EZ1 DSP, it is essential that the line power cord is connected to true electrical earth (ground).

| WARNING | Electrical hazard [W2] Any interruption of the protective conductor |
|---------|---|
| | (earth/ground lead) inside or outside the instrument or disconnection of the protective conductor terminal is likely to make the instrument dangerous. Intentional interruption is prohibited. Lethal voltages inside the instrument When the instrument is connected to line power, terminals may be live, and opening covers or removing parts is likely to expose live parts. |
| W | hen working with the BioRobot EZ1 DSP: Make sure the line power cord is connected to a line power outlet that has a protective conductor (earth/ ground). |
| | Do not attempt to make any internal adjustments or replacements. |
| | Do not operate the instrument with any covers or parts removed. |
| | If water or reagent has spilled inside the instrument, switch off the instrument and disconnect it from the line power supply. Call QIAGEN Technical Services. |
| | Servicing should be carried out only by QIAGEN Instrument Service Specialists. |
| | If the instrument becomes electrically unsafe for use, make the instrument inoperative and secure it against unauthorized or unintentional operation. Call QIAGEN Technical Services. |
| Th | e instrument is likely to be electrically unsafe when: It shows visible damage The line power cord shows signs of damage |
| | It has been stored under unfavorable conditions for a prolonged period |
| WARNING | It has been subjected to severe transport stresses Risk of electric shock IW31 |
| | Risk of electric shock [W3] Do not touch the BioRobot EZ1 DSP with wet hands. |

Voltage rating label

The following label appears on the back of the BioRobot EZ1 DSP. Ensure that the voltage rating specified on the label matches the voltage available at the installation site.



1.3 Environment

Operating conditions

WARNING Explosive atmosphere [W4] Main The BioRobot EZ1 DSP is not designed for use in an explosive atmosphere. [W4]

The BioRobot EZ1 DSP will operate correctly under the following conditions:

- Indoors
- Ambient temperature of 5–40°C (41–104°F)
- Ambient relative humidity of <80% at <31°C (88°F) (no condensation)</p>

Storage conditions

If you intend to store the instrument for a prolonged period of time, unplug the power cord from the wall power outlet. The instrument can be stored at -25° C to 70° C (-13° F to 158° F).

1.4 Biological safety

Specimens and reagents containing materials from humans should be treated as potentially infectious. Use safe laboratory procedures as outlined in publications such as Biosafety in Microbiological and Biomedical Laboratories, HHS (www.cdc.gov/od/ohs/biosfty/biosfty.htm).

Samples

Samples may contain infectious agents. You should be aware of the health hazard presented by such agents and should use, store, and dispose of such samples in accordance with the required safety regulations.

| WARNING | Samples containing infectious agents[W5]Some samples used with this instrument may contain infectious agents. Handle such samples with the greatest of care and in accordance with the required safety regulations.[W5]Always wear safety glasses, two pairs of gloves, and a lab coat.[W5]The responsible body (e.g., laboratory manager) must take the necessary precautions to ensure that the surrounding workplace is safe, and that the instrument operators are suitably trained and not exposed to hazardous levels of infectious agents as defined in the applicable Material Safety Data Sheets (MSDSs) or OSHA, ACGIH, or COSHH documents. Venting for fumes and disposal of wastes must be in accordance with all national, state, and local health and safety regulations and laws. |
|---------|---|
|---------|---|

OSHA: Occupational Safety and Health Administration (United States of America).

ACGIH: American Conference of Government Industrial Hygienists (United States of America).

COSHH: Control of Substances Hazardous to Health (United Kingdom).

1.5 Chemicals

| WARNING | Hazardous chemicals [W6] Some chemicals used with this instrument may be hazardous or may become hazardous after completion of the protocol run. Always wear safety glasses, gloves, and a lab coat. The responsible body (e.g., laboratory manager) must take the necessary precautions to ensure that the surrounding workplace is safe and that the instrument operators are not exposed to hazardous levels of toxic substances (chemical or biological) as defined in the applicable Material Safety Data Sheets (MSDSs) or OSHA, ACGIH, or COSHH documents. Venting for fumes and disposal of wastes must be in |
|---------|---|
| | accordance with all national, state, and local health and safety regulations and laws. |

OSHA: Occupational Safety and Health Administration (United States of America).

ACGIH: American Conference of Government Industrial Hygienists (United States of America).

COSHH: Control of Substances Hazardous to Health (United Kingdom).

Toxic fumes

If you work with volatile solvents, toxic substances, etc., you must provide an efficient laboratory ventilation system to remove vapors that may be produced.

1.6 Waste disposal

Used labware, such as reagent cartridges and filter-tips, may contain hazardous chemicals or infectious agents from the purification process. Such wastes must be collected and disposed of properly in accordance with the local safety regulations.

For disposal of waste electrical and electronic equipment (WEEE), see page A-4.

1.7 Mechanical hazards

The worktable of the BioRobot EZ1 DSP moves during operation of the instrument.

| Moving parts[W7]Never open the workstation door while the BioRobot EZ1DSP is operating. |
|--|
| Risk of overheating[W8]To ensure proper ventilation, maintain a minimumclearance of 15 cm and 30 cm at the rear and sides ofthe BioRobot EZ1 DSP, respectively.Slits and openings which ensure the ventilation of theBioRobot EZ1 DSP must not be covered. |

1.8 Heat hazard

The BioRobot EZ1 DSP worktable contains a heating system.

| WARNING | Hot surface [W9] |
|---------|---|
| | The heating system can reach high temperatures. Avoid touching it when it is hot. |

1.9 Symbols on the BioRobot EZ1 DSP

| Symbol | Location | Description |
|--------|--|---|
| | Heating system | Heat hazard — the temperature of the heating system can reach up to 95°C |
| | Near the tip rack | Biohazard — the tip rack may be contaminated with biohazardous material and must be handled with gloves |
| CE | Type plate on the back of the instrument | CE mark for Europe |
| | Type plate on the back of the instrument | UL listing mark for Canada and the USA |
| | Type plate on the back of the instrument | WEEE mark for Europe |
| IVD | Type plate on the back of the instrument | In vitro diagnostic medical device |

| Symbol | Location | Description |
|--------|--|--------------------|
| SN | Type plate on the back of the instrument | Serial number |
| | Type plate on the back of the instrument | Legal manufacturer |

1.10 Additional symbols in this user manual

| Symbol | Location | Description |
|--------|----------------|----------------|
| REF | Front cover | Catalog number |
| HB | Front cover | Handbook |

Symbol on the Heating System



Symbol near the Tip Rack



2 Introduction

Thank you for choosing the QIAGEN BioRobot EZ1 DSP workstation. We are confident it will become an integral part of your laboratory.

Before using the instrument, it is essential to read this manual carefully and to pay particular attention to any advice it contains concerning hazards that may arise from use of this instrument.

2.1 About this user manual

This manual provides information about the BioRobot EZ1 DSP. It guides you systematically through the following sections:

- 1. Safety Information
- 2. Introduction
- 3. BioRobot EZ1 DSP General Description
- 4. Installation Procedures
- 5. General Operation
- 6. Preventive Maintenance
- 7. Troubleshooting
- 8. Glossary

Appendices

The Appendices contain the following:

- Contact information for technical assistance
- Technical data
- Warranty terms

2.2 General information

2.2.1 Technical assistance

At QIAGEN we pride ourselves on the quality and availability of our technical support. Our Technical Service Departments are staffed by experienced scientists with extensive practical and theoretical expertise in molecular biology and the use of QIAGEN products. If you have any questions regarding the BioRobot EZ1 DSP or QIAGEN products in general, please do not hesitate to contact us.

QIAGEN customers are a major source of information regarding advanced or specialized uses of our products. This information is helpful to other scientists as well as to the researchers at QIAGEN. We therefore encourage you to contact us if you have any suggestions about product performance or new applications and techniques.

For technical assistance and more information please call one of the QIAGEN Technical Service Departments or local distributors (see back cover).

2.2.2 Policy statement

It is the policy of QIAGEN to improve products as new techniques and components become available. QIAGEN reserves the right to change specifications at any time.

In an effort to produce useful and appropriate documentation, we appreciate your comments on this publication. Please contact QIAGEN Technical Services.

2.2.3 Version management

This document is the BioRobot EZ1 DSP Workstation User Manual version 1, revision R1.

2.3 Intended use of the BioRobot EZ1 DSP

The BioRobot EZ1 DSP workstation is designed to perform automated purification of nucleic acids for in vitro diagnostic purposes. The system is intended for use by professional users, such as technicians and physicians trained in molecular biological techniques and the operation of the BioRobot EZ1 DSP. Any diagnostic results that are generated using the sample preparation procedure in conjunction with any downstream diagnostic assay must be interpreted in conjunction with other clinical or laboratory findings.

2.3.1 Requirements for BioRobot EZ1 DSP users

This table covers the general level of competence and training necessary for transportation, installation, use, maintenance, and servicing of the BioRobot EZ1 DSP.

| Type of task | Personnel | Training and experience |
|---|---|---|
| Transportation | No special requirements | No special requirements |
| Installation | Laboratory technicians or equivalent | Appropriately trained and experienced personnel familiar with use of computers and automation in general |
| Routine use (running protocols) | Laboratory technicians or equivalent | Appropriately trained and experienced personnel familiar with use of computers and automation in general |
| Preventive maintenance | Laboratory technicians or equivalent | Appropriately trained and experienced personnel familiar with use of computers and automation in general |
| Servicing and annual preventive maintenance | QIAGEN Instrument Service Specialists only | |

This page intentionally left blank

General Description

The BioRobot EZ1 DSP workstation performs fully automated nucleic acid purification from up to 6 samples using magnetic particles. The automated steps include:

Lysis of samples

3

- Binding of nucleic acids to magnetic particles
- Washing and elution of nucleic acids

The user inserts an EZ1 Card containing protocol(s) into the BioRobot EZ1 DSP. After starting worktable setup using the control panel, the user loads samples, reagent cartridges, filter-tips in tip holders, and elution tubes onto the BioRobot EZ1 DSP worktable. The user then closes the workstation door and starts the protocol. The protocol provides all the necessary instructions for the BioRobot EZ1 DSP to carry out automated nucleic acid purification.

The aspiration and dispensing of samples and reagents and the separation of magnetic particles are performed by the 6-channel pipettor head. The temperature of samples is regulated by a heating system.

3.1 External features of the BioRobot EZ1 DSP

Front View of the BioRobot EZ1 DSP Workstation





3.1.1 Workstation door

The workstation door can be manually opened by the user in order to gain access to the worktable. A protocol cannot be started until the workstation door is closed.

3.1.2 Control panel

The control panel is the user interface that allows the user to operate the BioRobot EZ1 DSP. It consists of a keypad and a liquid-crystal display (LCD).

Keypad

The following keys of the control panel are available to the user.

| Кеу | Description |
|-------|---|
| 0–9 | Selects a menu. |
| START | Initiates an action or starts a protocol. |
| STOP | Interrupts a protocol run. |
| ESC | Displays the previous menu or text. |

The other keys of the control panel are for service personnel only.

Liquid-crystal display

The LCD consists of 4 lines. There are 20 spaces per line.

Liquid-Crystal Display

| | se_button: | |
|---|-----------------------|--|
| | T:Protocols :Tools | |
| 2 | | |

3.1.3 EZ1 Card slot

The EZ1 Card slot accepts an EZ1 Card. Each EZ1 Card contains one or more protocols that allow the BioRobot EZ1 DSP to perform nucleic acid isolation.

Note: The workstation should only be switched on after an EZ1 Card is inserted. Make sure that the EZ1 Card is completely inserted! Otherwise essential instrument data

could be lost, leading to a memory error. EZ1 Cards should not be exchanged while the workstation is switched on. Do not remove the EZ1 Card while the machine is switched on. Also, take care not to expose the EZ1 Card to electric shock, water, or dirt.



EZ1 Card Completely Inserted into EZ1 Card Slot

3.1.4 Status LEDs

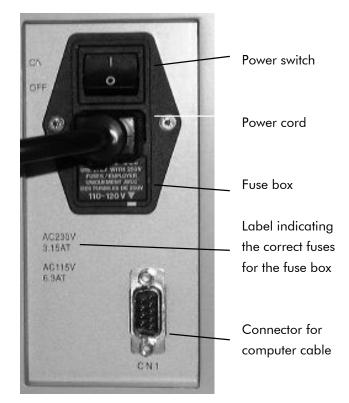
There are 2 light-emitting diodes (LEDs) at the front of the BioRobot EZ1 DSP:

- Green LED indicates that the instrument is receiving power
- Red LED indicates that an error has occurred

3.1.5 Connector panel

The connector panel is located at the rear of the BioRobot EZ1 DSP.

Connector Panel



It contains the power switch, the socket for the power cord, the fuse box, and a connector for a computer cable (for service use only).

3.2 Internal features of the BioRobot EZ1 DSP

The interior of the BioRobot EZ1 DSP contains the worktable and the pipettor head.

3.2.1 Worktable

The worktable contains various racks for holding the labware, samples, and reagent cartridges that are required for the protocol run. The worktable also contains a heating system for controlling the temperature of samples.

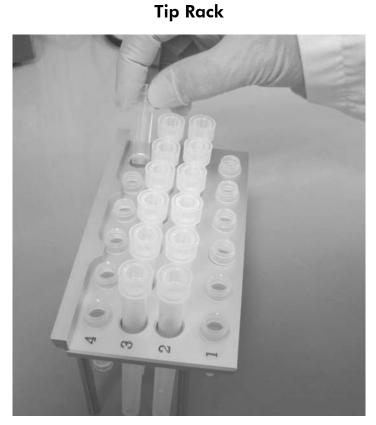
Pipettor head Heating system Sample tubes Reagent cartridge rack Sample tubes Tip holders with tips in tip rack Elution tubes

The BioRobot EZ1 DSP Worktable

Tip rack

This rack is located in the front of the worktable. The front row holds up to 1.5 ml elution tubes. The recommended elution tubes are screw-capped, made of polypropylene, and supplied by Sarstedt (cat. no. 72.692).

The next 2 rows hold up to 12 tip holders containing filtertips. (Note: Some protocols require only one row of filtertips.) The remaining row holds up to 6 sample tubes. Sample tubes are 2 ml in volume, screw-capped, made of polypropylene, and available from Sarstedt (cat. no. 72.693).



Both tip holders and filter-tips are made of polypropylene and available from QIAGEN. The filter-tips have a capacity of 50–1000 μ l.



Tip Holders and Filter-tips

Cartridge rack

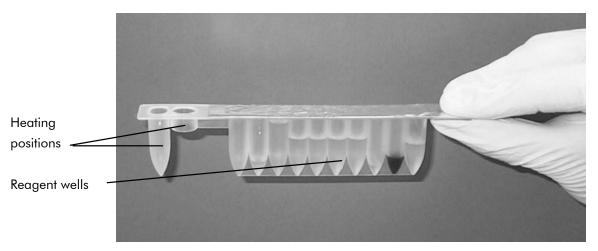
This rack is located behind the tip rack and holds up to 6 reagent cartridges.



Cartridge Rack

Reagent cartridges are made of polypropylene, contain prefilled reagents, and are available from QIAGEN.

Reagent Cartridges



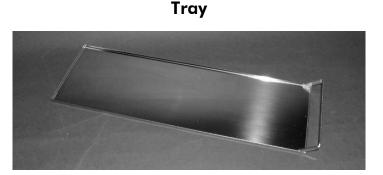
A reagent cartridge consists of 10 reagent wells and 2 heating positions. One heating position is a well, the other is a slot that can accept a tube.

Heating system

The heating system is located under the far end of the cartridge rack. It holds the heating positions of the reagent cartridges.

Tray

The tray is located under the racks and collects any drops of liquid that may fall.



3.2.2 Pipettor head

The pipettor head is mounted above the worktable and moves in the Z direction (i.e., up and down) in order to reach the samples and reagents on the worktable. The worktable itself moves in the Y direction (i.e., front to back) in order to present different samples and reagents under the pipettor head.

The pipettor head contains 6 high-precision syringe pumps that are connected to tip adapters that can be attached to filter-tips. The syringe pumps operate simultaneously to allow aspiration or dispensing of small volumes of liquid $(50-1000 \ \mu l)$ via the filter-tips.

The pipettor head also contains a magnet whose distance from the attached filter-tips can be varied. This feature allows the capture of magnetic particles that are present in the liquid aspirated into the filter-tips.

Located behind the tip adapters is the piercing unit, a row of 6 metal spikes for puncturing the foil that covers the reagent cartridges. During operation of the BioRobot EZ1 DSP, the piercing unit first exposes the reagents in the reagent cartridges. The pipettor head then picks up filter-tips from the tip rack, and performs aspiration and dispensing operations at different locations on the worktable before ejecting the tips back into the tip rack.

4 Installation Procedures

The BioRobot EZ1 DSP is a plug-and-play instrument, making unpacking and installation easy. A member of your group who is familiar with laboratory equipment should oversee the installation.

4.1 Requirements

Site

The BioRobot EZ1 DSP must be located out of direct sunlight, away from heat sources, and away from sources of vibration and electrical interference. Refer to Appendix A for the operating conditions (temperature and humidity).

Use a level workbench that is large and strong enough to accommodate the BioRobot EZ1 DSP. Refer to Appendix A for the weight and dimensions of the BioRobot EZ1 DSP.

The BioRobot EZ1 DSP must be placed near to a properly grounded (earthed) AC power outlet. The power line to the instrument should be voltage regulated and surge protected.

4.2 AC power connection

Power requirements

The BioRobot EZ1 DSP operates at:

- 200–240 V AC ± 10%, 50/60 Hz, 300 VA
- 100–120 V AC ± 10%, 50/60 Hz, 300 VA

Make sure the voltage rating of the BioRobot EZ1 DSP is compatible with the AC voltage available at the installation site.

Grounding requirements

To protect operating personnel, the BioRobot EZ1 DSP must be correctly grounded (earthed). The workstation is equipped with a 3-conductor AC power cord that, when connected to an appropriate AC power outlet, grounds (earths) the workstation. To preserve this protection feature, do not operate the workstation from an AC power outlet that has no ground (earth) connection.

Installation of AC power cord

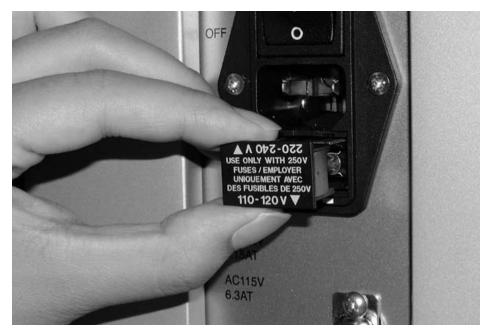
Connect one end of the AC power cord to the socket located on the rear of the BioRobot EZ1 DSP, and the other end to the AC power outlet.

The fuse box of the BioRobot EZ1 DSP is located under the socket for the power cord and contains 2 fuses which are labeled as follows:

- **110–120 V** a 6.3 A (250 V) fuse compatible with 110–120 V power supplies
- **220–240 V** a 3.15 A (250 V) fuse compatible with 220–240 V power supplies

Before connecting the instrument to the power supply, you may need to rotate the fuse box in order to select the correct fuse. A fuse is correctly selected when its label is readable and closer to the bottom of the instrument.

Selecting the Correct Fuse for a 110–120 V Power Supply



| WARNING | Electrical hazard [W12] |
|---------|--|
| | Never install a fuse different from that specified in the user manual. |

4.3 Hardware installation

The following items are delivered:

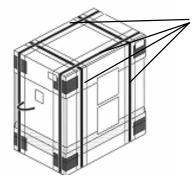
- BioRobot EZ1 DSP workstation
- Power cord (8 pieces)
- BioRobot EZ1 DSP accessories
- BioRobot EZ1 DSP Workstation User Manual
- 6GC teaching data sheet

The BioRobot EZ1 DSP accessories include:

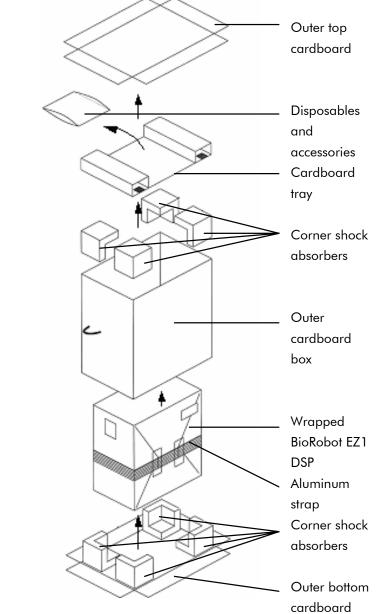
- Cartridge rack
- Tip rack
- Tray
- O-ring (pack of 6) and silicon grease
- Fuses (1 each: 6.3 A and 3.15 A)

Unpacking the BioRobot EZ1 DSP

1. Cut and remove the plastic straps.



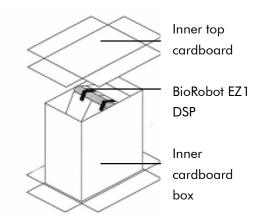
Plastic straps



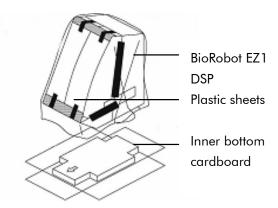
2. Remove the outer top cardboard.

- 3. Take out the packages with the disposables and accessories.
- 4. Remove the cardboard tray.
- 5. Pull out the 4 corner shock absorbers at the top, and remove the outer cardboard box by pulling it up.
- 6. Take out the wrapped BioRobot EZ1 DSP, and remove the aluminum strap.

7. Remove the inner top cardboard, and remove the BioRobot EZ1 DSP from the inner cardboard box.



8. Remove all plastic sheets.

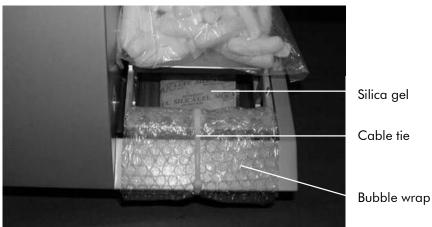


Note: Be careful not to damage the surface of the BioRobot EZ1 DSP after removing the plastic sheets.

Note: It is recommended to save the original packaging material for later transportation of the BioRobot EZ1 DSP.

Removing the protectors for the Y- and Z-axes

During transportation, protectors prevent the moveable parts of the BioRobot EZ1 DSP from moving along the Y- and Z-axes. Before using the instrument, these protectors must be removed. 1. Cut and remove the cable tie.



- 2. Remove the bubble wrap and the silica gel.
- 3. Push the pipettor head upward.



Pipettor head

4. Remove the bag of foam packaging material.



Note: It is recommended to save the original packaging material for later transportation of the BioRobot EZ1 DSP.

Installing the BioRobot EZ1 DSP

- 1. Adjust the fuse box if necessary (Section 4.2, page 4-1).
- 2. Connect the BioRobot EZ1 DSP to the power cord.

This page intentionally left blank

5 General Operation

This section describes how to operate the BioRobot EZ1 DSP.

Before proceeding, it is recommended that you familiarize yourself with the features of the BioRobot EZ1 DSP by referring to Section 3.

5.1 Overview

The steps for operating the BioRobot EZ1 DSP are presented below. Further details are provided later in this section.

- 1. Insert the EZ1 Card completely into the EZ1 Card slot.
- 2. Switch on the BioRobot EZ1 DSP.
- 3. Press "START" to start worktable setup, and press any key to proceed through the messages displayed by the LCD.
- 4. Open the workstation door.
- 5. Set up the worktable according to the messages displayed by the LCD:
 - Load the reagent cartridges into the cartridge rack; then load the rack onto the worktable
 - Load elution tubes into the tip rack
 - Load filter-tips and sample tubes into the tip rack; then load the rack onto the worktable
- 6. Close the workstation door.
- 7. Press "START" to start the protocol.
- 8. At the end of the protocol run:
 - Press "STOP" twice if you do not want to run another protocol
 - Press "ESC" if you want to run another protocol
- 9. Remove the purified nucleic acid samples.
- 10. Clean the BioRobot EZ1 DSP.
- 11. Run another protocol or switch off the BioRobot EZ1 DSP.

5.2 Inserting and removing the EZ1 Card



Damage to the instrument

[C3]

Ensure that the BioRobot EZ1 DSP is switched off before you insert or remove the EZ1 Card. Otherwise, the card and/or the instrument may be damaged.

5.2.1 Inserting the EZ1 Card

1. Lift up the cover of the EZ1 Card slot.



2. Insert the EZ1 Card into the EZ1 Card slot.



Orientate the card so that the picture faces to the left and the triangle symbol is at the bottom.

Ensure that the card is completely inserted into the slot.



It is extremely important that the EZ1 Card is completely inserted to avoid memory error and loss of essential instrument data.

- 3. Close the cover of the EZ1 Card slot.
- 4. Switch on the BioRobot EZ1 DSP (Section 5.3.1, page 5-4).

Note: Do not remove the EZ1 Card while the machine is switched on.

5.2.2 Removing the EZ1 Card

- 1. Switch off the BioRobot EZ1 DSP (Section 5.3.2, page 5-5).
- 2. Lift up the cover of the EZ1 Card slot.



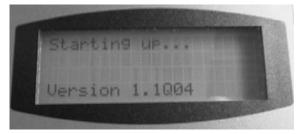
3. Press the button at the bottom of the EZ1 Card slot.

The EZ1 Card is ejected.

5.3 Switching the BioRobot EZ1 DSP on and off

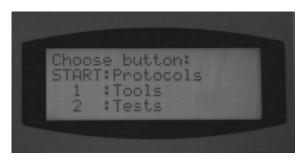
5.3.1 Switching on the BioRobot EZ1 DSP

- 1. Insert the EZ1 Card (Section 5.2.1, page 5-2).
- 2. Switch on the BioRobot EZ1 DSP at the rear power switch.
- 3. The LCD displays the following text for a few seconds.



This text indicates that the BioRobot EZ1 DSP is initializing. All motors move to their home positions.

4. After initialization, the main menu appears.



You can now operate the BioRobot EZ1 DSP.

5.3.2 Switching off the BioRobot EZ1 DSP

- 1. If you had run a protocol, refer to "End of the protocol run" on page 5-7.
- 2. Switch off the BioRobot EZ1 DSP at the rear power switch.

5.4 Opening and closing the workstation door

| WARNING | Moving parts [W7] |
|---------|--|
| | Never open the workstation door while the BioRobot EZ1 DSP is operating. |

5.4.1 Opening the workstation door

1. Slide your fingers under the door and push it upward.



2. Rest the door on the door lock that is located near the top of the BioRobot EZ1 DSP.

5.4.2 Closing the workstation door

- 1. Press the door down to disengage the door lock.
- 2. Gradually lower the door until it rests on the worktable. Take care that your fingers do not get caught between the door and worktable.

5.5 Starting and stopping a protocol run

WARNING Moving parts [W7] Never open the workstation door while the BioRobot EZ1 DSP is operating.

5.5.1 Starting a protocol run

After you have inserted the EZ1 Card and switched on the BioRobot EZ1 DSP, start a protocol as follows:

1. Press "START" on the control panel.

- Start worktable setup by pressing the appropriate number key (e.g., "1" or "2").
 For details, refer to the handbook supplied with the EZ1 DSP Kit you are using.
- 3. Follow the instructions displayed by the LCD.
- 4. Open the workstation door and set up the worktable according to the messages displayed by the LCD (Section 5.6, page 5-8).
- Close the workstation door.
 The protocol run cannot start until the door is closed.
- 6. Press "START" to start the protocol run.

End of the protocol run

After a protocol run ends, the LCD displays "Finished":

1. Press "STOP" twice if you are not running another protocol. The LCD displays the main menu and the motors return to their home positions.

Alternatively, press "ESC" if you are running another protocol. The LCD displays "Protocols", from which you can start the next worktable setup.

- 2. Check that the BioRobot EZ1 DSP is no longer operating. Then open the workstation door and remove the elution tubes, which contain the purified nucleic acid samples.
- 3. Clean the workstation (Section 6, page 6-1).
- 4. Run another protocol or switch off the BioRobot EZ1 DSP.

5.5.2 Stopping a protocol run

When a protocol is running, you have the option of either pausing or canceling it:

1. Press "STOP". The protocol run pauses and the LCD displays the following text.



- To continue the protocol run, press "START".
 The protocol run continues from where it had stopped.
- 3. To cancel the protocol run, press "STOP". The LCD displays the main menu.

Then follow these steps:

- Ensure that the workstation door is closed
- Press "1" to display "Manual" in the LCD



- Press "2" to return the tips to the tip rack and to return the motors to their home positions
- When "Manual" reappears in the LCD, press "ESC" to redisplay the main menu
- Another protocol can now be run

5.6 Setting up the worktable

Note: For specific details about setting up the worktable, refer to the onscreen instructions, which are also included in the handbook supplied with the EZ1 DSP Kit you are using.

5.6.1 Removing and replacing the tray

The tray is located under the worktable and can be removed for cleaning:

- 1. Switch off the BioRobot EZ1 DSP.
- 2. Push the worktable toward the back of the BioRobot EZ1 DSP.
- 3. Remove the tray using its handle.



Reverse this procedure to replace the tray. To avoid instrument damage, ensure that the tray is positioned correctly.

5.6.2 Loading the reagent cartridges

Note: Do not remove the foil from the reagent cartridges.

- 1. Invert the reagent cartridges several times to mix the magnetic particles.
- 2. Tap the reagent cartridges until the reagents are deposited at the bottom of the wells.
- 3. Remove the cartridge rack from the worktable.

General Operation

4. Slide the reagent cartridges into the cartridge rack in the direction of the arrow, as shown below, until you feel resistance.



Press down the cartridges until they click into place.

5. Return the cartridge rack to the worktable.



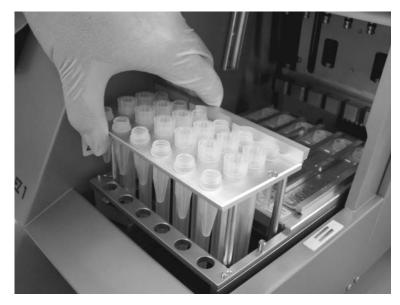
Ensure that the 2 heating positions of each cartridge fit into the heating system.

5.6.3 Loading the elution tubes, filter-tips, and sample tubes

- 1. Remove the tip rack from the worktable.
- 2. Load the elution tubes into row 1 of the tip rack. Label the elution tubes before you load them into the rack. Ensure that the caps of the tubes are removed before you start the protocol.
- Place the filter-tips into the tip holders.
 Ensure that the tips are positioned correctly in the holders.
- 4. Load the tip holders into rows 2 and 3 of the tip rack. **Note**: Some protocols require only one row of filter-tips. Please follow the messages displayed by the LCD.
- 5. Load the sample tubes into row 4 of the tip rack.

Ensure that the caps of the tubes are removed before you start the protocol.





6. Return the tip rack to the worktable.

Ensure that the tips, tip holders, and tip rack are correctly positioned on the worktable.

6 Preventive Maintenance

The following preventive maintenance procedures must be carried out to ensure reliable operation of the BioRobot EZ1 DSP:

- Regular preventive maintenance after each protocol run
- Daily preventive maintenance after the last protocol run of the day
- Weekly preventive maintenance every week
- Annual preventive maintenance every year; removal and replacement of parts are carried out by QIAGEN Instrument Service Specialists only

| WARNING | Risk of electric shock | [W10] |
|---------|--|-------|
| | Do not open any panels on the BioRobot EZ1 DSP. Risk of personal injury and material damage Only perform maintenance which is specifically described in this manual. | |

Servicing

Each BioRobot EZ1 DSP workstation is supplied with a oneyear warranty that includes all repairs due to mechanical breakdown. Worldwide, the maximum time for response to a breakdown is 5 days. Application development, software upgrades, worktable accessories, disposable items, and replacement of spare parts such as syringes, tubing, and pipet tips are not included in the warranty.

QIAGEN offers comprehensive Service Support Agreements, including IQ/OQ, Warranty Extensions, Full Cover Support Agreements, and Preventive Maintenance Agreements. Service Support Agreements ensure high performance from your workstation. In addition, service histories are fully documented and all parts are certified and guaranteed.

Contact your local QIAGEN Instrument Service representative, or your local distributor for more information about flexible Service Support Agreements from QIAGEN.

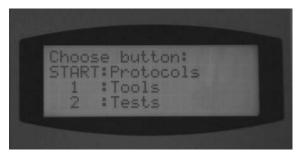
6.1 Regular maintenance procedure

| Risk of personal injury and material damage[W1]Improper use of the BioRobot EZ1 DSP may causepersonal injuries or damage to the instrument.The BioRobot EZ1 DSP must only be operated byqualified personnel who have been appropriatelytrained.Servicing of the BioRobot EZ1 DSP must only beperformed by QIAGEN Instrument Service Specialists. |
|--|
| Hazardous chemicals and infectious agents [W11] The waste contains samples and reagents. This waste may contain toxic or infectious material and must be disposed of properly. Refer to your local safety regulations for proper disposal procedures. |

If working with potentially infectious materials, such as human blood, serum, or plasma, the BioRobot EZ1 DSP system should be decontaminated after use (Section 6.4, page 6-6).

After running a protocol, clean the piercing unit of the pipettor head:

- 1. Remove used disposable labware and unwanted samples and reagents. Discard them according to your local safety regulations.
- 2. In the main menu, press "1" to display "Tools".

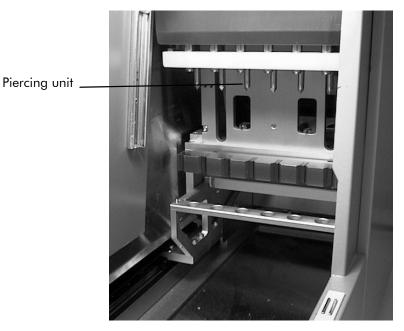


3. Press "3" to select "Clean pierce unit".

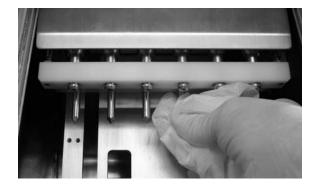


The piercing unit moves downward.

4. Wipe the piercing unit using a soft tissue moistened with 70% ethanol. The piercing unit is sharp. Double gloves are recommended.



5. Wipe the piercing unit using a soft tissue moistened with distilled water.



- 6. Press "ESC" to return the piercing unit to its original position.
- 7. Clean the tray and racks with 70% ethanol and then with distilled water.
- 8. Clean the BioRobot EZ1 DSP worktable with 70% ethanol and then with distilled water.
- 9. Wipe the other surfaces of the workatable with a diluted neutral soap solution and then with distilled water.

You can now run another protocol or switch off the BioRobot EZ1 DSP.

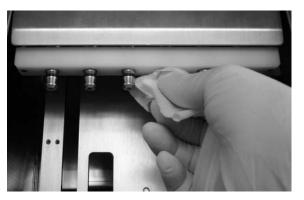
6.2 Daily maintenance procedure

Hazardous chemicals and infectious agents [W11] The waste contains samples and reagents. This waste may contain toxic or infectious material and must be disposed of properly. Refer to your local safety regulations for proper disposal procedures.

After running the last protocol of the day, perform the daily maintenance procedure:

- 1. Clean the piercing unit (Section 6.1, page 6-2).
- 2. Remove used disposable labware and unwanted samples and reagents, and discard them according to your local safety regulations.
- 3. Check that the tray is clean. If necessary, clean it with 70% ethanol, and then with distilled water.
- 4. Clean the worktable and its racks with 70% ethanol, and then with distilled water.
- 5. Wipe the other surfaces of the workstation with diluted neutral soap solution, and then with water.

6. Wipe the O-rings of the tip adapters with tissue.

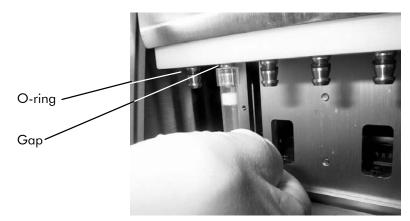


6.3 Weekly maintenance procedure

Perform the daily maintenance procedure before you perform the weekly maintenance procedure.

To maintain good contact between tip adapters and filter-tips and to prevent liquid leaking from the tips, grease the O-rings of the tip adapters every week:

- 1. Apply a small amount of silicon grease to the end of a filter-tip.
- 2. Apply the silicon grease to the surface of the O-rings.
- 3. Place the tip onto the pipettor head, and rotate the tip on the pipettor head to distribute the silicon grease evenly.



Note: The filter-tips should sit flush against the upper white plastic bar if the O-rings are properly greased. There should not be a gap. Excess or insufficient grease can affect the performance of the BioRobot EZ1 DSP.

6.4 Reagents for decontamination

The following disinfectants and detergents are compatible with surfaces and components of the BioRobot EZ1 DSP system. Use according to manufacturers' instructions for effective disinfection.

| WARNING | Toxic fumes [W13] |
|---------|--|
| | Do not use bleach to clean or disinfect the instrument. Bleach in contact with salts from the buffers can produce toxic fumes. |
| | |

- Mikrozid[®] Liquid (Schülke & Mayr GmbH; <u>www.schuelke-mayr.com</u>)* — ethanol-based disinfectant for cleaning surfaces, such as the worktable (consists of 25 g ethanol and 35 g 1-propanol per 100 g Mikrozid Liquid)
- Lysetol® AF or Gigasept® Instru AF (Schülke & Mayr GmbH)* — quaternary ammonium solution for submerging worktable items, such as holders (consists of 14 g cocospropylene-diamine-guanidine diacetate, 35 g phenoxypropanols, and 2.5 g benzalkonium chloride per 100 g, with anticorrosion components, fragrance, and 15–30% nonionic surfactants)

Note: If you want to use disinfectants different from those recommended, ensure that their compositions are similar to those described above. A suitable alternative to Mikrozid Liquid is Incidin Liquid (EcoLab; <u>www.ecolab.com</u>). A suitable alternative to Lysetol AF or Gigasept Instru AF is DECON-QUAT[®] 100 (Veltek Associates, Inc.; <u>www.sterile.com</u>).*

Note: Do not spray cleaning or disinfectant liquids onto surfaces of the BioRobot EZ1 DSP. Spray bottles should be used only for items that have been removed from the workstation.

* This is not a complete list of suppliers and does not include many important vendors of biological supplies.

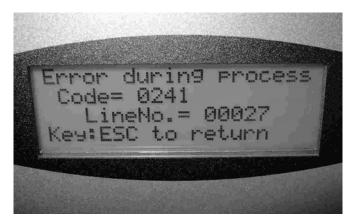
7 Troubleshooting

7.1 Detecting an error

If a protocol run is interrupted due to an error:

- The red LED flashes
- An alarm sounds
- The LCD displays an error message

LCD Displaying an Error Message



The second line of the error message gives the error code (see list below). The third line indicates the line number of the protocol at which the error occurred.

Record the error code and the line number, and contact QIAGEN Technical Services. Then reset the BioRobot EZ1 DSP:

- 1. Press "ESC" to display the main menu in the LCD.
- 2. Ensure that the workstation door is closed.
- 3. Press "1" to display "Manual" in the LCD.
- 4. Press "2" to return the tips to the tip rack and to return the motors to their home positions.
- 5. When "Manual" reappears in the LCD, press "ESC" to redisplay the main menu.

Another protocol can now be run.

Note: It is not possible to continue a protocol run that has been interrupted due to an error.

| 7.2 | Error codes |
|------------|--|
| Error code | Description |
| 10 | Failed to return to origins, protocol cannot run |
| 11 | Limit error, protocol cannot run |
| 12 | Failed to return to Z axis, protocol in run |
| 13 | Failed to return to P axis, protocol in run |
| 14 | Failed to return to M axis, protocol in run |
| 15 | Failed to return to Y axis, protocol in run |
| 16 | Z axis limit error, protocol in run |
| 19 | Y axis end limit, protocol in run |
| 20 | Z axis time-out, protocol in run |
| 21 | P axis time-out, protocol in run |
| 22 | M axis time-out, protocol in run |
| 23 | Y axis time-out, protocol in run |
| 24 | Open door in motion |
| 25 | Abnormal input from bottom sensor in motion |
| 26 | Failed to initialize heating block |
| 27 | Failed to initialize motion control board |
| 29 | Memory error |

| Term | Description |
|--------------------|--|
| Cartridge rack | A metal rack that accommodates reagent cartridges on the worktable. |
| Connector panel | The panel on the rear of the BioRobot EZ1 DSP. It contains the power switch, the socket for the power cord, the fuse box, and a connector for a computer cable. |
| Control panel | The user interface that allows the user to operate the BioRobot EZ1 DSP. The control panel consists of an LCD and a keypad. |
| Elution tube | A polypropylene, screw-capped 1.5 ml tube for collecting purified nucleic acids. |
| Error code | A 1 or 2 digit number that indicates a particular error of the BioRobot EZ1 DSP. |
| EZ1 Card | A card that contains one or more protocols for the BioRobot EZ1 DSP and is inserted into the instrument. |
| EZ1 Card slot | A slot at the front of the BioRobot EZ1 DSP that accepts an EZ1 Card. |
| Filter-tip | An item of labware that is picked up by a tip adapter during operation of the BioRobot EZ1 DSP. Liquid is aspirated into and dispensed from a filter-tip. A filter-tip is also the location where separation of magnetic particles occurs. |
| Heating system | A component of the BioRobot EZ1 DSP that accommodates the heating positions of the reagent cartridges and heats samples. |

Glossary

| Term | Description |
|----------------------|--|
| O-ring | A ring that is fitted at the bottom of a tip adapter. It is required for good contact between the tip adapter and a filter-tip. |
| Pipettor head | The component of the BioRobot EZ1 DSP that aspirates and dispenses liquid and separates magnetic particles. The pipettor head moves up and down above the worktable and contains 6 syringe pumps, each of which is connected to a tip adapter. |
| Protocol | A set of instructions for the BioRobot EZ1 DSP that allows the instrument to automate a nucleic acid purification procedure. Protocols are run using the control panel. |
| Reagent cartridge | An item of labware that contains 10 wells and 2 heating positions. One heating position is a well, the other is a slot that can accept a tube. A reagent cartridge is prefilled with reagents. |
| Sample tube | A polypropylene, screw-capped 2 ml tube for holding a sample containing nucleic acids to be purified. |
| Tip adapter | One of 6 metal probes installed on the pipettor head. During operation of the BioRobot EZ1 DSP, the tip adapters pick up filter-tips from the worktable. |
| Tip holder | A polypropylene tube that holds a single filter-tip. Tip holders are loaded onto the tip rack. |
| Tip rack | A metal rack that accommodates tip holders containing filter-tips on the worktable. The tip rack also accommodates sample tubes and elution tubes. |
| Tray | A metal tray is located under the worktable. It collects any drops of liquid that may fall. |

| Term | Description |
|---------------------|--|
| Workstation door | The main door at the front of the BioRobot EZ1 DSP. When open, it provides complete access to the worktable. |
| Worktable | The surface of the BioRobot EZ1 DSP that contains racks and is where samples, reagent cartridges, and disposable labware are loaded. The worktable moves backwards and forwards to present different samples and reagents under the pipettor head. |

This page intentionally left blank

Appendix A

Technical data

Environmental conditions

| | 3.15 A (250 V) (for 220–240 V AC) |
|-------|--|
| Fuses | 6.3 A (250 V) (for 110–120 V AC) |
| Power | 100–120/200–240 V AC ± 10%, 50/60 Hz, 300 VA |

| | Electrical hazard [W12] Never install a fuse different from that specified in the user manual. |
|--------------------------|---|
| Operating temperature | 5–40°C (41–104°F) |
| Humidity | Maximum 80% relative humidity for temperatures up to 31°C (88°F), decreasing linearly to 50% humidity at 40°C (104°F) (no condensation) |
| Altitude | Up to 2000 m (6500 ft.) |
| Place of operation | For indoor use only |
| Storage temperature | –25°C to 70°C (–13°F to 158°F) |
| Pollution level | 2 |
| Overvoltage category | II |

Appendix A

| Mechanical data and | hardware features |
|---------------------|-------------------|
|---------------------|-------------------|

| Dimensions | Width: 0.32 m (13 in.) Height: 0.54 m (21 in.) with door closed 0.73 m (29 in.) with door open Depth: 0.50 m (20 in.) |
|------------------------|---|
| Mass | 25.8 kg (57 lb.) |
| Instrument features | Automated nucleic acid isolation using magnetic particles Desktop instrument Protocols stored on EZ1 Cards Aspirates and dispenses 6 samples or reagents simultaneously using a 6-channel pipettor head Separates magnetic particles using patented technology Processes up to 6 samples in one run Controlled through LCD user interface Temperature control through a heating system |

| Pipettor head | Contains 6 high-precision syringe pumps, each containing a tip adapter which attaches to filter-tips. Each tip aspirates and dispenses 50–1000 μ l liquid. | | |
|-------------------|--|--|--|
| | Pipetting accuracy is as follows: | | |
| | 50–100 μ l ± 5% | | |
| | ■ 100–1000 μ l: ± 2% | | |
| | Syringe pumps are air-filled. | | |
| | Liquids containing salts, alcohol, solvents, and/or magnetic particles can be aspirated and dispensed. | | |
| | Air gaps can be aspirated to prevent aspirated liquid from dripping. | | |
| | The pipettor head contains a magnet that allows separation of magnetic particles from the aspirated liquid. | | |
| | Filter-tips are picked up from the tip rack and ejected back into the tip rack. | | |
| | The pipettor head moves in the Z direction above the worktable. | | |
| Heating system | Accommodates the heating positions of reagent cartridges and has a temperature range of between ambient temperature and 95°C (203°F). | | |
| | Heating block accuracy at 60° C is ± 2°C. | | |
| Filter-tips | Attach to the tip adapters of the pipettor head to allow liquid aspiration and dispensing. Capacity of 50–1000 μ l. The BioRobot EZ1 DSP accommodates up to 12 tip | | |
| | holders, each containing a filter-tip, in the tip rack on the worktable. | | |

Labware Reagents are loaded onto the worktable using the reagent cartridges. These cartridges are already prefilled with reagents by QIAGEN.

Several reagent cartridges are accommodated together on the worktable by a cartridge rack.

Samples are loaded onto the worktable using 2 ml sample tubes.

Steps which require heating occur on the heating system, which accommodates the heating positions of the reagent cartridges.

Purified nucleic acids are collected in 1.5 ml elution tubes.

Waste Electrical and Electronic Equipment (WEEE)

This section provides information about disposal of waste electrical and electronic equipment by users in the European Union.

The European Directive 2002/96/EC on WEEE requires proper disposal of electrical and electronic equipment when it reaches its end of life. The crossed-out wheeled bin symbol (see below) indicates that this product must **not** be disposed of with other waste; it must be taken to an approved treatment facility or to a designated collection point for recycling, according to local legislation. The separate collection and recycling of waste electronic equipment at the time of disposal helps to conserve natural resources and ensures that the product is recycled in a manner that protects human health and the environment.



QIAGEN accepts its responsibility in accordance with the specific WEEE recycling requirements and, where a replacement product is being supplied by QIAGEN, provides free recycling of its WEEE-marked electronic equipment in Europe. If a replacement product is not being purchased from QIAGEN, recycling can be provided upon request at additional cost. To recycle electronic equipment, contact your local QIAGEN sales office for the required return form. Once the form is submitted, you will be contacted by QIAGEN either to request follow-up information for scheduling collection of the electronic waste or to provide you with an individual quote. This page intentionally left blank

Appendix B

Warranty statement

Thank you for your purchase of QIAGEN instrumentation. Your instrument has been carefully tested to ensure optimum operating efficiency and reproducibility of results. QIAGEN warrants that all new instrumentation manufactured by QIAGEN will correspond to the product specifications and be free from defects in workmanship and materials for a period of twelve (12) months from the original date of shipment. Repair or replacement of defective parts will be provided to the purchaser during this time period provided the QIAGEN instrumentation is operated under conditions of normal and proper use, but not for damage caused by the customer. If any part or subassembly proves to be defective, it will be repaired or replaced at QIAGEN's sole option, subsequent to inspection at the factory, or in the field by an authorized factory representative, provided that such defect manifested under normal and proper use. The shipper will pay all transport fees.

Limitation of warranties and remedies

THE FOREGOING WARRANTY IS QIAGEN'S SOLE AND EXCLUSIVE WARRANTY, AND REPAIR OR REPLACEMENT OF DEFECTIVE PARTS IS THE SOLE AND EXCLUSIVE REMEDY. THERE ARE NO OTHER WARRANTIES OR GUARANTEES, EXPRESS OR IMPLIED. THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE EXPRESSLY EXCLUDED, TO THE FULLEST EXTENT PERMITTED BY LAW. (NOTE: SOME STATES DO NOT PERMIT DISCLAIMERS OF IMPLIED WARRANTIES SO THIS LIMITATION MAY NOT APPLY TO YOU). WITH THE EXCEPTION OF THE ABOVE-REFERENCED REPAIR OR REPLACEMENT REMEDY, QIAGEN SHALL HAVE NO OBLIGATION OR LIABILITY OF ANY NATURE WHATSOEVER WITH RESPECT TO THE QIAGEN INSTRUMENTATION, WHETHER ARISING IN CONTRACT, TORT, STRICT LIABILITY, OR OTHERWISE, INCLUDING BUT NOT LIMITED TO, LIABILITY FOR INDIRECT, CONSEQUENTIAL, INCIDENTAL AND/OR SPECIAL, PUNITIVE, MULTIPLE AND/OR EXEMPLARY DAMAGES AND/OR OTHER LOSSES (INCLUDING LOSS OF USE, LOST REVENUES, LOST PROFITS AND DAMAGE TO REPUTATION), EVEN IF SUCH DAMAGES WERE FORESEEN OR FORSEEABLE, OR WERE BROUGHT TO QIAGEN'S ATTENTION. IN NO EVENT SHALL QIAGEN'S LIABILITY TO YOU EXCEED THE PURCHASE PRICE OF THE PRODUCT.

Liability clause

QIAGEN shall be released from all obligations under its warranty in the event repairs or modifications are made by persons other than its own personnel, except in cases where the Company has given its written consent to perform such repairs or modifications.

All materials replaced under this warranty will be warranted only for the duration of the original warranty period, and in no case beyond the original expiration date of original warranty unless authorized in writing by an officer of the Company. Read-out devices, interfacing devices and associated software will be warranted only for the period offered by the original manufacturer of these products. Representations and warranties made by any person, including representatives of QIAGEN, which are inconsistent or in conflict with the conditions in this warranty shall not be binding upon the Company unless produced in writing and approved by an officer of QIAGEN.

Index

С

Cartridge rack, 3-8 Connector panel, 3-5 Control panel, 3-1, 3-2

Ε

Elution tubes, 3-6 loading, 5-11 EZ1 Card, 3-1, 3-2 inserting, 5-2 removing, 5-3 slot, 3-2, 3-3

F

Filter-tips, 3-6 loading, 5-11 Fuse box, 3-5, 4-2

Η

Heating positions, 3-8 Heating system, 3-1, 3-9

L

LCD, 3-2

Μ

Magnet, 3-9 Magnetic particles, 3-1 Maintenance, 6-1 daily, 6-4 decontamination, 6-6 weekly, 6-5

0

Operating conditions, 1-4

P

Piercing unit, 3-10 Pipettor head, 3-1, 3-9 Power cord, 3-5 Power requirements, 4-1 Power switch, 3-5 Protocol, 3-1 end, 5-7 starting, 5-6 stopping, 5-7

R

Racks, 3-5 Reagent cartridges, 3-1, 3-8 loading, 5-9 Reagent wells, 3-8

S

Safety biological, 1-5 chemical, 1-6 electrical, 1-2 heat hazard, 1-7 mechanical hazards, 1-7 proper use, 1-2 symbols, 1-8 Sample tubes, 3-6 loading, 5-11 Servicing, 6-1 Status LEDs, 3-2, 3-4 Storage conditions, 1-4 Switching off, 5-5 Switching on, 5-4 Symbols, 1-8, 1-9 Syringe pumps, 3-9

Т

Tip adapters, 3-9 Tip holders, 3-1, 3-6 Tip rack, 3-6 Tips, 3-6 Ioading, 5-11 Tray, 3-9 removing, 5-9 Troubleshooting, 7-1

W

Waste disposal, 1-6, A-4 Workstation door, 3-1, 3-2 closing, 5-6 opening, 5-6 Worktable, 3-1, 3-5 setting up, 5-8

QIAGEN Distributors and Importers

Please see the back cover for contact information for your local QIAGEN office.

Argentina

Tecnolab S.A. Tel: (011) 4555 0010 Fax: (011) 4553 3331 E-mail: info@tecnolab.com.ar

snia-Herzegovina

MEDILINE d.o.o. Tel.: +386 1 830-80-40 Fax: +386 1 830-80-70 +386 1 830-80-63 E-mail: info@mediline.si

Brazil

Uniscience do Brasil Tel: 011 3622 2320 Fax: 011 3622 2323 E-mail: info@uniscience.com

Chile Biosonda SA Tel: +562 209 6770 Fax: +562 274 5462 E-mail: ventas@biosonda.cl

China Eastwin Scientific, Inc. Order: +86-400-8182168 Tel: +86-10-51663168 Fax: +86-10-82898283 E-mail: laborder@eastwin.com.cn

 Gene Company Limited

 Tel:
 +86-21-64951899

 Fax:
 +86-21-64955468
 E-mail: info_bj@genecompany.com (Beijing)

info_sh@genecompany.com (Shanghai) info_cd@genecompany.com (Chengdu) info_gz@genecompany.com (Guangzhou)

Genetimes Technology, Inc. Order: 800-820-5565 Tel· +86-21-54262677 +86-21-64398855 Fax: E-mail: order@genetimes.com.cn

Colombia GENTECH – Genetics & Technology Tel: (+57)(4)2519037 : (+57)(4)2516555 Fax: E-mail: gerencia@gentechcolombia.com soporte@gentechcolombia.com

Croatia Jordan INEL Medicinska Tehnika d.o.o. Tel: (01) 2984-898 Fax. (01) 6520-966 E-mail: inel-medicinska-tehnika@zg.htnet.hr

Cyprus Scientronics Ltd
 Tel:
 +357
 22
 467880/90
 Tel:
 (02)
 924.86
 97

 Fax:
 +357
 22
 764614
 Fax:
 (02)
 924.86
 96

 E-mail:
 a.sarpetsas@biotronics.com.cy
 E-mail:
 webmaster@Irslab.co.kr

Czech Republic BIO-CONSULT spol. s.r.o. Tel/Fax: (+420) 2 417 29 792 E-mail: info@bioconsult.cz

INMUNOCHEM S.A.C. Tel: +51 1 4409678 Fax: +51 1 4223701 E-mail: inmunochem@terra.com.pe

Egypt Clinilab Tel: 52 57 212 Fax: 52 57 210 E-mail: Clinilab@link.net

Ecuador

Estonia Quantum Eesti AS Tel: +372 7301321 Fax: +372 7304310 E-mail: guantum@guantum.ee

BioAnalytica S.A.

(210)-640 03 18 (210)-646 27 48 Tel: Fax: E-mail: biognalvt@hol.gr Hong Kong SAR Gene Company Limited Tel: +852-2896-6283 Fax: +852-2515-9371

E-mail: info@genehk.com Genetimes Technology International Holding Ltd. Tel: +852-2385-2818 Fax: +852-2385-1308 E-mail: hongkong@genetimes.com.hk

Hungary BioMarker Kft. Tel: +36 28 419 986 Fax: +36 28 422 319

India Genetix Tel:

E-mail: biomarker@biomarker.hu Tel: +91-11-51427031 Fax: +91-11-25419631 E-mail: genetix@genetixbiotech.com

Indonesia PT Research Biolabs Tel: +62 21 5865357 E-mail: indonesia@researchbiolabs.com

Zist Baran (BIORAIN) Tel: +98 (21) 88066348 or +98 (21) 88066349 Fax +98 (21) 88214107 E-mail: info@biorain.com

Israel Eldan Electronic Instruments Co. Ltd. Tel: +972-3-937 1133 Fax: +972-3-937 1121 E-mail: bio@eldan.biz

SAHOURY GROUP Tel: +962 6 4633290-111 Fax: +962 6 4633290-110

E-mail: info@sahoury.com LRS Laboratories, Inc

 Philekorea Technology, Inc.

 Tel:
 (02) 576-6540

 Fax:
 (02) 576-6541
 E-mail: support@philekorea.co.kr

Latvia SIA "J.I.M." Tel: 7136393 Fax: 7136394 E-mail: jim@mednet.lv

Lithuania INTERLUX Tel: +370-5-2786850 Fax: +370-5-2796728

E-mail: spirit@interlux.lt

Malaysia RESEARCH BIOLABS SDN. BHD. Tel: (603)-8070 3101 Fax: (603)-8070 5101 E-mail: biolabs@tm.net.my

Mexico
 Mexico

 Quimica Valaner S.A. de C.V.

 Tel:
 (55) 55 25 57 25

 Fax:
 (55) 55 25 56 25

 E-mail: ventas@valaner.com

New Zealand Biolab Ltd Tel: (09) 980 6700 0800 933 966 Fax: (09) 980 6788 E-mail: biosciences@nzl.biolabgroup.com

Omar Al Mazouri Medical & Chemical Supplies +971 4 266 1272 Tel:

(ext. 301, 310, 311) +971 4 269 0612 (ATTN: LAB DIVISION) Fax: E-mail: shaji@almaz.net.ae

Pakistan Pakistan Microbiological Associates Tel: +92-51-5567953 Fax: +92-51-5514134 E-mail: orderpma@comsats.net.pk

INMUNOCHEM S.A.C. Tel: +51 1 4409678 Fax: +51 1 4223701 E-mail: inmunochem@terra.com.pe

Poland
 Syngen Biotech Sp.z.o.o.

 Tel:
 (071) 798 58 50 - 52

 Fax:
 (071) 798 58 53
 E-mail: info@syngen.pl

Portugal IZASA PORTUGAL, LDA Tel: (21) 424 7312 Fax (21) 417 2674 E-mail: consultasbiotec@izasa.es

Qata Sedeer Medical +974 - 488 5218 +974 - 488 1988 Tel: Fax: E-mail: sedeer@qatar.net.qa

Romania Zyrcon Medical S. R. L. Tel: +40 21 2245607 Fax: +40 21 2245608 E-mail: virgil.dracea@zyrconmedical.ro

secretariat@zyrconmedical.ro Saudi Arabia Abdulla Fouad Holding Company Tel: (03) 8324400 Fax: (03) 8346174

E-mail: sadiq.omar@abdulla-fouad.com

Singapore Research Biolabs Pte Ltd Tel: 6777 5366 Fax: 6778 5177

E-mail: sales@researchbiolabs.com

Slovak Republic

BIO-CONSULT Slovakia spol. s.r.o. Tel/Fax: (02) 5022 1336 E-mail hio-cons@cdicon sk

Slovenia MEDILINE d.o.o. Tel: (01) 830-80-40 Fax: (01) 830-80-70

(01) 830-80-63 E-mail: info@mediline.si South Africa

Southern Cross Biotechnology Tel: (021) 671 5166 Fax: (021) 477 E-mail: info@scb.co.za

IZASA SA Tel: (93) 902.20.30.90 Fax: (93) 902.22.33.66 E-mail: consultasbiotec@izasa.es

Taiwan TAIGEN Bioscience Corporation Tel: (02) 2880 2913 Fax: (02) 2880 2916 E-mail: order@taigen.com

Thailand Theera Trading Co. Ltd. Tel: (02) 412-5672 (02) 412-3244 Fax: E-mail: theetrad@samart.co.th

Medek Medikal Ürünler ve Saglik Hizmetleri A. S. Tel: (216) 302 15 80 Fax: (216) 302 15 88 E-mail: makialp@med-ek.com

United Arab Emirates Al Mazouri Medical & Chemical Supplies +971 4 266 1272 Tel:

Fax: E-mail: shaji@almaz.net.ae

Bionova Ltda Tel: +598 2 6130442 Fax: +598 2 6142592 E-mail: bionova@internet.com.uv

Venezuela SAIXX Technologies c.a. Tel: +58212 3248518

+58212 3255838 +58212 7615945 Fax: E-mail: ventas@saixx.com saixxventas@cantv.net

Vietnam Viet Anh Instruments Co., Ltd. Tel: +84-4-5119452 Fax: +84-4-5119453 E-mail: VietanhHN@hn.vnn.vn

All other countries QIAGEN GmbH, Germany

(ext. 301, 310, 311) +971 4 269 0612 (ATTN: LAB DIVISION)

Uruguay

+58212 7616143

www.qiagen.com

Australia = Orders 03-9840-9800 = Fax 03-9840-9888 = Technical 1-800-243-066 Austria Corders 0800/28-10-10 Fax 0800/28-10-19 Technical 0800/28-10-11 Belgium = Orders 0800-79612 = Fax 0800-79611 = Technical 0800-79556 Canada = Orders 800-572-9613 = Fax 800-713-5951 = Technical 800-DNA-PREP (800-362-7737) China = Orders 021-51345678 = Fax 021-51342500 = Technical 021-51345678 **Denmark** Orders 80-885945 Fax 80-885944 Technical 80-885942 Finland
Orders 0800-914416
Fax 0800-914415
Technical 0800-914413 France Orders 01-60-920-926 = Fax 01-60-920-925 = Technical 01-60-920-930 = Offers 01-60-920-928 Germany = Orders 02103-29-12000 = Fax 02103-29-22000 = Technical 02103-29-12400 Ireland Crders 1800-555-049 Fax 1800-555-048 Technical 1800-555-061 Italy = Orders 02-33430411 = Fax 02-33430426 = Technical 800-787980 Japan = Telephone 03-5547-0811 = Fax 03-5547-0818 = Technical 03-5547-0811 Luxembourg = Orders 8002-2076 = Fax 8002-2073 = Technical 8002-2067 The Netherlands Corders 0800-0229592 Fax 0800-0229593 Technical 0800-0229602 Norway Corders 800-18859 Fax 800-18817 Technical 800-18712 Sweden = Orders 020-790282 = Fax 020-790582 = Technical 020-798328 Switzerland Corders 055-254-22-11 Fax 055-254-22-13 Technical 055-254-22-12 UK = Orders 01293-422-911 = Fax 01293-422-922 = Technical 01293-422-999 USA = Orders 800-426-8157 = Fax 800-718-2056 = Technical 800-DNA-PREP (800-362-7737)



Sample & Assay Technologies

1037181 124102347

EZ1® DNA Investigator Handbook

For automated purification of DNA from forensic and biosecurity samples using EZ1 instruments



Sample & Assay Technologies

QIAGEN Sample and Assay Technologies

QIAGEN is the leading provider of innovative sample and assay technologies, enabling the isolation and detection of contents of any biological sample. Our advanced, high-quality products and services ensure success from sample to result.

QIAGEN sets standards in:

- Purification of DNA, RNA, and proteins
- Nucleic acid and protein assays
- microRNA research and RNAi
- Automation of sample and assay technologies

Our mission is to enable you to achieve outstanding success and breakthroughs. For more information, visit <u>www.qiagen.com</u>.

Contents

| Kit Contents | | 5 |
|-------------------------|--|----|
| Stor | 5 | |
| Qua | lity Control | 6 |
| Product Use Limitations | | 6 |
| Proc | Product Warranty and Satisfaction Guarantee | |
| Technical Assistance | | 7 |
| Safety Information | | 8 |
| Intro | duction | 9 |
| | Principle and procedure | 9 |
| | Description of protocols | 11 |
| Equi | pment and Reagents to Be Supplied by User | 13 |
| Impo | ortant Notes | 15 |
| | Starting material | 15 |
| | Working with EZ1 instruments | 15 |
| | Yield of purified DNA | 20 |
| | Precipitate in reagent cartridge | 20 |
| | Equilibrating reagent cartridges | 20 |
| | Lysis with proteinase K | 21 |
| | Quantification of DNA | 21 |
| Pret | reatment protocols | |
| | Pretreatment for Whole Blood | 22 |
| | Pretreatment for Dried Blood | 23 |
| | Pretreatment for Saliva | 25 |
| | Pretreatment for Forensic Surface and Contact Swabs | 26 |
| | Pretreatment for Nail Scrapings | 28 |
| | Pretreatment for Chewing Gum | 29 |
| | Pretreatment for Cigarette Butts | 30 |
| | Pretreatment for Postage Stamps | 32 |
| | Pretreatment for Stains on Fabric | 34 |
| | Pretreatment for Human Tissues | 36 |
| | Pretreatment for Epithelial Cells Mixed with Sperm Cells | 37 |
| | Pretreatment for Hair | 39 |
| | Pretreatment for Bones or Teeth | 40 |

| | Pretreatment for Soil | 41 |
|--|--|----|
| | Pretreatment for Other Forensic Samples | 42 |
| Purif | fication protocols | |
| | DNA Purification (Trace Protocol) | 44 |
| | DNA Purification ("Tip Dance" Protocol) | 46 |
| | DNA Purification (Large-Volume Protocol) | 49 |
| Troubleshooting Guide | | 52 |
| Appendix A: Purification of Low Amounts of DNA | | 54 |
| Appendix B: Example of an EZ1 Advanced Report File | | 55 |
| Ordering Information | | 57 |

Kit Contents

| EZ1 DNA Investigator Kit | (48) | |
|--------------------------------------|------------|--|
| Catalog no. | 952034 | |
| Number of preps | 48 | |
| Reagent Cartridge, DNA Investigator* | 48 | |
| Disposable Tip Holders | 50 | |
| Disposable Filter-Tips | 50 | |
| Sample Tubes (2 ml) | 50 | |
| Elution Tubes (1.5 ml) | 50 | |
| Buffer G2 | 1 x 11 ml | |
| Proteinase K | 2 x 250 µl | |
| Carrier RNA [†] | 1 x 310 µg | |
| Q-Card [‡] | 1 | |
| Handbook | 1 | |

* Contains a guanidine salt. Not compatible with disinfectants containing bleach. See page 8 for safety information.

[†] Use of carrier RNA is optional. See "Description of protocols", page 12 and Appendix A for more information.

[‡] The information encoded in the bar code on the Q-Card is needed for reagent data tracking using the EZ1 Advanced or EZI Advanced XL instrument.

Additional filter-tips and tip holders are available separately. Additional Buffer G2 and QIAGEN Proteinase K, required for some protocols, are available separately. See page 57 for ordering information.

Storage

The EZ1 DNA Investigator Kit is shipped at ambient temperature. All buffers and reagents can be stored at room temperature (15–25°C). Do not freeze the reagent cartridges. When stored properly, the reagent cartridges are stable until the expiration date on the Q-Card. Lyophilized carrier RNA is stable until the expiration date on the Q-Card when stored at room temperature.

The ready-to-use proteinase K solution is stable for up to one year after delivery when stored at room temperature.

Quality Control

In accordance with QIAGEN's ISO-certified Quality Management System, each lot of EZ1 DNA Investigator Kits is tested against predetermined specifications to ensure consistent product quality. Functional QC testing ensures that the EZ1 DNA Investigator Kit meets the high standards required by forensic scientists.

Product Use Limitations

The EZ1 DNA Investigator Kit is intended for molecular biology applications. This product is neither intended for the diagnosis, prevention, or treatment of a disease, nor has it been validated for such use either alone or in combination with other products.

All due care and attention should be exercised in the handling of the products. We recommend all users of QIAGEN® products to adhere to the NIH guidelines that have been developed for recombinant DNA experiments, or to other applicable guidelines.

Product Warranty and Satisfaction Guarantee

QIAGEN guarantees the performance of all products in the manner described in our product literature. The purchaser must determine the suitability of the product for its particular use. Should any product fail to perform satisfactorily due to any reason other than misuse, QIAGEN will replace it free of charge or refund the purchase price. We reserve the right to change, alter, or modify any product to enhance its performance and design. If a QIAGEN product does not meet your expectations, simply call your local Technical Service Department or distributor. We will credit your account or exchange the product — as you wish. Separate conditions apply to QIAGEN scientific instruments, service products, and to products shipped on dry ice. Please inquire for more information.

A copy of QIAGEN terms and conditions can be obtained on request, and is also provided on the back of our invoices. If you have questions about product specifications or performance, please call QIAGEN Technical Services or your local distributor (see back cover or visit <u>www.qiagen.com</u>).

Technical Assistance

At QIAGEN we pride ourselves on the quality and availability of our technical support. Our Technical Service Departments are staffed by experienced scientists with extensive practical and theoretical expertise in sample and assay technologies and the use of QIAGEN products. If you have any questions or experience any difficulties regarding the EZ1 DNA Investigator Kit or QIAGEN products in general, please do not hesitate to contact us.

QIAGEN customers are a major source of information regarding advanced or specialized uses of our products. This information is helpful to other scientists as well as to the researchers at QIAGEN. We therefore encourage you to contact us if you have any suggestions about product performance or new applications and techniques.

For technical assistance and more information, please see our Technical Support Center at <u>www.qiagen.com/goto/TechSupportCenter</u> or call one of the QIAGEN Technical Service Departments or local distributors (see back cover or visit <u>www.qiagen.com</u>).

Safety Information

When working with chemicals, always wear a suitable lab coat, disposable gloves, and protective goggles. For more information, please consult the appropriate material safety data sheets (MSDSs). These are available online in convenient and compact PDF format at <u>www.qiagen.com/Support/MSDS.aspx</u> where you can find, view, and print the MSDS for each QIAGEN kit and kit component.



CAUTION: DO NOT add bleach or acidic solutions directly to the sample-preparation waste.

Buffers in the reagent cartridges contain guanidine salts, which can form highly reactive compounds when combined with bleach. If liquid containing these buffers is spilt, clean with suitable laboratory detergent and water. If the spilt liquid contains potentially infectious agents, clean the affected area first with laboratory detergent and water, and then with 1% (v/v) sodium hypochlorite.

If liquid containing potentially infectious agents is spilt on the EZ1 Advanced XL, EZ1 Advanced, or BioRobot® EZ1, clean the affected area first with laboratory detergent and water, and then with 1% (v/v) sodium hypochlorite, followed by water.

The following risk and safety phrases apply to components of the EZ1 DNA Investigator Kit.

Reagent cartridge

Contains ethanol, guanidine hydrochloride, and guanidine thiocyanate: highly flammable, harmful, and irritant. Risk and safety phrases:* R11-20/21/22-32-36/38, S13-26-36/37/39-46

QIAGEN proteinase K

Contains proteinase K: sensitizer, irritant. Risk and safety phrases:* R36/37/38-42/43, S23-24-26-36/37

24-hour emergency information

Emergency medical information in English, French, and German can be obtained 24 hours a day from:

Poison Information Center Mainz, Germany

Tel: +49-6131-19240

* R11: Highly flammable; R20/21/22: Harmful by inhalation, in contact with skin, and if swallowed; R32: Contact with acids liberates very toxic gas; R36/38: Irritating to eyes and skin; R36/37/38: Irritating to eyes, respiratory system, and skin; R42/43: May cause sensitization by inhalation and skin contact. S13: Keep away from food, drink, and animal feedingstuffs; S23: Do not breathe spray; S24: Avoid contact with skin; S26: In case of contact with eyes, rinse immediately with plenty of water and seek medical advice; S36/37: Wear suitable protective clothing and gloves; S36/37/39: Wear suitable protective clothing, gloves, and eye/face protection; S46: If swallowed, seek medical advice immediately and show container or label.

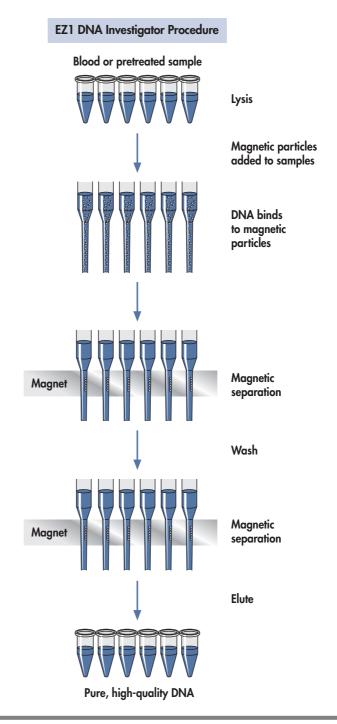
Introduction

EZ1 instruments and the EZ1 DNA Investigator Kit reproducibly automate purification of genomic DNA from 1–6 samples (EZ1 Advanced and BioRobot EZ1) or 1–14 samples (EZ1 Advanced XL) encountered in forensic, human-identity, and biosecurity applications. Purification is efficient and purified DNA performs well in downstream analyses, such as quantitative PCR and STR analysis, with high signal-to-noise ratios.

Magnetic-particle technology provides high-quality DNA that is suitable for direct use in downstream applications such as STR analysis or other enzymatic reactions. EZ1 instruments perform all steps of the sample preparation procedure, and the user can choose sample input volumes of 200 μ l or 500 μ l, allowing purification from varying amounts of starting material. Up to 6 samples (BioRobot EZ1, EZ1 Advanced) or up to 14 samples (EZ1 Advanced XL) are processed in a single run.

Principle and procedure

Magnetic-particle technology combines the speed and efficiency of silica-based DNA purification with the convenient handling of magnetic particles (see flowchart, page 10). DNA is isolated from lysates in one step through its binding to the silica surface of the particles in the presence of a chaotropic salt. The particles are separated from the lysates using a magnet. The DNA is then efficiently washed and eluted in the user's choice of either water or TE buffer. The user can choose elution volumes of 40 μ l (EZ1 Advanced XL only), 50 μ l, 100 μ l, or 200 μ l.



Description of protocols

This handbook contains two types of protocols.

- Pretreatment protocols detail the preliminary steps, such as proteinase K digestion, prior to processing on the EZ1 instrument.
- DNA purification protocols describe setting up the EZ1 instrument and starting a fully automated run.

Pretreatment protocols

Since the type of samples that can be processed using the EZ1 DNA Investigator Kit can vary greatly, there is also a variety of different pretreatments, optimized for specific sample types. For sample types not specifically included in this handbook, the Protocol: Pretreatment for Other Forensic Samples, page 42, provides a generic protocol that can serve as a starting point for optimizing pretreatment for other sample types.

DNA purification protocols

There are 3 DNA purification protocols, which can be used in conjunction with the pretreatment protocols. Within each protocol, the user can specify elution in water or TE buffer, with elution volumes of 40 µl (EZ1 Advanced XL only), 50 µl, 100 µl, or 200 µl. The standard **Protocol: DNA Purification (Trace Protocol)**, page 44, can be used with all sample types.

In the **Protocol: DNA Purification ("Tip Dance" Protocol)**, page 46, the filter-tip moves back-and-forth relative to the worktable platform while pipetting. This enables processing of solid materials, such as swabs, fabrics, blood discs, or cigarette butts, directly in the sample tube. There is generally no need for prior centrifugation to remove solid materials that could clog the tip. However, when processing fluffy sample material such as cotton wool, we recommend removing solid material if you cannot process a replicate sample or the sample material is precious.

The **Protocol: DNA Purification (Large-Volume Protocol)**, page 49, enables fully automated processing of starting volumes up to 500 µl. This not only allows efficient DNA purification from dilute samples with low concentrations of DNA, such as diffuse stains, but also enables purification from samples that require larger volumes for thorough lysis. The ability to process larger sample volumes — with the same elution volume as the standard trace protocol — enables higher yields of more concentrated DNA for greater sensitivity in downstream applications.

The protocol for **purification of low amounts of DNA** in Appendix A, describes the optional use of carrier RNA in the purification procedure. Carrier RNA enhances binding of DNA to the silica surface of the magnetic particles, especially if the sample contains low amounts of DNA (<100 ng). Recently published data suggest that addition of carrier RNA enables more efficient isolation of low amounts of DNA from forensic samples and may, for some sample types, provide improved DNA yields. Addition of carrier RNA to sample lysates did not interfere with downstream STR analyses. This protocol has not been thoroughly tested and optimized by QIAGEN.

Equipment and Reagents to Be Supplied by User

When working with chemicals, always wear a suitable lab coat, disposable gloves, and protective goggles. For more information, consult the appropriate material safety data sheets (MSDSs), available from the product supplier.

All protocols

- Thermomixer, heating block, or water bath
- Vortexer
- Pipets and pipet tips (to prevent cross-contamination, we strongly recommend the use of pipet tips with aerosol barriers)
- Distilled water

For BioRobot EZ1 users

- BioRobot EZ1 instrument (cat. no. 9000705) and disposables
- EZ1 DNA Investigator Card (cat. no. 9016387)

For EZ1 Advanced users

- EZ1 Advanced instrument (cat. no. 9001410)
- EZ1 Advanced DNA Investigator Card (cat. no. 9018302)

For EZ1 Advanced XL users

- EZ1 Advanced XL instrument (cat. no. 9001492)
- EZ1 Advanced XL DNA Investigator Card (cat. no. 9018699)

For EZ1 Advanced and EZ1 Advanced XL users

For documentation purposes, one of the following is required:

- EZ1 Advanced Communicator Software (supplied with the EZ1 Advanced and EZ1 Advanced XL instruments), PC (can be connected with up to 4 EZ1 Advanced and EZ1 Advanced XL instruments), and monitor (cat. no. for PC and monitor 9016643)
- EZ1 Advanced Communicator Software (supplied with the EZ1 Advanced and EZ1 Advanced XL instruments) and your own PC and monitor (connection with up to 4 EZ1 Advanced and EZ1 Advanced XL instruments not recommended)
- Printer (cat. no. 9018464) and accessory package for printer (cat. no. 9018465)

For purification of DNA from dried blood

- Filter paper (e.g., QIAcard® FTA® Spots, see "Ordering Information", page 57)
- Manual paper punch, 3 mm (e.g., Harris UNI-CORE 3.00 mm Punch Kit (4), cat. no. 159331, or equivalent punch with cutting mat)

For purification of DNA from forensic surface and contact swabs

Plastic swabs with cotton or Dacron® tips (Puritan® applicators with plastic shafts and cotton or Dacron tips are available from: Hardwood Products Company, <u>www.hwppuritan.com</u>, item nos. 25-806 1PC and 25-806 1PD; and from Daigger, <u>www.daigger.com</u>, cat. nos. EF22008D and EF22008DA). Nylon cytology brushes and other swab types may also be used.*

For purification of DNA from chewing gum

Forceps

For purification of DNA from human tissues

1.5 ml screw-capped tubes

For purification of DNA from epithelial cells mixed with sperm cells

- Buffer G2, cat. no. 1014636
- 1 M dithiothreitol (DTT)
- Microcentrifuge
- Forceps

For purification of DNA from hair

- QIAGEN Proteinase K, cat. no. 19131 or 19133
- DTT solution (1 M dithiothreitol, 10 mM sodium acetate, pH 5.2)

For purification of DNA from bones or teeth

- QIAGEN Proteinase K, cat. no. 19131 or 19133
- 0.5 M EDTA, pH 8.3
- Liquid nitrogen
- 2 ml microcentrifuge tubes
- Microcentrifuge
- TissueLyser II, cat. no. 85300, with the Grinding Jar Set, S. Steel, cat. no. 69985, or an equivalent bead mill

For purification of DNA from soil

- InhibitEX® tablets (contact QIAGEN Technical Services, see back cover)
- Microcentrifuge

For DNA purification, large-volume protocol

Buffer MTL (contact QIAGEN Technical Services, see back cover)

^{*} This is not a complete list of suppliers and does not include many important vendors of biological supplies.

Important Notes Starting material

The amount of starting material for use in EZ1 DNA Investigator procedures can vary greatly, depending on the amount of DNA in the sample. Specific guidance for starting amounts is given in the individual protocols. EZ1 instruments can process 200 µl pretreated samples using the trace protocol (page 44) or the "tip dance" protocol (page 46) for DNA purification. With the large-volume protocol (page 49), up to 500 µl pretreated samples can be processed.

Working with EZ1 instruments

The main features of the EZ1 instruments include:

- Purification of high-quality nucleic acids from 1–6 or 1–14 samples per run
- Small footprint to save laboratory space
- Preprogrammed EZ1 Cards containing ready-to-use protocols for nucleic acid purification
- Prefilled, sealed reagent cartridges for easy, safe, and fast setup of EZ1 instruments
- Complete automation of nucleic acid purification, from opening of reagent cartridges to elution of nucleic acids, with no manual centrifugation steps

Additional features of the EZ1 Advanced and EZ1 Advanced XL include:

- Bar code reading and sample tracking
- Kit data tracking with the Q-Card provided in the kit
- UV lamp to help eliminate sample carryover from run-to-run and to allow pathogen decontamination on the worktable surfaces

Note: UV decontamination helps to reduce possible pathogen contamination of the EZ1 Advanced and EZ1 Advanced XL worktable surfaces. The efficiency of inactivation has to be determined for each specific organism and depends, for example, on layer thickness and sample type. QIAGEN cannot guarantee complete eradication of specific pathogens.

EZ1 Cards, EZ1 Advanced Cards, and EZ1 Advanced XL Cards

Protocols for nucleic acid purification are stored on preprogrammed EZ1 Cards (integrated circuit cards). The user simply inserts an EZ1 Advanced XL Card into the EZ1 Advanced XL, an EZ1 Advanced Card into the EZ1 Advanced, or an EZ1 Card into the BioRobot EZ1, and the instrument is then ready to run a protocol (Figure 1). The availability of various protocols increases the flexibility of EZ1 instruments.



Figure 1. Ease of protocol setup using EZ1 Cards. Inserting an EZ1 Card, containing a protocol, into an EZ1 instrument. The instrument should only be switched on after an EZ1 Card is inserted. EZ1 Cards should not be exchanged while the instrument is switched on.

The EZ1 DNA Investigator Kit requires use of the EZ1 Advanced XL DNA Investigator Card with the EZ1 Advanced XL, or use of the EZ1 Advanced DNA Investigator Card with the EZ1 Advanced, or use of the EZ1 DNA Investigator Card with the BioRobot EZ1. These EZ1 Cards contain protocols for purification of DNA from forensic and human-identity samples.

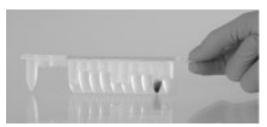
EZ1 instruments should only be switched on after an EZ1 Card is inserted. Make sure that the EZ1 Card is completely inserted (Figure 2), otherwise essential instrument data could be lost, leading to a memory error. EZ1 Cards should not be exchanged while the instrument is switched on.



Figure 2. Complete insertion of EZ1 Card. The EZ1 Card must be completely inserted before the EZ1 instrument is switched on.

Reagent cartridges

Reagents for the purification of nucleic acids from a single sample are contained in a single reagent cartridge (Figure 3). Each well of the cartridge contains a particular reagent, such as magnetic particles, lysis buffer, wash buffer, or elution buffer. Since each well contains only the required amount of reagent, generation of waste due to leftover reagent at the end of the purification procedure is avoided.



В

Α



Figure 3. Ease of setup using reagent cartridges. A sealed, prefilled reagent cartridge. Fill levels vary, depending on the type of reagent cartridge. I Loading reagent cartridges into the cartridge rack. The cartridge rack itself is labeled with an arrow to indicate the direction in which reagent cartridges must be loaded.

Worktable

The worktable of EZ1 instruments is where the user loads samples and the components of the EZ1 DNA Investigator Kit (Figure 4).

Details on worktable setup are provided in the protocols in this handbook and are also displayed in the vacuum fluorescent display (VFD) of the EZ1 Advanced and EZ1 Advanced XL or the liquid-crystal display (LCD) of the BioRobot EZ1 control panel when the user starts worktable setup.

The display also shows protocol status during the automated purification procedure.



Figure 4. Typical EZ1 worktable.

- 1. First row: Elution tubes (1.5 ml) are loaded here.
- 2. Second row: Tip holders containing filter-tips are loaded here.
- 3. Third row: Tip holders containing filter-tips are loaded here. (In some protocols, this row is empty or loaded with 2 ml Sarstedt tubes.)
- 4. Fourth row: Sample tubes (2 ml) are loaded here.
- 5. Reagent cartridges are loaded into the cartridge rack.
- 6. Heating block with 2 ml tubes in the reagent cartridges for lysis.

Data tracking with the EZ1 Advanced and EZ1 Advanced XL

The EZ1 Advanced and EZ1 Advanced XL enable complete tracking of a variety of data for increased process control and reliability. The EZ1 Kit lot number and expiration date are entered at the start of the protocol using the Q-Card bar code. A user ID and the Q-Card bar code can be entered manually via the keypad or by scanning bar codes using the handheld bar code reader. Sample and assay information can also be optionally entered at the start of the protocol. At the end of the protocol run, a report file is automatically generated. The EZ1 Advanced and EZ1 Advanced XL can store up to 10 result files, and the data can be transferred to a PC or directly printed on a printer (for ordering information, see "Equipment and Reagents to Be Supplied by User" on page 13).

To receive report files on a PC, the EZ1 Advanced Communicator software needs to be installed. The software receives the report file and stores it in a folder that you define. After the PC has received the report file, you can use and process the file with a LIMS (Laboratory Information Management System) or other programs. An example of a report file is shown in Appendix B (page 55). In report files, the 6 pipetting channels of the EZ1 Advanced are named, from left to right, channels A to F or the 14 pipetting channels of the EZ1 Advanced XL are named, from left to right, channels 1–14.

When scanning a user ID or Q-Card bar code with the bar code reader, a beep confirms data input. After the information is displayed for 2 seconds, it is automatically stored, and the next display message is shown. When scanning sample ID, assay kit ID, or notes, a beep confirms data input, the information is displayed, and a message prompts you to enter the next item of information. After scanning sample ID, assay kit ID, and notes, press "ENT" once to confirm that the information entered is correct. If, for example, a wrong bar code was scanned for one of the samples, press "ESC" and then rescan all sample bar codes according to the onscreen instructions. For user ID and notes, you can enter the numbers using the keypad, or you can easily generate your own bar codes to encode these numbers.

For details about data tracking and using EZ1 Advanced Communicator software, see the EZ1 Advanced User Manual or the EZ1 Advanced XL User Manual.

Workflow of EZ1 operation



^{*} EZ1 Advanced and EZ1 Advanced XL only.

Yield of purified DNA

DNA yields depend on the sample type, number of nucleated cells in the sample, and the protocol used for DNA purification. Table 1 shows typical yields for some common reference sample types.

| Sample type | Sample amount | Protocol | DNA yield |
|--------------|---------------|--------------------|-------------|
| Blood* | 10–200 µl | Trace or Tip dance | 150 ng–2 µg |
| Dried blood | 4 x 3 mm dics | Tip dance | 0.2–0.5 µg |
| Buccal cells | 1 swab | Tip dance | 100 ng–2 µg |

Table 1. DNA yields from common reference sample types using EZ1 DNA Investigator procedures

 $^{*}\,$ Whole blood with 3–7 x 10 6 white blood cells/ml; elution volume 200 $\mu l.$

Precipitate in reagent cartridge

The buffer in well 1 of the reagent cartridge (the well that is nearest to the front of the EZ1 instrument when the reagent cartridge is loaded) may form a precipitate upon storage. If necessary, redissolve by mild agitation at 37° C and then place at room temperature ($15-25^{\circ}$ C).

Equilibrating reagent cartridges

If reagent cartridges have been stored at 2–8°C, they must be equilibrated to operating temperature before use. Place the reagent cartridge into a shaker-incubator and incubate at $30-40^{\circ}$ C with mild agitation for at least 2 hours before use. If precipitates are visible at the bottom of the wells, redissolve by incubating at $30-40^{\circ}$ C with mild agitation for a further 2 hours. Do not use the reagent cartridges if the precipitates do not redissolve.

Lysis with proteinase K

The EZ1 DNA Investigator Kit contains proteinase K, which is the enzyme of choice for lysis buffers used in EZ1 DNA Investigator protocols. Proteinase K is a recombinant protein expressed in *Pichia pastoris* and is particularly suitable for short digestion times. It possesses a high specific activity and remains stable over a wide range of temperatures and pH values, with substantially increased activity at higher temperatures. The activity of the proteinase K solution is 600 mAU/ml solution (or 40 mAU/mg protein). This activity provides optimal results in EZ1 DNA Investigator protocols.

Additional QIAGEN Proteinase K is required for purification of DNA from hair, bones, or teeth (see page 57 for ordering information).

Quantification of DNA

Depending on the sample type, the yields of DNA obtained in the purification procedure may be below 1 µg and therefore difficult to quantify using a spectrophotometer. In addition, eluates prepared with carrier RNA may contain much more carrier RNA than target nucleic acids. We recommend using quantitative amplification methods to determine yields.

Carryover of magnetic particles may affect the absorbance reading at 260 nm (A_{260}) of the purified DNA but should not affect downstream applications. The measured absorbance at 320 nm (A_{320}) should be subtracted from all absorbance readings.

To eliminate carried-over magnetic particles, the tube containing the eluate should first be applied to a suitable magnetic separator and the eluate transferred to a clean tube.

Protocol: Pretreatment for Whole Blood

This protocol is designed for isolation of total (genomic and mitochondrial) DNA from fresh or frozen blood.

Starting material

This protocol is designed for processing up to 200 μl of human whole blood.

Storage of blood samples

Whole blood samples treated with EDTA, ACD, or heparin* can be used, and may be either fresh or frozen. Frozen samples should be thawed at room temperature (15–25°C) with mild agitation before beginning the procedure. Yield and quality of the purified DNA depend on storage conditions of the blood. Fresher blood samples may yield better results.

- For short-term storage (up to 10 days), collect blood in tubes containing EDTA as an anticoagulant, and store the tubes at 2–8°C. However, for applications requiring maximum fragment size, such as Southern blotting, we recommend storage at 2–8°C for up to 3 days only, as low levels of DNA degradation will occur after this time.
- For long-term storage, collect blood in tubes containing a standard anticoagulant (preferably EDTA, if high-molecular–weight DNA is required), and store the tubes at –70°C.

Important points before starting

- Before beginning the procedure, read "Important Notes", page 15.
- Proteinase K is not required in this protocol.

Procedure

- 1. Thaw and equilibrate up to 6 whole blood samples at room temperature (15–25°C).
- 2. Transfer 200 µl of each sample into EZ1 sample tubes (2 ml).

For samples <200 µl, bring the volume up to 200 µl with Buffer G2.

3. Continue with Protocol: DNA Purification (Trace Protocol), page 44.

^{*} When working with chemicals, always wear a suitable lab coat, disposable gloves, and protective goggles. For more information, consult the appropriate material safety data sheets (MSDSs), available from the product supplier.

Protocol: Pretreatment for Dried Blood

This protocol is designed for isolation of total (genomic and mitochondrial) DNA from dried blood. The protocol describes sample collection and the preliminary lysis of dried blood samples using proteinase K.

Starting material

Drying blood on filter paper is an effective form of storage and samples prepared in this manner are cheaper and safer to transport. A disc (3 mm diameter) punched out from filter paper stained with dried blood contains white blood cells from approximately 5 µl whole blood; we recommend using 4 punched-out discs as starting material.

Important point before starting

Before beginning the procedure, read "Important Notes", page 15.

Things to do before starting

- As filter paper tends to be absorbent, it is generally necessary to add a greater volume of digestion buffer to the sample in step 4. To provide sufficient digestion buffer for absorbent samples, Buffer G2 should be diluted with distilled water before use. Dilute Buffer G2 in distilled water using a ratio of 1:1 (i.e., one volume of Buffer G2 to one volume of distilled water) for n+1 samples (where n is the number of samples to be digested). Use of diluted Buffer G2 does not influence DNA yield or quality.
- Heat a thermomixer, heating block, or water bath to 56°C for the proteinase K digest in step 6.
- Heat a thermomixer, heating block, or water bath to 95°C for use in step 7.

Procedure

1. Collect 70 µl of each blood sample onto a ring marked on filter paper. Allow the blood to air-dry.

Either untreated blood or blood containing an anticoagulant (EDTA, ACD, or heparin)* can be used.

- 2. For each dried blood sample, use the manual paper punch to cut out four 3 mm diameter discs.
- 3. Transfer each set of 4 discs to a 2 ml sample tube.

^{*} When working with chemicals, always wear a suitable lab coat, disposable gloves, and protective goggles. For more information, consult the appropriate material safety data sheets (MSDSs), available from the product supplier.

 Add 190 µl diluted Buffer G2 to the sample. Check if the sample has absorbed some or all of the buffer, and if necessary add more diluted Buffer G2 to the sample tube until the sample volume is 190 µl.

Note: Prepare diluted Buffer G2 as described in "Things to do before starting".

- 5. Add 10 µl proteinase K, and mix thoroughly by vortexing for 10 s.
- 6. Incubate at 56°C for 15 min.

Vortex the tube once or twice during the incubation, or place in a thermomixer.

7. Recommended: Incubate at 95°C for 5 min.

Incubating the sample at 95°C may increase the yield of DNA.

- 8. If necessary, flick the tube to remove drops from inside the lid.
- 9. Continue with Protocol: DNA Purification ("Tip Dance" Protocol), page 46.

Using the "tip dance" protocol, there is generally no need to remove solid material from the tube.

Alternatively, to eliminate the risk of clogging the tips, remove any solid material from the tube. Using forceps, press the solid material against the inside of the tube to obtain maximum sample volume. The sample volume should be approximately 200 µl. Continue with Protocol: DNA Purification (Trace Protocol), page 44.

This protocol is designed for isolation of total (genomic and mitochondrial) DNA from saliva samples. The protocol describes the preliminary lysis of saliva samples using proteinase K.

Starting material

The amount of saliva should not exceed 50 µl. For larger volumes, if the sample is very dilute, see Protocol: DNA Purification (Large-Volume Protocol), page 49.

Important point before starting

Before beginning the procedure, read "Important Notes", page 15.

Things to do before starting

Heat a thermomixer, heating block, or water bath to 56°C for the proteinase K digest in step 4.

Procedure

- 1. Place up to 50 µl saliva in a 2 ml sample tube.
- 2. Add 140–190 µl Buffer G2 to the sample to bring the total volume up to 190 µl.
- 3. Add 10 μl proteinase K, and mix thoroughly by vortexing for 10 s.
- 4. Incubate at 56°C for 15 min.

Vortex the tube once or twice during the incubation, or place in a thermomixer.

- 5. If necessary, flick the tube to remove drops from inside the lid.
- 6. Continue with Protocol: DNA Purification (Trace Protocol), page 44.

Protocol: Pretreatment for Forensic Surface and Contact Swabs

This protocol is designed for isolation of total (genomic and mitochondrial) DNA from forensic surface and contact swabs. The protocol describes the preliminary lysis of forensic surface and contact swabs using proteinase K.

Starting material

Swabs may be processed on the same day as collection or stored for future processing. While storage at -20°C is recommended, DNA of suitable quality for single-copy gene amplification has been documented from swabs stored at room temperature for 24 months.

Important points before starting

- This protocol has been tested using the following swab types: plastic swabs with cotton or Dacron tips. (Puritan applicators with plastic shafts and cotton or Dacron tips are available from: Hardwood Products Company, <u>www.hwppuritan.com</u>, item nos. 25-806 1PC and 25-806 1PD; and from Daigger, <u>www.daigger.com</u>, cat. nos. EF22008D and EF22008DA). Nylon cytology brushes and other swab types may also be used.
- Before beginning the procedure, read "Important Notes", page 15.

Things to do before starting

- Allow the swab or brush to air-dry for at least 2 h after sample collection.
- As swabs tend to be absorbent, it is generally necessary to add a greater volume of digestion buffer to the sample in step 2. To provide sufficient digestion buffer for absorbent samples, Buffer G2 should be diluted with distilled water before use. Dilute Buffer G2 in distilled water using a ratio of 1:1 (i.e., one volume of Buffer G2 to one volume of distilled water) for n+1 samples (where n is the number of samples to be digested). Use of diluted Buffer G2 does not influence DNA yield or quality.
- Heat a thermomixer, heating block, or water bath to 56°C for the proteinase K digest in step 4.
- Heat a thermomixer, heating block, or water bath to 95°C for use in step 5.

Forensic Surface and Contact Swabs

Procedure

- 1. Carefully cut or break off the end part of the swab or brush into a 2 ml sample tube, using an appropriate tool (e.g., scissors).
- 2. Add 290 µl of diluted Buffer G2 to the sample.

Note: Prepare diluted Buffer G2 as described in "Things to do before starting".

3. Add 10 µl proteinase K, and mix thoroughly by vortexing for 10 s.

If processing brush samples, centrifuge the tube briefly (at $10,000 \times g$ for $30 \times g$) to force the brush to the bottom of the tube.

4. Incubate at 56°C for 15 min.

Vortex the tube 1–2 times during the incubation, or place in a thermomixer.

5. Recommended: Incubate at 95°C for 5 min.

Incubating the sample at 95°C may increase the yield of DNA.

6. If necessary, flick the tube to remove drops from inside the lid.

7. Continue with Protocol: DNA Purification ("Tip Dance" Protocol), page 46.

Using the "tip dance" protocol, there is generally no need to remove the swab or brush from the tube.

Alternatively, to eliminate the risk of clogging the tips, remove the swab or brush from the tube. Using forceps, press the swab or brush against the inside of the tube to obtain maximum sample volume. The sample volume should be approximately 200 µl. Continue with Protocol: DNA Purification (Trace Protocol), page 44.

Protocol: Pretreatment for Nail Scrapings

This protocol is designed for isolation of total (genomic and mitochondrial) DNA from forensic nail-scraping samples. The protocol describes the preliminary lysis of nail-scraping samples using proteinase K.

Starting material

The amount of biological sample material should not exceed 40 mg.

Important point before starting

Before beginning the procedure, read "Important Notes", page 15.

Things to do before starting

Heat a thermomixer, heating block, or water bath to 56°C for the proteinase K digest in step 4.

Procedure

- 1. Place the nail-scraping sample in a 2 ml sample tube.
- 2. Add 190 µl Buffer G2 to the sample.
- 3. Add 10 µl proteinase K, and mix thoroughly by vortexing for 10 s.
- 4. Incubate at 56°C for 15 min.

Vortex the tube once or twice during the incubation, or place in a thermomixer.

5. If necessary, flick the tube to remove drops from inside the lid.

6. Continue with Protocol: DNA Purification ("Tip Dance" Protocol), page 46.

Using the "tip dance" protocol, there is generally no need to remove solid material from the tube.

Alternatively, to eliminate the risk of clogging the tips, remove any solid material from the tube. Using forceps, press the solid material against the inside of the tube to obtain maximum sample volume. The sample volume should be approximately 200 µl. Continue with Protocol: DNA Purification (Trace Protocol), page 44.

Protocol: Pretreatment for Chewing Gum

This protocol is designed for isolation of total (genomic and mitochondrial) DNA from forensic chewing-gum samples. The protocol describes the preliminary lysis of chewing-gum samples using proteinase K.

Starting material

Use of up to 40 mg of chewing gum cut into small pieces is recommended.

Important point before starting

Before beginning the procedure, read "Important Notes", page 15.

Things to do before starting

Heat a thermomixer, heating block, or water bath to 56°C for the proteinase K digest in step 4.

Procedure

- 1. Place the chewing-gum sample in a 2 ml sample tube.
- 2. Add 190 µl Buffer G2 to the sample.
- 3. Add 10 µl proteinase K, and mix thoroughly by vortexing for 10 s.
- 4. Incubate at 56°C for 15 min.

Vortex the tube once or twice during the incubation, or place in a thermomixer.

- 5. If necessary, flick the tube to remove drops from inside the lid.
- Remove any solid material from the tube. Using forceps, press the solid material against the inside of the tube to obtain maximum sample volume. The sample volume should be approximately 200 µl. Continue with Protocol: DNA Purification (Trace Protocol), page 44.

Protocol: Pretreatment for Cigarette Butts

This protocol is designed for isolation of total (genomic and mitochondrial) DNA from forensic cigarette-butt samples. The protocol describes the preliminary lysis of saliva and epithelial cells on paper from cigarette butts using proteinase K.

Starting material

Use of approximately 1 \mbox{cm}^2 paper from the end of the cigarette or filter is recommended.

Important point before starting

Before beginning the procedure, read "Important Notes", page 15.

Things to do before starting

- As cigarette butts tend to be absorbent, it is generally necessary to add a greater volume of digestion buffer to the sample in step 2. To provide sufficient digestion buffer for absorbent samples, Buffer G2 should be diluted with distilled water before use. Dilute Buffer G2 in distilled water using a ratio of 1:1 (i.e., one volume of Buffer G2 to one volume of distilled water) for n+1 samples (where n is the number of samples to be digested). Use of diluted Buffer G2 does not influence DNA yield or quality.
- Heat a thermomixer, heating block, or water bath to 56°C for the proteinase K digest in step 4.
- Heat a thermomixer, heating block, or water bath to 95°C for use in step 5.

Procedure

- 1. Place the cigarette-butt sample in a 2 ml sample tube.
- 2. Add 190 µl diluted Buffer G2 to the sample. Check if the sample has absorbed some or all of the buffer, and if necessary add more diluted Buffer G2 to the sample tube until the sample volume is 190 µl.

Note: Prepare diluted Buffer G2 as described above in "Things to do before starting".

- 3. Add 10 µl proteinase K, and mix thoroughly by vortexing for 10 s.
- 4. Incubate at 56°C for 15 min.

Vortex the tube once or twice during the incubation, or place in a thermomixer.

5. Recommended: Incubate at 95°C for 5 min.

Incubating the sample at 95°C may increase the yield of DNA.

6. If necessary, flick the tube to remove drops from inside the lid.

7. Continue with Protocol: DNA Purification ("Tip Dance" Protocol), page 46.

Using the "tip dance" protocol, there is generally no need to remove solid material from the tube.

Alternatively, to eliminate the risk of clogging the tips, remove any solid material from the tube. Using forceps, press the solid material against the inside of the tube to obtain maximum sample volume. The sample volume should be approximately 200 µl. Continue with Protocol: DNA Purification (Trace Protocol), page 44.

Protocol: Pretreatment for Postage Stamps

This protocol is designed for isolation of total (genomic and mitochondrial) DNA from postage stamps. The protocol describes the preliminary lysis of postage-stamp samples using proteinase K.

Starting material

Use of a 0.5–2.5 cm² piece of postage stamp is recommended.

Important point before starting

Before beginning the procedure, read "Important Notes", page 15.

Things to do before starting

- As postage stamps tend to be absorbent, it is generally necessary to add a greater volume of digestion buffer to the sample in step 2. To provide sufficient digestion buffer for absorbent samples, Buffer G2 should be diluted with distilled water before use. Dilute Buffer G2 in distilled water using a ratio of 1:1 (i.e., one volume of Buffer G2 to one volume of distilled water) for n+1 samples (where n is the number of samples to be digested). Use of diluted Buffer G2 does not influence DNA yield or quality.
- Heat a thermomixer, heating block, or water bath to 56°C for the proteinase K digest in step 4.
- Heat a thermomixer, heating block, or water bath to 95°C for use in step 5.

Procedure

- 1. Place the piece of postage stamp in a 2 ml sample tube.
- Add 190 µl diluted Buffer G2 to the sample. Check if the sample has absorbed some or all of the buffer, and if necessary add more diluted Buffer G2 to the sample tube until the sample volume is 190 µl.

Note: Prepare diluted Buffer G2 as described above in "Things to do before starting".

- 3. Add 10 µl proteinase K, and mix thoroughly by vortexing for 10 s.
- 4. Incubate at 56°C for 15 min.

Vortex the tube once or twice during the incubation, or place in a thermomixer.

5. Recommended: Incubate at 95°C for 5 min.

Incubating the sample at 95°C may increase the yield of DNA.

6. If necessary, flick the tube to remove drops from inside the lid.

7. Continue with Protocol: DNA Purification ("Tip Dance" Protocol), page 46.

Using the "tip dance" protocol, there is generally no need to remove solid material from the tube.

Alternatively, to eliminate the risk of clogging the tips, remove any solid material from the tube. Using forceps, press the solid material against the inside of the tube to obtain maximum sample volume. The sample volume should be approximately 200 µl. Continue with Protocol: DNA Purification (Trace Protocol), page 44.

Protocol: Pretreatment for Stains on Fabric

This protocol is designed for isolation of total (genomic and mitochondrial) DNA from stains on fabric (e.g., blood- or saliva-stained fabrics or leather). The protocol describes the preliminary lysis of stains on fabric using proteinase K. Some samples may require larger volumes for lysis; see Protocol: DNA Purification (Large-Volume Protocol), page 49.

Important point before starting

Before beginning the procedure, read "Important Notes", page 15.

Things to do before starting

- As fabrics tend to be very absorbent, it is generally necessary to add a greater volume of digestion buffer to the sample in step 2. To provide sufficient digestion buffer for absorbent samples, Buffer G2 should be diluted with distilled water before use. Dilute Buffer G2 in distilled water using a ratio of 1:1 (i.e., one volume of Buffer G2 to one volume of distilled water) for n+1 samples (where n is the number of samples to be digested). Use of diluted Buffer G2 does not influence DNA yield or quality.
- Heat a thermomixer, heating block, or water bath to 56°C for the proteinase K digest in step 4.
- Heat a thermomixer, heating block, or water bath to 95°C for use in step 5.

Procedure

- 1. Place the fabric sample in a 2 ml sample tube.
- 2. Add 190 µl diluted Buffer G2 to the sample. Check if the sample has absorbed some or all of the buffer, and if necessary add more diluted Buffer G2 to the sample tube until the sample volume is 190 µl.

Note: Prepare diluted Buffer G2 as described above in "Things to do before starting".

- 3. Add 10 μl proteinase K, and mix thoroughly by vortexing for 10 s.
- 4. Incubate at 56°C for 15 min.

Vortex the tube once or twice during the incubation, or place in a thermomixer.

5. Recommended: Incubate at 95°C for 5 min.

Incubating the sample at 95°C may increase the yield of DNA.

6. If necessary, flick the tube to remove drops from inside the lid.

7. Continue with Protocol: DNA Purification ("Tip Dance" Protocol), page 46.

Using the "tip dance" protocol, there is generally no need to remove solid material from the tube.

Alternatively, to eliminate the risk of clogging the tips, remove any solid material from the tube. Using forceps, press the solid material against the inside of the tube to obtain maximum sample volume. The sample volume should be approximately 200 µl. Continue with Protocol: DNA Purification (Trace Protocol), page 44.

Protocol: Pretreatment for Human Tissues

This protocol is designed for isolation of total (genomic and mitochondrial) DNA from human tissues. The protocol describes the preliminary lysis of tissues using proteinase K.

Important point before starting

Before beginning the procedure, read "Important Notes", page 15.

Things to do before starting

Heat a thermomixer, heating block, or water bath to 56°C for the proteinase K digest in step 4.

Procedure

- 1. Transfer the tissue sample into a 1.5 ml screw-capped tube (not supplied).
- 2. Add 190 µl Buffer G2.

Ensure that tissue pieces are fully submerged in Buffer G2.

- 3. Add 10 µl proteinase K solution and mix by tapping the tube gently.
- 4. Incubate at 56°C until the tissue is completely lysed. Vortex 2–3 times per hour during incubation to disperse the sample, or place in a thermomixer, shaking water bath, or on a rocking platform.

Lysis time varies depending on the type of tissue processed. Lysis is usually complete in 3 h. Lysis overnight is possible and does not influence the preparation.

5. Homogenize the sample by pipetting up and down several times. Transfer the supernatant to a new 2 ml sample tube.

6. Continue with Protocol: DNA Purification ("Tip Dance" Protocol), page 46.

Using the "tip dance" protocol, there is generally no need to remove solid material from the tube.

Alternatively, to eliminate the risk of clogging the tips, remove any solid material from the tube. Remove large pieces of insoluble material and centrifuge at $300 \times g$ for 1 min. The sample volume should be approximately 200μ l. Continue with Protocol: DNA Purification (Trace Protocol), page 44.

Protocol: Pretreatment for Epithelial Cells Mixed with Sperm Cells

This protocol is designed for purification of total (genomic and mitochondrial) DNA from epithelial cells mixed with sperm cells. The protocol describes the preliminary lysis of samples using proteinase K and dithiothreitol (DTT).

Important points before starting

- Before beginning the procedure, read "Important Notes", page 15.
- As some sample types (e.g., fabrics) tend to be very absorbent, it may be necessary to add a greater volume of digestion buffer to the sample in step 2.

Things to do before starting

Heat a thermomixer, heating block, or water bath to 56°C for the proteinase K digest in steps 4 and 12.

Procedure

- 1. Place the forensic sample in a 1.5 ml or 2 ml sample tube.
- 2. Add 190 µl Buffer G2 to the sample.
- 3. Add 10 µl proteinase K, and mix thoroughly by vortexing for 10 s.
- 4. Incubate at 56°C for 15 min.

Vortex the tube once or twice during the incubation, or place in a thermomixer.

- 5. Centrifuge the tube briefly to remove drops from inside the lid.
- 6. Remove any solid material from the tube.

Using forceps, press the solid material against the inside of the tube to obtain maximum sample volume.

The sample volume should be approximately 200 µl.

7. Centrifuge the tube at $15,000 \times g$ for 5 min. Carefully transfer the supernatant to a new tube without disturbing the sperm cell pellet.

DNA from epithelial cells can be purified from the tube containing the supernatant following Protocol: DNA Purification (Trace Protocol), page 44, or, if the epithelialcell fraction is very dilute, Protocol: DNA Purification (Large-Volume Protocol), page 49.

Note: The cell pellet may not be visible.

- 8. Wash the sperm cell pellet by resuspending the pellet in 500 µl Buffer G2. Centrifuge the tube at 15,000 x g for 5 min and discard the supernatant.
- 9. Repeat step 8 two or three times.
- 10. Add 180 µl Buffer G2 to the pellet and resuspend the pellet.
- 11. Add 10 µl proteinase K and 10 µl 1 M DTT, and mix thoroughly by vortexing for 10 s.
- 12. Incubate at 56°C overnight at 850 rpm in a shaker-incubator or thermomixer.
- 13. Centrifuge the tube briefly to remove drops from inside the lid. DNA from sperm cells can now be purified from this tube.
- 14. Continue with Protocol: DNA Purification (Trace Protocol), page 44.

The two tubes in which the epithelial and sperm cells have been separated are now ready for DNA purification.

This protocol is designed for isolation of total (genomic and mitochondrial) DNA from the root ends of plucked hair samples. The protocol describes the preliminary lysis of hair samples using proteinase K and dithiothreitol (DTT).

Starting material

We recommend using 0.5–1 cm from the root ends of plucked hair samples.

Important point before starting

Before beginning the procedure, read "Important Notes", page 15.

Things to do before starting

Heat a thermomixer, heating block, or water bath to 56°C for the proteinase K digest in steps 4 and 6.

Procedure

- 1. Place the hair sample in a 2 ml sample tube.
- 2. Add 180 µl Buffer G2 to the sample.
- 3. Add 10 µl proteinase K and 10 µl DTT solution, and mix thoroughly by vortexing for 10 s.
- 4. Incubate at 56°C for at least 6 h.

Vortex the tube once or twice during the incubation, or place in a thermomixer.

- 5. Add another 10 µl proteinase K and 10 µl DTT solution, and mix thoroughly by vortexing for 10 s.
- 6. Incubate at 56°C for at least 2 h or until the hair samples are completely dissolved.
- 7. If necessary, flick the tube to remove drops from inside the lid.
- 8. Continue with Protocol: DNA Purification ("Tip Dance" Protocol), page 46.

Using the "tip dance" protocol, there is generally no need to remove solid material from the tube.

Alternatively, to eliminate the risk of clogging the tips, remove any solid material from the tube. Using forceps, press the solid material against the inside of the tube to obtain maximum sample volume. Continue with Protocol: DNA Purification (Trace Protocol), page 44.

Protocol: Pretreatment for Bones or Teeth

This protocol is designed for isolation of total (genomic and mitochondrial) DNA from bones or teeth. The protocol describes the preliminary grinding, decalcification using EDTA, and lysis of bone or teeth samples using proteinase K.

Starting material

The amount of biological sample material should not exceed 200 mg.

Important points before starting

- Before beginning the procedure, read "Important Notes", page 15.
- Take time to familiarize yourself with the TissueLyser before starting this protocol. See the TissueLyser Handbook.

Things to do before starting

 Heat a thermomixer, heating block, or water bath to 37°C for the decalcification in step 3.

Procedure

1. Remove and discard the bone or teeth surfaces. Grind the remaining bone or tooth root to a fine powder using the TissueLyser system or an equivalent bead mill.

When using the TissueLyser, transfer the bone sample and the ball into the grinding jar. Pour liquid nitrogen into the grinding jar over the ball and bone fragments. Allow the temperature to equilibrate (i.e., liquid nitrogen stops boiling). Decant the excess liquid nitrogen, close the grinding jar with the lid, and transfer it to the TissueLyser. Grind the bone at 30 Hz for 1 min or until the bone is pulverized (grinding times depend on type, condition, and size of bone).

- 2. Place 150–200 mg of powdered bone into a 2 ml microcentrifuge tube.
- 3. Add 600–700 μl 0.5 M EDTA (pH 8.3), and incubate at 37°C for 24–48 h.

After incubation, set the temperature to 56°C for the next incubation step.

- 4. Add 20 µl QIAGEN Proteinase K, and incubate at 56°C for 3 h.
- 5. Centrifuge at 6000 rpm for 4 min. Transfer 200 µl of the supernatant to an EZ1 sample tube if proceeding with Protocol: DNA Purification (Trace Protocol) or transfer 500 µl of the supernatant to an EZ1 sample tube if proceeding with Protocol: DNA Purification (Large-Volume Protocol).
- 6. Continue with Protocol: DNA Purification (Trace Protocol), page 44, or Protocol: DNA Purification (Large-Volume Protocol), page 49.

This protocol is designed for isolation of total (genomic and mitochondrial) DNA from soil. The protocol describes the preliminary lysis of soil samples and adsorption of inhibitors using InhibitEX tablets (contact QIAGEN Technical Services, see back cover).

Starting material

Up to 0.5 g of soil can be used, depending on the type of soil. With flocculent soil samples, less starting material should be used.

Important points before starting

- Before beginning the procedure, read "Important Notes", page 15.
- Proteinase K is not required in this protocol.
- This protocol requires InhibitEX tablets (contact QIAGEN Technical Services, see back cover).

Things to do before starting

Heat a thermomixer, heating block, or water bath to 95°C for use in step 2.

Procedure

- 1. Place the soil sample in a 2 ml sample tube.
- Add 900 µl distilled water. Resuspend the soil by vortexing, and incubate at 95°C for 10 min.
- 3. Centrifuge the tube at 4000 x g for 10 min. Transfer the supernatant to another 2 ml sample tube and add 190 µl Buffer G2. Mix by vortexing.
- 4. Add 1 InhibitEX tablet and incubate at room temperature (15-25°C) for 1 min.
- 5. Mix by vortexing and centrifuge at 10,000 x g for 2 min. Transfer 200 μ l of the supernatant to an EZ1 sample tube if proceeding with Protocol: DNA Purification (Trace Protocol) or transfer 500 μ l of the supernatant to an EZ1 sample tube if proceeding with Protocol: DNA Purification (Large-Volume Protocol).
- 6. Continue with Protocol: DNA Purification (Trace Protocol), page 44, or Protocol: DNA Purification (Large-Volume Protocol), page 49.

Protocol: Pretreatment for Other Forensic Samples

This protocol is designed as a generic protocol for isolation of total (genomic and mitochondrial) DNA from various forensic samples. The protocol describes the preliminary lysis of samples using proteinase K.

Important point before starting

Before beginning the procedure, read "Important Notes", page 15.

Things to do before starting

- As some sample types (e.g., bloodstained fabrics) tend to be very absorbent, it may be necessary to add a greater volume of digestion buffer to the sample in step 2. To provide sufficient digestion buffer for absorbent samples, Buffer G2 can be diluted with distilled water before use. If necessary, dilute Buffer G2 in distilled water using a ratio of 1:1 (i.e., one volume of Buffer G2 to one volume of distilled water) for n+1 samples (where n is the number of samples to be digested). Use of diluted Buffer G2 does not influence DNA yield or quality.
- Heat a thermomixer, heating block, or water bath to 56°C for the proteinase K digest in step 4.

Procedure

- 1. Place the forensic sample in a 2 ml sample tube.
- 2. Depending on the type of sample, follow either step 2a (for non-absorbent samples) or step 2b (for absorbent samples).
- 2a. Non-absorbent samples:Add 190 µl Buffer G2 to the sample.
- 2b. Absorbent samples:

Add 190 μ l diluted Buffer G2 to the sample. Check if the sample has absorbed some or all of the buffer, and if necessary add more diluted Buffer G2 to the sample tube until the sample volume is 190 μ l.

Note: Prepare diluted Buffer G2 as described above in "Things to do before starting".

3. Add 10 µl proteinase K, and mix thoroughly by vortexing for 10 s.

Other Forensic Samples

4. Incubate at 56°C for 15 min.

Vortex the tube once or twice during the incubation, or place in a thermomixer.

5. If necessary, flick the tube to remove drops from inside the lid.

6. Continue with Protocol: DNA Purification ("Tip Dance" Protocol), page 46.

Using the "tip dance" protocol, there is generally no need to remove solid material from the tube.

Alternatively, to eliminate the risk of clogging the tips, remove any solid material from the tube. Using forceps, press the solid material against the inside of the tube to obtain maximum sample volume. The sample volume should be approximately 200 µl. Continue with Protocol: DNA Purification (Trace Protocol), page 44.

Protocol: DNA Purification (Trace Protocol)

This protocol is designed for isolation of total (genomic and mitochondrial) DNA from forensic samples that have been pretreated as described in the relevant protocols in this handbook (pages 22–43). The protocol describes the simple procedure for setting up the EZ1 instrument and starting a run.

Important points before starting

- If using the EZ1 DNA Investigator Kit for the first time, read "Important Notes" (page 15).
- The reagent cartridges contain guanidine salts and are therefore not compatible with disinfecting reagents containing bleach. See page 8 for safety information.
- Perform all steps of the protocol at room temperature (15–25°C). During the setup procedure, work quickly.
- In some steps of the procedure, one of 2 choices can be made. Choose ▲ (blue) if using the EZ1 Advanced or the EZ1 Advanced XL; choose ● (red) if using the BioRobot EZ1.

Things to do before starting

- If reagent cartridges have been stored at 2–8°C, equilibrate to operating temperature before use. See "Equilibrating reagent cartridges", page 20.
- Remove any solid material from the sample tube. Using forceps, press the solid material against the inside of the tube to obtain maximum sample volume.
- The lysis buffer in the reagent cartridge may form a precipitate during storage. If necessary, redissolve by warming at 37°C, and then place at room temperature (15–25°C).

Procedure

- Insert ▲ the EZ1 Advanced DNA Investigator Card completely into the EZ1 Advanced Card slot of the EZ1 Advanced or the EZ1 Advanced XL DNA Investigator Card completely into the EZ1 Advanced XL Card slot of the EZ1 Advanced XL or ● the EZ1 DNA Investigator Card completely into the EZ1 Card slot of the BioRobot EZ1.
- 2. Switch on the EZ1 instrument.
- 3. Press "START" to start protocol setup. ▲ Follow the onscreen instructions for data tracking.
- 4. Press "1" (for Trace protocol).
- 5. Choose the elution buffer and volume: press "1" to elute in water or "2" to elute in TE buffer. Then press "1", "2", or "3", (or "4", EZ1 Advanced XL only) to select the elution volume.
- 6. Press any key to proceed through the text shown on the display and start worktable setup.

The text summarizes the following steps which describe loading of the worktable. Wear gloves when loading the required items on the worktable.

- 7. Open the instrument door.
- Invert reagent cartridges twice to mix the magnetic particles. Then tap the cartridges to deposit the reagents at the bottom of their wells. Check that the magnetic particles are completely resuspended.

9. Load the reagent cartridges into the cartridge rack.

Note: After sliding a reagent cartridge into the cartridge rack, ensure that you press down on the cartridge until it clicks into place.

- 10. Load opened elution tubes into the first row of the tip rack.
- 11. Load tip holders containing filter-tips into the second row of the tip rack.
- 12. Load opened sample tubes containing digested samples into the back row of the tip rack.

Pretreat the samples following the individual protocols in this handbook.

Note: When using the data tracking option, ensure that the sample ID follows the same order as the samples on the worktable to avoid data mixup.

- 13. Close the instrument door.
- 14. Press "START" to start the purification procedure.

The automated purification procedure takes 15-20 min.

15. When the protocol ends, the display shows "Protocol finished". ▲ Press "ENT" to generate the report file.

The EZ1 Advanced and the EZ1 Advanced XL can store up to 10 report files. Report files can be printed directly on a connected printer or transferred to a computer.

- 16. Open the instrument door.
- 17. Retrieve the elution tubes containing the purified DNA. The DNA is ready to use, or can be stored at 2-8°C for 24 h or at -20°C for longer periods. Discard the sample-preparation waste.*

If the purified DNA is to be analyzed by real-time PCR, tubes containing eluate should first be applied to a suitable magnetic separator and the eluate transferred to a clean tube in order to minimize the risk of magnetic-particle carryover.

- ▲ Optional: Follow the onscreen instructions to perform UV decontamination of the worktable surfaces.
- 19. To run another protocol, press "ESC", prepare samples as described in the relevant protocol, and follow the procedure from step 4 onward. Otherwise, press "STOP" twice to return to the first screen of the display, close the instrument door, and switch off the EZ1 instrument.
- 20. Clean the EZ1 instrument.

Follow the maintenance instructions in the user manual supplied with your EZ1 instrument.

^{*} Sample waste contains guanidine salts and is therefore not compatible with bleach. See page 8 for safety information.

Protocol: DNA Purification ("Tip Dance" Protocol)

This protocol is designed for isolation of total (genomic and mitochondrial) DNA from forensic samples that have been pretreated as described in the relevant protocols in this handbook (pages 22–43). This protocol describes the simple procedure for setting up the EZ1 instrument and starting a run.

In the "tip dance" protocol, the filter-tip moves back-and-forth relative to the worktable platform while pipetting. This enables processing of solid materials, such as swabs, fabrics, blood discs, or cigarette butts, directly in the sample tube. There is generally no need for prior centrifugation to remove solid materials that could clog the tip. However, when processing fluffy sample material such as cotton wool, we recommend removing solid material if you cannot process a replicate sample or the sample material is precious. (Using forceps, press the solid material against the inside of the tube to obtain maximum sample volume.)

Important points before starting

- If using the EZ1 DNA Investigator Kit for the first time, read "Important Notes" (page 15).
- The reagent cartridges contain guanidine salts and are therefore not compatible with disinfecting reagents containing bleach. See page 8 for safety information.
- Perform all steps of the protocol at room temperature (15–25°C). During the setup procedure, work quickly.
- In some steps of the procedure, one of 2 choices can be made. Choose ▲ (blue) if using the EZ1 Advanced or the EZ1 Advanced XL; choose (red) if using the BioRobot EZ1.

Things to do before starting

- If reagent cartridges have been stored at 2–8°C, equilibrate to operating temperature before use. See "Equilibrating reagent cartridges", page 20.
- The lysis buffer in the reagent cartridge may form a precipitate during storage. If necessary, redissolve by warming at 37°C, and then place at room temperature (15–25°C).

Procedure

 Insert ▲ the EZ1 Advanced DNA Investigator Card completely into the EZ1 Advanced Card slot of the EZ1 Advanced or the EZ1 Advanced XL DNA Investigator Card completely into the EZ1 Advanced XL Card slot of the EZ1 Advanced XL or ● the EZ1 DNA Investigator Card completely into the EZ1 Card slot of the BioRobot EZ1.

- 2. Switch on the EZ1 instrument.
- 3. Press "START" to start protocol setup. ▲ Follow the onscreen instructions for data tracking.
- 4. Press "2" (for Trace TD protocol).
- 5. Choose the elution buffer and volume: press "1" to elute in water or "2" to elute in TE. Then press "1", "2", or "3", (or "4", EZ1 Advanced XL only) to select the elution volume.
- 6. Press any key to proceed through the text shown on the display and start worktable setup.

The text summarizes the following steps which describe loading of the worktable. Wear gloves when loading the required items on the worktable.

- 7. Open the instrument door.
- 8. Invert reagent cartridges twice to mix the magnetic particles. Then tap the cartridges to deposit the reagents at the bottom of their wells. Check that the magnetic particles are completely resuspended.
- 9. Load the reagent cartridges into the cartridge rack.

Note: After sliding a reagent cartridge into the cartridge rack, ensure that you press down on the cartridge until it clicks into place.

- 10. Load opened elution tubes into the first row of the tip rack.
- 11. Load tip holders containing filter-tips into the second row of the tip rack.
- 12. Load opened sample tubes containing digested samples into the back row of the tip rack.

Pretreat the samples following the individual protocols in this handbook.

Note: When using the data tracking option, ensure that the sample ID follows the same order as the samples on the worktable to avoid data mixup.

- 13. Close the instrument door.
- 14. Press "START" to start the purification procedure.

The automated purification procedure takes 15–20 min.

15. When the protocol ends, the display shows "Protocol finished". ▲ Press "ENT" to generate the report file.

The EZ1 Advanced and the EZ1 Advanced XL can store up to 10 report files. Report files can be printed directly on a connected printer or transferred to a computer.

16. Open the instrument door.

17. Retrieve the elution tubes containing the purified DNA. The DNA is ready to use, or can be stored at 2-8°C for 24 h or at -20°C for longer periods. Discard the sample-preparation waste.*

If the purified DNA is to be analyzed by real-time PCR, tubes containing eluate should first be applied to a suitable magnetic separator and the eluate transferred to a clean tube in order to minimize the risk of magnetic-particle carryover.

- 18. ▲ Optional: Follow the onscreen instructions to perform UV decontamination of the worktable surfaces.
- 19. To run another protocol, press "ESC", prepare samples as described in the relevant protocol, and follow the procedure from step 4 onward. Otherwise, press "STOP" twice to return to the first screen of the display, close the instrument door, and switch off the EZ1 instrument.
- 20. Clean the EZ1 instrument.

Follow the maintenance instructions in the user manual supplied with your EZ1 instrument.

^{*} Sample waste contains guanidine salts and is therefore not compatible with bleach. See page 8 for safety information.

Protocol: DNA Purification (Large-Volume Protocol)

This protocol is designed for isolation of total (genomic and mitochondrial) DNA from forensic samples that have been pretreated as described in the relevant protocols in this handbook (pages 22–43). This protocol describes the simple procedure for setting up the EZ1 instrument and starting a run.

Starting material

Using this protocol, up to $500 \ \mu$ l of pretreated sample can be processed. This not only allows efficient DNA purification from dilute samples with low concentrations of DNA, such as diffuse stains, but also enables purification from samples that require larger volumes for thorough lysis. For these samples, increase the amount of Buffer G2 as required. The amount of proteinase K generally does not need to be increased.

The ability to process larger sample volumes — with the same elution volume as the standard trace protocol — enables higher yields of more concentrated DNA for greater sensitivity in downstream applications.

Important points before starting

- If using the EZ1 DNA Investigator Kit for the first time, read "Important Notes" (page 15).
- The reagent cartridges contain guanidine salts and are therefore not compatible with disinfecting reagents containing bleach. See page 8 for safety information.
- Perform all steps of the protocol at room temperature (15–25°C). During the setup procedure, work quickly.
- This protocol requires extra Buffer MTL (contact QIAGEN Technical Services, see back cover).
- In some steps of the procedure, one of 2 choices can be made. Choose ▲ (blue) if using the EZ1 Advanced or the EZ1 Advanced XL; choose (red) if using the BioRobot EZ1.

Things to do before starting

- If reagent cartridges have been stored at 2–8°C, equilibrate to operating temperature before use. See "Equilibrating reagent cartridges", page 20.
- Remove any solid material from the sample tube. Using forceps, press the solid material against the inside of the tube to obtain maximum sample volume.
- The lysis buffer in the reagent cartridge may form a precipitate during storage. If necessary, redissolve by warming at 37°C, and then place at room temperature (15–25°C).

Procedure

- Insert ▲ the EZ1 Advanced DNA Investigator Card completely into the EZ1 Advanced Card slot of the EZ1 Advanced or the EZ1 Advanced XL DNA Investigator Card completely into the EZ1 Advanced XL Card slot of the EZ1 Advanced XL or ● the EZ1 DNA Investigator Card completely into the EZ1 Card slot of the BioRobot EZ1.
- 2. Switch on the EZ1 instrument.
- 3. Press "START" to start protocol setup. ▲ Follow the onscreen instructions for data tracking.
- 4. Press "3" (for Large-Volume protocol).
- 5. Choose the elution buffer and volume: press "1" to elute in water or "2" to elute in TE buffer. Then press "1", "2", or "3", (or "4", EZ1 Advanced XL only) to select the elution volume.
- 6. Press any key to proceed through the text shown on the display and start worktable setup.

The text summarizes the following steps which describe loading of the worktable. Wear gloves when loading the required items on the worktable.

- 7. Open the instrument door.
- 8. Invert reagent cartridges twice to mix the magnetic particles. Then tap the cartridges to deposit the reagents at the bottom of their wells. Check that the magnetic particles are completely resuspended.
- 9. Load the reagent cartridges into the cartridge rack.

Note: After sliding a reagent cartridge into the cartridge rack, ensure that you press down on the cartridge until it clicks into place.

- 10. Load opened elution tubes into the first row of the tip rack.
- 11. Load tip holders containing filter-tips into the second row of the tip rack.
- 12. Add 400 µl Buffer MTL to each sample tube containing digested samples. Load opened sample tubes containing Buffer MTL and digested samples into the back row of the tip rack.

Pretreat the samples following the individual protocols in this handbook.

Note: When using the data tracking option, ensure that the sample ID follows the same order as the samples on the worktable to avoid data mixup.

13. Close the instrument door.

14. Press "START" to start the purification procedure.

The automated purification procedure takes 15–20 min.

15. When the protocol ends, the display shows "Protocol finished". ▲ Press "ENT" to generate the report file.

The EZ1 Advanced and the EZ1 Advanced XL can store up to 10 report files. Report files can be printed directly on a connected printer or transferred to a computer.

- 16. Open the instrument door.
- 17. Retrieve the elution tubes containing the purified DNA. The DNA is ready to use, or can be stored at 2-8°C for 24 h or at -20°C for longer periods. Discard the sample-preparation waste.*

If the purified DNA is to be analyzed by real-time PCR, tubes containing eluate should first be applied to a suitable magnetic separator and the eluate transferred to a clean tube in order to minimize the risk of magnetic-particle carryover.

- ▲ Optional: Follow the onscreen instructions to perform UV decontamination of the worktable surfaces.
- 19. To run another protocol, press "ESC", prepare samples as described in the relevant protocol, and follow the procedure from step 4 onward. Otherwise, press "STOP" twice to return to the first screen of the display, close the instrument door, and switch off the EZ1 instrument.
- 20. Clean the EZ1 instrument.

Follow the maintenance instructions in the user manual supplied with your EZ1 instrument.

^{*} Sample waste contains guanidine salts and is therefore not compatible with bleach. See page 8 for safety information.

Troubleshooting Guide

This troubleshooting guide may be helpful in solving any problems that may arise. For more information, see also the Frequently Asked Questions page at our Technical Support Center: <u>www.qiagen.com/FAQ/FAQList.aspx</u>. The scientists in QIAGEN Technical Services are always happy to answer any questions you may have about either the information and protocols in this handbook or sample and assay technologies (for contact information, see back cover or visit <u>www.qiagen.com</u>)

| | | comments and soggestions |
|-----|--|--|
| Gei | neral handling | |
| a) | Error message in instrument display | Refer to the user manual supplied with your EZ1 instrument. |
| b) | Report file not printed | Check whether the printer is connected to the EZ1 Advanced or EZ1 Advanced XL via the "PC/Printer" serial port. |
| | | Check whether the serial port is set for use with a printer. |
| c) | Report file not sent to the PC | Check whether the PC is connected to the EZ1 Advanced or EZ1 Advanced XL via the "PC/Printer" serial port. |
| | | Check whether the serial port is set for use with a PC. |
| d) | Wrong Q-Card ID entered | If the wrong ID was entered instead of the Q-Card ID, the EZ1 Advanced/EZ1 Advanced XL will not accept the ID and will prompt for the Q-Card ID until the correct ID is entered. Press "STOP" twice to go to the main menu. |
| Lov | v DNA yield | |
| a) | Magnetic particles not completely resuspended | Ensure that you invert the reagent cartridges several times to resuspend the magnetic particles. |
| b) | Insufficient reagent aspirated | After inverting the reagent cartridges to resuspend the magnetic particles, ensure that you tap the cartridges to deposit the reagents at the bottom of the wells. |

Comments and suggestions

| | | Comments and suggestions |
|----|-----------------------------------|---|
| c) | Purified DNA stored in water | Elute in TE buffer instead of water. Elution in TE buffer gives comparable performance and provides increased stability for long- term storage of small amounts of purified DNA. |
| d) | Varying pipetting volumes | To ensure pipetting accuracy, it is important that buffer volumes in the reagent cartridges are correct and that the filter tips fit optimally to the tip adapter. Ensure that samples are thoroughly mixed and that reagent cartridges have not passed their expiry date. Perform regular maintenance as described in the instrument user manual. Check the fit of the filter tips regularly as described in the user manual. |
| DN | A does not perform well in downst | ream applications |

UNA does not perform well in downstream applications

| a) | Insufficient DNA used in | | | | | downstream |
|----|--------------------------|-----|----------------|------------|---------|-----------------|
| | downstream applications | app | olication usir | ng more e | eluate. | |
| b) | Excess DNA used in | | | | | e enzymatic |
| | downstream application | rea | ctions. Dilute | e the elua | te or ι | ise less in the |

downstream application. Quantify the purified DNA by measurement of the absorbance using an appropriate method.

Appendix A: Purification of Low Amounts of DNA

This protocol is designed for purification of isolation of total (genomic and mitochondrial) DNA from forensic samples that contain <100 ng DNA. The protocol describes the addition of carrier RNA to sample lysates. For full details, refer to Kishore, R., Hardy, W.R., Anderson, V.J., Sanchez, N.A., and Buoncristiani, M.P.H. (2006) Optimization of DNA extraction from low-yield and degraded samples using the BioRobot EZ1 and BioRobot M48. J. Forensic Sci. Vol. **51**, No. 5, 1055.

The procedure has not been thoroughly tested and optimized by QIAGEN.

Important point before starting

Before beginning the procedure, read "Important Notes", page 15.

Things to do before starting

- Add 310 µl nuclease-free water or TE buffer to the tube containing carrier RNA (310 µg) to obtain a solution of 1 µg/µl.
- Dissolve the carrier RNA thoroughly, divide it into single-use aliquots, and store at -70°C.

Procedure

- 1. Pretreat samples according to the appropriate pretreatment protocol given on pages 22–43 of this handbook.
- 2. Add 1 µl of thawed carrier RNA solution (1 µg) to each lysate. It is not necessary to incubate the carrier RNA and sample lysate.
- 3. Continue immediately with Protocol: DNA Purification (Trace Protocol), Protocol: DNA Purification ("Tip Dance" Protocol), or Protocol: DNA Purification (Large-Volume Protocol) on pages 44, 46, or 49 of this handbook.

Appendix B: Example of an EZ1 Advanced Report File

This appendix shows a typical report file generated on the EZ1 Advanced. The values for each parameter will differ from the report file generated on your EZ1 Advanced. Please note that "User ID" is allowed a maximum of 9 characters, and that "Assay kit ID" and "Note" are allowed a maximum of 14 characters.

The EZ1 Advanced XL generates a similar report file containing instrument and protocol information relevant to the EZ1 Advanced XL and information for channels 1–14.

REPORT - FILE EZ1 Advanced:

| Serial No. EZ1 Advanced: User ID: Firmware version: Installation date of instr.: Weekly maintenance done on: Yearly maintenance done on: Date of last UV-run: Start of last UV-run: | 4121 4121 V 1.0.0 Arr 15, 2008 Mar 10, 2008 Arr 20, 2008 16:06 |
|--|--|
| End of last UV-run: | |
| Status UV-run: Protocol name: | _ DNA Investigator |
| Date of run: | Aprl 21, 2008 |
| Start of run: | 12:57 |
| End of run: | 13:31 |
| Status run: | o.k. |
| Error Code: | |
| Sample input Vol [ul]: | 200 |
| Elution volume [ul]: | 100 |
| Channel A: | |
| Sample ID: | 123456789 |
| Reagen Kit number: | 9801301 |
| Reagen Lot number: | 23456789 |
| Reagent Expiry date: | 1208 |
| Assay kit ID: | 848373922 |
| Note: | 2000 |

Channel B:

| Sample ID: | 234567890 |
|----------------------|-----------|
| Reagen Kit number: | 9801301 |
| Reagen Lot number: | 23456789 |
| Reagent Expiry date: | 1208 |
| Assay kit ID: | 836266738 |
| Note: | |

Channel C:

| Sample ID: | 345678901 |
|----------------------|-----------|
| Reagen Kit number: | 9801301 |
| Reagen Lot number: | 23456789 |
| Reagent Expiry date: | 1208 |
| Assay kit ID: | 883727832 |
| Notes: | 1000 |

Channel D:

| Sample ID: | 456789012 |
|----------------------|-----------|
| Reagen Kit number: | 9801301 |
| Reagen Lot number: | 23456789 |
| Reagent Expiry date: | 1208 |
| Assay kit ID: | 763684837 |
| Note: | |

Channel E:

| Sample ID: | 567890123 |
|----------------------|------------|
| Reagen Kit number: | 9801301 |
| Reagen Lot number: | 23456789 |
| Reagent Expiry date: | |
| Assay kit ID: | 4387728002 |
| Note: | |

Channel F:

| Sample ID: | 678901234 |
|----------------------|-----------|
| Reagen Kit number: | 9801301 |
| Reagen Lot number: | 23456789 |
| Reagent Expiry date: | 1208 |
| Assay kit ID: | 509389403 |
| Note: | 50 |

Ordering Information

| Product | Contents | Cat. no. |
|--|---|----------|
| EZ1 DNA Investigator Kit (48) | For 48 preps: Reagent Cartridges, Disposable Tip Holders, Disposable Filter-Tips, Sample Tubes, Elution Tubes, Buffers and Reagents; includes Certificate of Analysis | 952034 |
| EZ1 Advanced XL | Robotic instrument for automated purification of nucleic acids from up to 14 samples using EZ1 Kits, 1-year warranty on parts and labor* | 9001492 |
| EZ1 Advanced | Robotic instrument for automated purification of nucleic acids using EZ1 Kits, 1-year warranty on parts and labor* | 9001410 |
| EZ1 Advanced XL DNA Investigator Card | Preprogrammed card for EZ1 Advanced XL DNA Investigator protocols on the EZ1 Advanced XL | 9018699 |
| EZ1 Advanced DNA Investigator Card | Preprogrammed card for EZ1 Advanced DNA Investigator protocols | 9018302 |
| EZ1 DNA Investigator Card | Preprogrammed card for BioRobot EZ1 DNA Investigator protocols | 9016387 |
| Accessories | | |
| Filter-Tips and Holders, EZ1 (50) | 50 Disposable Filter-Tips, 50 Disposable Tip Holders; additional tips and holders for use with EZ1 Kits | 994900 |
| 12-Tube Magnet | Magnet for separating magnetic particles in 12 x 1.5 ml or 2 ml tubes | 36912 |
| Buffer G2 (260 ml) | Lysis buffer for EZ1 DNA procedures | 1014636 |
| QIAGEN Proteinase K (2 ml) | 2 ml (>600 mAU/ml, solution) | 19131 |
| QIAGEN Proteinase K (10 ml) | 10 ml (>600 mAU/ml, solution) | 19133 |
| TissueLyser II | Universal laboratory mixer-mill disruptor | 85300 |

* Warranty PLUS 2 (cat. no. 9237720) recommended: 3-year warranty, 1 preventive maintenance visit per year, 48-hour priority response, all labor, travel, and repair parts.

Ordering Information

| Product | Contents | Cat. no. |
|--|---|----------|
| Grinding Jar Set, S. Steel (2 x 10 ml) | 2 Grinding Jars (10 ml), 2 Stainless Steel Grinding Balls (20 mm) | 69985 |
| PC and TFT Monitor, 17" | PC capable of connection with up to 4 EZ1 Advanced or EZ1 Advanced XL instruments; Monitor for use with PC | 9016643 |
| Printer | Printer for connection with EZ1 Advanced or EZ1 Advanced XL instrument | 9018464 |
| Printer Accessory Package | Accessories for printer connected to EZ1 Advanced or EZ1 Advanced XL instrument | 9018465 |
| QIAcard FTA One Spot (100) | For collection and storage of 100 samples: 100 QIAcard FTA One Spots | 159201 |
| QIAcard FTA Two Spots (100) | For collection and storage of 100 x 2 samples: 100 QIAcard FTA Two Spots | 159203 |
| QIAcard FTA Four Spots (100) | For collection and storage of 100 x 4 samples: 100 QIAcard FTA Four Spots | 159205 |
| QIAcard FTA Indicator Four Spots (25) | For collection and storage of 25 x 4 samples: 25 QIAcard FTA Indicator Four Spots | 159214 |
| QIAcard FTA Purification Reagent (500 ml) | For use with QIAcard FTA Spots: 500 ml QIAcard FTA Purification Reagent | 159300 |
| Related products | | |
| EZ1 DNA Blood 200 µl Kit (48) | 48 Reagent Cartridges, 50 Disposable Tip Holders, 50 Disposable Filter-Tips, 50 Sample Tubes, 50 Elution Tubes | 951034 |
| EZ1 DNA Blood 350 µl Kit (48) | 48 Reagent Cartridges, 50 Disposable Tip Holders, 50 Disposable Filter-Tips, 50 Sample Tubes, 50 Elution Tubes | 951054 |

Ordering Information

| Product | Contents | Cat. no. |
|------------------------------|--|----------|
| EZ1 DNA Tissue Kit (48) | 48 Reagent Cartridges, 50 Disposable Tip Holders, 50 Disposable Filter-Tips, 50 Sample Tubes, 50 Elution Tubes, Buffer G2, Proteinase K | 953034 |
| EZ1 Virus Mini Kit v2.0 (48) | For 48 virus nucleic acid preps: Reagent Cartridges (Virus Mini v2.0), Disposable Tips, Disposable Tip-Holders, Sample Tubes, Elution Tubes, Buffers | 955134 |

For up-to-date licensing information and product-specific disclaimers, see the respective QIAGEN kit handbook or user manual. QIAGEN kit handbooks and user manuals are available at <u>www.qiagen.com</u> or can be requested from QIAGEN Technical Services or your local distributor.

Visit www.qiagen.com/goto/EZ1Advanced to find out more about other EZ1 Kits!

Notes

Notes

Notes

Trademarks: QIAGEN®, QIAcard®, BioRobot®, EZ1®, InhibitEX® (QIAGEN Group); 903® (S&S Biosciences, Inc.); Dacron® (E. I. du Pont de Nemours and Company); FTA® (Whatman PLC); Puritan® (Hardwood Products Company).

Limited License Agreement

Use of this product signifies the agreement of any purchaser or user of the EZ1 DNA Investigator Kit to the following terms:

- The EZ1 DNA Investigator Kit may be used solely in accordance with the EZ1 DNA Investigator Handbook and for use with components contained in the Kit only. QIAGEN grants no license under any of its intellectual property to use or incorporate the enclosed components of this Kit with any components not included within this Kit except as described in the EZ1 DNA Investigator Handbook and additional protocols available at <u>www.giagen.com</u>.
- Other than expressly stated licenses, QIAGEN makes no warranty that this Kit and/or its use(s) do not infringe the rights of third-parties.
- 3. This Kit and its components are licensed for one-time use and may not be reused, refurbished, or resold.
- 4. QIAGEN specifically disclaims any other licenses, expressed or implied other than those expressly stated.
- 5. The purchaser and user of the Kit agree not to take or permit anyone else to take any steps that could lead to or facilitate any acts prohibited above. QIAGEN may enforce the prohibitions of this Limited License Agreement in any Court, and shall recover all its investigative and Court costs, including attorney fees, in any action to enforce this Limited License Agreement or any of its intellectual property rights relating to the Kit and/or its components.

For updated license terms, see <u>www.qiagen.com</u>.

© 2009 QIAGEN, all rights reserved.

www.qiagen.com

Australia = Orders 03-9840-9800 = Fax 03-9840-9888 = Technical 1-800-243-066 Austria = Orders 0800/28-10-10 = Fax 0800/28-10-19 = Technical 0800/28-10-11 Belgium = Orders 0800-79612 = Fax 0800-79611 = Technical 0800-79556 Brazil = Orders 0800-557779 = Fax 55-11-5079-4001 = Technical 0800-557779 Canada = Orders 800-572-9613 = Fax 800-713-5951 = Technical 800-DNA-PREP (800-362-7737) China = Orders 0086-21-3865-3865 = Fax 0086-21-3865-3965 = Technical 800-988-0325, 800-988-0327 Denmark = Orders 80-885945 = Fax 80-885944 = Technical 80-885942 Finland = Orders 0800-914416 = Fax 0800-914415 = Technical 0800-914413 France = Orders 01-60-920-926 = Fax 01-60-920-925 = Technical 01-60-920-930 = Offers 01-60-920-928 Germany = Orders 02103-29-12000 = Fax 02103-29-22000 = Technical 02103-29-12400 Hong Kong = Orders 800 933 965 = Fax 800 930 439 = Technical 800 930 425 Ireland = Orders 1800-555-049 = Fax 1800-555-048 = Technical 1800-555-061 Italy = Orders 02-33430-420 = Fax 02-33430-426 = Technical 800-787980 Japan = Telephone 03-6890-7300 = Fax 03-5547-0818 = Technical 03-6890-7300 Korea (South) = Orders 1544 7145 = Fax 1544 7146 = Technical 1544 7145 Luxembourg = Orders 8002-2076 = Fax 8002-2073 = Technical 8002-2067 Mexico = Orders 01-800-7742-639 = Fax 01-800-1122-330 = Technical 01-800-7742-639 The Netherlands = Orders 0800-0229592 = Fax 0800-0229593 = Technical 0800-0229602 Norway = Orders 800-18859 = Fax 800-18817 = Technical 800-18712 Singapore = Orders 65-67775366 = Fax 65-67785177 = Technical 65-67775366 Spain = Orders 91-630-7050 = Fax 91-630-5145 = Technical 91-630-7050 Sweden = Orders 020-790282 = Fax 020-790582 = Technical 020-798328 Switzerland = Orders 055-254-22-11 = Fax 055-254-22-13 = Technical 055-254-22-12 UK = Orders 01293-422-911 = Fax 01293-422-922 = Technical 01293-422-999 USA = Orders 800-426-8157 = Fax 800-718-2056 = Technical 800-DNA-PREP (800-362-7737)



Sample & Assay Technologies



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

12.0 Certification of a New or Reconditioned VERSA 1100 Liquid Handler

12.1 Purpose:

Acceptance of a new or reconditioned VERSA 1100 Liquid Handler before implementation in the laboratory relies upon (1) the proper installation (2) proper internal calibration checks (3) protocol setup, and (4) a certification exercise.

Documentation of <u>these</u> exercises will be retained in the appropriate VERSA use log next to the instrument in the lab. The certification protocol will ensure that a new or reconditioned VERSA is calibrated so that it functions reliably in achieving specified liquid handling results when operated according to the user manual and laboratory defined protocols.

Thereafter, internal calibration checks of consumable calibration settings will be performed according to the manufacturer's instructions on an as needed basis or during the annual maintenance service call by Aurora Biomed. Records of these tests will be kept in the appropriate VERSA use log next to the robots in the lab.

12.2 References:

VERSA 100 Operation Manual January

1. HARDWARE INSTALLATION AND SETUP

The VERSA 1100 is approximately 920W x 615 L x 999H (mm) including bio-safety hood. It is recommended that the user provide enough space on all sides of the instrument, especially at the back where the Priming, Waste Bottles, and Reagent Box will be situated. The workbench should be stable, vibration free, and capable of handling up to 90kg.

There are a total of five tubing connections to be made on the VERSA 1100.

- A out (Vacuum) This hole is open to air.
- V in (Vacuum) Blue This tubing provides vacuum and is connected to the Waste Bottle.
 Make sure that this tubing DOES NOT touch the waste solution.
- *W* (*Waste*) *Blue* This tubing connects to the Waste Bottle. Waste liquid that comes from the priming block of the single channel and 4-channel pumps is deposited here.
- **PB (Pressure Box)** This tubing is used for providing pressure to the reagent bottles. This tubing goes to the 3-way reagent bottle valve.
- *P (Pressure) Red* This tubing is used to provide air pressure and is connected to the Priming Bottle. This tubing should not touch the water in the bottle.
- L (Priming Solution) Red Cap This tubing supplies the priming solution for both the 4channel and single channel syringe pumps and is connected to the Priming Bottle. Fill this bottle with distilled water.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

The Priming, Waste, and Reagent bottles are provided with 3-hole bottle caps. Two holes are used either for the solution, pressure, or vacuum. The third hole is provided with either a stopper or a plug. Please observe that a bottle cap with the plug on the outside is used for the Waste Bottle and the bottom cap with the plug inside is used for the Priming and Reagent bottles. It is very important that the correct cap is used for its designated bottle.

The connection to the computer is via USB cable. Please plug the cable into the USB port at the back panel near the power outlet and to the personal computer socket labeled as USB. The power cable should then be plugged into the power source. The power switch is located above the power cable connection.

12.3 Software

Open the software by double-clicking the VERSAware 1100 icon. The username is "admin". No password is required. The Shell Status will appear first, followed by the VERSAware.

| Task ID | | |
|----------|---------|--|
| AS01 [1] |]: 4848 | |
| DH01 [1 |]: 4020 | |
| WW01 | | |
| | | |

Figure 1: Shell Status window.

There are three interfaces to the software: VERSAware, Aurora Station, and PWM Pump.

- VERSAware VERSAware is the main interface that the user will using to set up and run protocols
- Aurora Station Aurora station is a support interface that usually runs alongside VERSAware. Aurora Station controls all robotic movement and all manual manipulations of the robot. Position and plate calibration checks, along with control of the heat block, shaker, gripper, syringe pump, and tip changing can be accessed here. There are two ways to access the Aurora Station:
 - Open the "Shell Status" Window which runs alongside VERSAware. Double-click on "AS01 [1]: 1172" and Aurora Station will open from the background.
 - 2. In VERSAware, go to "Tools", then click on "Aurora Station". A checkmark will appear next to the interfaces if it is already opened.



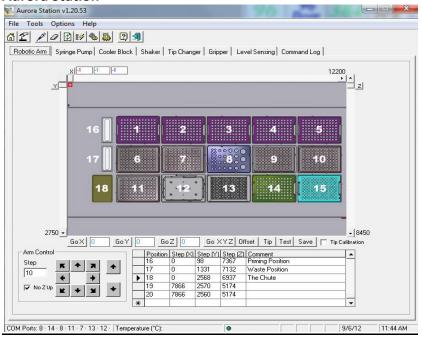
Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

DO NOT CLOSE THE AURORA STATION. It is required for VERSAware to run. Simply minimize the Aurora station window when it is not used.

- PWM Pump The PWM Pump is a support interface that controls all of the liquid pumps, including the single channel syringe, 4-channel syringe, and reagent drop. All of the settings regarding the liquid pumps can be accessed here. Volume calibration checks can also be performed here. There are two ways to access the PMP Pump:
 - Open the "Shell Status" Window which runs alongside VERSAware. Double-click on "DH01 [1]: 5616" and the PWM Pump will open from the background.
 - 2. In VERSAware, go to "Tools", then click on "PWM Pump". A checkmark will appear next to the interfaces if it is already opened.

12.4 Aurora Station





12.4.1 Robotic Arm Tab

The Robotic Arm Tab is the control center for all manual manipulation of the robotic arm. It is crucial that there are no obstructions in the path of the robotic arm prior to movement of the robotic arm.

To initialize all axes of the robotic arm, click on the unlabeled button between the X and Y axes. The robotic arm should travel towards the upper left corner of the workstation. The robotic arm movement can be controlled using two methods:



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

- Scroll bars The scroll bars labeled X (on the top), Y (on the left), and Z (on the right) can be used to control the X, Y, Z axes independently. The current robotic arm coordinates will be displayed in text boxes in the upper left corner. Each scroll bar shows the maximum travel range for that particular axis. The scroll bars are used for bigger movement of the robotic arm.
- 2. Step/Arrow Buttons Enter a step value from 1 to 1,000 and use one of the eight arrows on the left side to control the horizontal X and Y axes. The two arrows on the right will control the vertical Z axis. Please be aware of the amount of space between the robotic arm and the surface when selecting the step value. The step/arrow buttons are used for finer movement of the robotic arm.

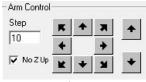


Figure 3: Step/arrow buttons

There are several functions listed above the table:

| | Comment | Step [Z] | Step [Y] | Step (X) | Position |
|---|-----------------------|----------|----------|----------|----------|
| - | 1000 μL Tip Box/Plate | 7737 | 2525 | 7837 | 14 |
| | 20 μL Tip Box/Plate | 7756 | 2526 | 10233 | 15 |
| | Priming Position | 7367 | 98 | 0 | 16 |
| | Waste Position | 7132 | 1331 | 0 | 17 |
| | The Chute | 6937 | 2568 | 0 | 18 |

Figure 4

• Go X, Y, Z

To test previously saved default teaching positions, double-click on the record selector of the desired position. The X, Y, Z coordinates will be displayed in the text boxes "Go X, Go Y, and Go Z". Click on "Go X, Y, Z" to have the arm moved to the last calibrated position.

<u>Note</u>: Only use "Go X, Y, Z" if **no tip is engaged.** The robotic arm will move to the position directly above the surface of the teaching plate. Make sure that a teaching plate and not the plate type is in place to avoid crashing the robotic arm.

Offset

The offset calculator will automatically calculate the X, Y, and Z offsets of two different records in the table. Double-click one position record, then click on a second position record, then click "Offset". The difference in X, Y, and Z positions between the first and second record will be displayed.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

• Tip

To engage a tip, double-click on the record selector of the position from which the tip will be engaged. Positions 2 & 3 hold 50 μ L tips; positions 4 & 5 hold 1000 μ L tips. Click on "Tip" to have the arm move to the tip position and engage a tip.

Test

To test previously saved default teaching positions with **tips engaged**, first engage tips by following the instructions above on "Tip". Double-click on the record selector of the desired position. The X, Y, Z coordinates will be displayed in the text boxes "Go X, Go Y, and Go Z". Click on "Test" to have the robotic arm moved to the last calibrated position. The tip offset difference is incorporated in the Z coordinate.

<u>Note</u>: Make sure that a teaching plate and not the plate type is in place to avoid crashing the robotic arm.

Position Calibration Check

VERSA 1100 workstation features 15 positions for various lab ware types, tips, blocks, tubes, reservoirs, etc. Positions 16, 17, and 18 are the priming, waste, and chute positions, respectively. All the deck positions are taught with a 96-well plate. The shaker position is taught as is. All positions should be taught to locate the surface of the upper left well (A1) of the 96-well teaching plate. No pipetting tip should be engaged. The X & Y coordinates should be adjusted so the tip barrel is positioned in the center of the well. For calibration check of the Z coordinate, a piece of paper can be placed in between the tip barrel and the surface of the 96-well teaching plate. Fine adjustments are made until the tip barrel just touches the paper. Slight resistance should be felt when inserting or removing the paper. Upon completion of all position calibration check, the position setting for all other plate types which are available in the Labware library will be automatically calibrated with respect to the 96-well teaching plate based on the offsets in the plate type library.

Calibrate a Position

To calibrate or teach a new plate type, double-click on the position you want to teach. No tip should be engaged. Place a 96-well teaching plate on the deck. Set the Z coordinate to 0 in the "Go Z" text box. Click "Go X, Y, Z". If necessary, adjust the X and Y coordinates. Click on the down arrow to adjust the Z coordinates. Reduce the steps of the arm control to 5 or 10 steps for more precise and safe control of the arm movement. The tip barrel should be directly above the teaching plate so that a piece of paper should be able to pass through between the teaching plate and the barrel tip with slight resistance. Click "Save".

Note: If a tip was engaged to calibrate a position, make sure that the **"Tip Calibration"** box is checked. This informs the robot to account for the height differences of a tip.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

Testing Plate Types

Aurora Station allows you to test previously or newly taught positions for all plate types. It is a good practice to test positions periodically to ensure that the calibration checks for a particular plate type and position is still accurate.

First, engage a tip following the instruction above on "Tip". Place the plate type onto the position to be tested. To test the position with that particular plate type, go to "Options \rightarrow

Aurora Station Settings" or click on the "Aurora Station settings" icon . Click the "Advanced" tab. On the bottom left corner of the screen under "Test Position [Plate Type]", select the position to test (ignore the description of the position). Click "Apply".

| eneral Advanced Accessories Plate Types Hardv Tip Engagement (Robotic Arm) | Shaker | Syringe Pump |
|--|---|---|
| Start Speed (step/s) 50 End Speed (step/s) 500 Acceleration (step/s ²) 1 | Start Speed (step/s) 100 Acceleration (step/s ²) 10 | Pump Connected to Arm Pump Device 0 Device Address (hex) 31 |
| | Communication | |
| Respent/Cooler Block Cooler Address 1 - Channel 1 - Position 12 - Shaker/Cooler Plate Taught using - Cooler Control Delay (me) 10000 Source Temperature Source 1 Address 2 - Channel 2 - Position 13 - Source/Target Flate - | Step Loss Error Count 10 Time Dut Error Count 10 1st Time Dut (s) 600 2nd Time Dut (s) 240 Command Delay (ms) 100 Arm Anddress (hex) 33 | Positions [Exclude X, Y, Z-Offset] |
| Source 2 Address 2 Channel 1 Position 9 - Source/Target Plate | Auto Recovery X-Offset (step) 2400 | Syringe Pump |
| Chute Orientation | Tip Disengagement | 250 µL Small Syringe Pump |
| ☞ Y-Axis C X-Axis | Y-Offset (step) 800 | Small Syringe Pump Only |
| Test Position [Plate Type] | Plate Type [Teaching Positions] | Position Test Mode |
| Position 15 - 20 µL Tip Box/Plate | Plate Type 1 - 96-well Plate 💌 | Single Channel Test |

Figure 5: Aurora Station settings/Advanced tab.

Next, click on the "Plate Types" tab. Under the "Symmetrical Plates" section, select the plate type that you want to test in that position by highlighting the selection. Click on the icon with a small red square on the top left corner to test the top left corner of the plate type or click on the icon with a small red square on the bottom right corner to test the bottom right corner of the plate type.

- · SlicPrep[™] Plate: Plate type #68
- 32-well sample block and reagent cooler block: Plate type #70
 (Testing the 32-well sample block includes the height of the samples tubes)



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

| | Plate Type | Description | | Columns | | | olumn Di | stance | • | | Plate Type | | Volum | ne 🔺 |
|---|------------|---------------------------------------|--------------|-------------|--------|---------|------------|-----------|-------|------|----------------------|----------|-----------------|---------|
| • | 1 | 96-well Plate | | 12 | 8 | 9 | | | _ | | 1 | 10.850 | | |
| | 2 | 384-well Plate | | 24 | 16 | 4. | | | | | 1 | 10.357 | | |
| | 3 | 1536-well Plate | | 48 | 32 | 2. | 25 | | | | 1 | 9.6174 | 40 | |
| | 4 | 12-column Reservoir | | 12 | 1 | 9 | | | | | 1 | 8.631 | 60 | |
| | 5 | 4-glass Slide Tray (X: 13 | 2066, Y: 1 | | 1 | 31 | .0784 | | | | 1 | 7.6446 | 100 | |
| | 6 | 20 µL Tip Box (1-channe | el) | 12 | 8 | 9 | | | - | | 1 | 5.9184 | 140 | |
| • | | | | | | | | • | | | 1 | 4.6854 | 180 | - |
| | 100 | 35-well Reagent/Cooler | | 1 | 1 | 0 | | | 4 [| 1 | 00 1 | 1 | 19.97 | 46 |
| | | es [Plate Types: 100 - 19 | 키 | | | | | | | | Level Sensir | - | | |
| | | Description 35-well Beagent/Cooler | Block (T1) | Column 1 | | | nt Diffen | ance - | 4 1 | | Plate Type (00 1 | | | |
| | 100 | 35-well Reagent/Cooler | | 1 | 2 | 0 | | | 1 F | 1 | 00 1 | - | | |
| | 100 | 35-well Reagent/Cooler | | 1 | 3 | 0 | | | | 1 | 00 1 | 1 | | |
| | 100 | 35-well Reagent/Cooler | Block [T4] | 1 | 4 | 0 | | _ | | 1 | 00 1 | 1 | 13.56 | 3 |
| | 100 | 35-well Reagent/Cooler | Block [T5] | 1 | 5 | 0 | | | -11 | 1 | 00 1 | 1 | 12.33 | - |
| • | | ••••••••••••••••••••••••••••••• | | 1 | | 1 | | • | | | | | | • |
| | | e, Column Offset, Row Of | ifset, LLS C | ompensatio | on, Ba | ase Off | set, Dep | oth in (m | m), V | olum | ə in (µL) | | 0 | |
| | | | Diseventer | Seele Dista | | Circles | Jan Caller | Uninter | D.00- | | Offset (X) | 0610 | مستحد بتلحم الد | |
| | 200 | | 88.57 (| | nce | 1 | 32 | -9.1489 | | ence | 47.7595 | ·13.3931 | | |
| | 201 | | |) | 2 | 1 | 32 | -9.0256 | | _ | 48,1514 | -12.467 | 0 | $-\Box$ |
| | 202 | | 119.28 (| | | 1 | | 17.111 | | | 49.4516 | -49.5522 | | - 1 |
| | 203 | | 118.37 (| | | 1 | | 17.021 | | | 48 | -50 | 0.3 | - |
| • | 200 | notor di 100 A | motor It | , | | | 1100 | 11.021 | | | 140 | 50 | 10.0 | |
| | | l | | | | | | | | | | | | |

Figure 6: Aurora Station settings/Plate Types tab.

The tip should be in the center of the plate type. If the tip isn't in the center of the plate, then either the position (1) wasn't calibrated correctly or the plate type off-set is not calibrated correctly. Test that particular plate type on a different position (2) by repeating the steps above. If the tip is now centered, then that indicates that the position (1) was calibrated incorrectly. Re-calibrate the position (1) by following the steps on how to "Calibrate a Position".

If the tip is still off-centered, then it indicates that the plate type off-set is not calibrated correctly. To adjust the plate type off-set, following the steps below on how to "Adjust Plate Type Off-set".

Adjust Plate Type Offset

Sometimes, the plate type off-sets that are saved in the Labware library can be slightly off. If that plate type is applied to a position, the tip will not be centered above a well but will instead be off-centered, depending on the severity. An off-centered calibration can result in inaccurate liquid pipetting or potential crashing of the robotic arm in severe cases.

To adjust the plate type off-set, bring the robotic arm to the calibrated plate type position by following the steps above on how to "Test Plate Position". Close the "Aurora Station Settings" screen. The X, Y, Z coordinates on the top left corner of the screen (in red, green, and blue numbers) indicates the current position of the robotic arm.

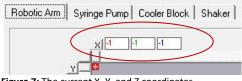


Figure 7: The current X, Y, and Z coordinates.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

Go to a new row on the record selector table, indicated with an "*". Type in an arbitrary position number, such as "100", to distinguish from an actual position. Under the comments column, type "Original". Select the new position by highlighting the selection, then click "Save". The current robotic arm coordinates are now saved onto this new position.

| | Position | Step (X) | Step (Y) | Step (Z) | Comment | |
|---|----------|----------|----------|----------|-----------------------|---|
| | 14 | 7837 | 2525 | 7737 | 1000 μL Tip Box/Plate | |
| | 15 | 10233 | 2526 | 7756 | 20 μL Tip Box/Plate | |
| | 16 | 0 | 98 | 7367 | Priming Position | |
| | 17 | 0 | 1331 | 7132 | Waste Position | |
| | 18 | 0 | 2568 | 6937 | The Chute | |
| * | | | | | | - |

Figure 8: The position records table.

Adjust the robotic arm using the "Step/Arrow Buttons" until the tip is in the center of the well. Create a new row on the record selector table. Type in an arbitrary position number, such as "101". Under the comments column, type "Adjusted". Select the new position by highlighting the selection, then click "Save". The adjusted robotic arm coordinates are now saved onto this new position.

Double-click on the "Adjusted" position record, then click on the "Original" position record, then click "Offset". The "Offset Calculator" screen will appear, showing the X, Y, and Z steps of both records and the difference between the two records will appear in the light blue numbers in millimeters (mm). Record the "Offset" value. Click "OK" to close.

| Column Distance | |
|-------------------|----------|
| ×1 (step) | 0 |
| ×2 (step) | 662 |
| Total Columns | 2 |
| Distance (mm) | 37.6843 |
| Offset (mm) | 37.6843 |
| Row Distance — | |
| Y1 (step) | 1331 |
| Y2 (step) | 42 |
| Total Rows | 2 |
| Distance (mm) | 99.253 |
| Offset (mm) | -99.253 |
| Height Difference | ə |
| Z1 (step) | 7132 |
| Z2 (step) | 7801 |
| Difference (mm) | -21.4481 |
| Offset (mm) | 21.4481 |
| Tip Calibration | 0 |

Figure 9: Offset calculator

Go to "Options \rightarrow Aurora Station Settings". Click on the "Plate Types" tab and select the plate type to be adjusted by highlighting the selection. Scroll to the right until you see the "Height Difference", "Column Offset", and "Row Offset" columns. Adjust the offsets by adding/subtracting the value(s) recorded from the "Offset Calculator". Click "Apply", then "OK" to close.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

| | Coordinate | Positive (+) Value | Negative (-) Value |
|-------------------|------------|-----------------------|-----------------------|
| Column Distance | Х | To the right | To the left |
| Row Distance | Y | Towards user | Away from User |
| Height Difference | Z | Up | Down |

Adjusting the Column and Row Offset Within a Plate Type

Position calibrations align the robot to well A1 of each plate type. Column and row offsets calibration settings for each plate type allow the robot to determine the distance from all other wells with respect to well A1. If it is observed that the calibrations for column 1 is correct but gets increasingly off as it moves to column 12, then the column and row differences may be off for that plate type. To adjust the column and row offset, go to "Options \rightarrow Aurora Station Settings" or click on the "Aurora Station settings" icon . Click the "Plate Type" tab. The following instructions are an example of adjusting the column and row offset for tip racks.

- Place an empty tip rack in the position to test
- In Aurora Station Settings → Accessories tab, change the tip availability to Next Row: 1, Next Column 12
- Go to Aurora Station and double click on the position, then click "Tip"
- Lower the robotic arm until it is right above the tip rack
- Adjust the positioning until it is centered, keeping track of the number of steps moved (x or y direction)
- Convert from steps to mm by going to Aurora Station settings → Hardware → Robotic
 Arm → Scale (x or y). This number is mm/step
- Divide the value in mm by 11
- Go to Plate type, column or row distance, and subtract the value from it.

Heater/Shaker Unit Position Calibration Check

The heater/shaker unit should be calibrated with the plate type used (SlicPrep[™] Plate)

Reagent Drop Pin Position Calibration Check

To calibrate the reagent drop pin, click "Options \rightarrow Aurora Station Settings". Click on the "Advanced" tab. In the bottom left corner under "Test Position [Plate Type]", select the test position. To the right under "Plate Type [Teaching Position]", select "1 – 96 well plate" and click "Apply". Place the 96-well teaching plate in that position. Click on the "Accessories" tab. Under the "Pin Groups" section on the bottom, select the pin number to test by double-clicking. (Only Pin 2 and 3 are used). Click "RD Test". The robotic arm will go to that position and align the reagent drop pin on the surface of the A1 well of the 96-well teaching plate.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

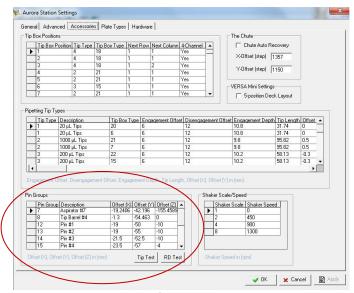


Figure 10: Aurora Station settings/Accessories tab.

To check if the pin is centered on the well, dispense some solution (e.g. 100μ L) manually using the PWM Pump. In the VERSAware interface, go to "Tools \rightarrow PWM Pump". Click on the "C" icon to go into the control mode. Under the "Valves" section, type "100" in the "Volume" column under the desired valve (Valve 1 for Pin 1, etc.). Watch the pin while it dispenses the liquid. If the pin is not dispensing in the center of the well, change the X and Y Offsets in the "Aurora Station Settings \rightarrow Accessories tab \rightarrow Pin Groups" to center the pin.

- Negative value in the X-offset moves the robotic arm/pin to the left side
- Negative value in the Y-offset moves the robotic arm/pin away from the user

When finished, go to the PWM Pump interface and click on the "A" icon to change back to assay mode.

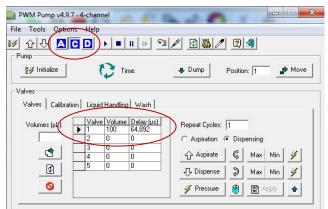


Figure 11: PWM Pump/C Mode.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

In the VERSAware interface, click "Tools \rightarrow Options". Click on the "Reagent Drop" tab. Adjust the reagent drop dispensing Z-offset as necessary. This is the height difference between the reagent drop pins and a plate type when dispensing liquid.

- Negative value moves the arm up
- Positive value moves the arm down

| Syringe Pump Tip Boxes Plate Types Reagent Drop Other | |
|---|----|
| Reagent Drop Priming | |
| Volume (uL) | 10 |
| Reagent Drop Z-Offset | |
| Dispensing Z-Offset (mm) | 3 |

Figure 12: VERSAware/Tools/Options/Reagent Drop Tab

12.4.2 Syringe Pump Tab

The Syringe Pump Tab allows access to manual control of the syringe pump. The syringe pump can be controlled manually to aspirate and dispense liquid and is used for the **syringe pump**

calibration check.

| Aurora Station v1.20.53 | | The second |
|---|--------------|---------------------|
| ile Tools Options Help | | |
| 12 / 0 0 14 % B Q 3 | 9 | |
| Robotic Arm Syringe Pump Cooler Block | | Sensing Command Log |
| Pump Calibration | Syringe Pump | |
| Syringe Pump Type 1000 µL | 🖸 🚺 📩 Time: | 🕼 Reset |
| Scale 26.8 | | |
| Equation: Step (X) = Scale * Volume (µ) | Pump Log | |
| | | * |
| Multiple Scale | | |
| Air Gap Aspiration (step) 390 | | |
| Sample Aspiration (step) 42 | | |
| Time Delay (sec) 5 | | |
| | | |
| Send | | |
| Pump Control | | |
| Function Aspiration | - | |
| Volume (µL) | | |
| Step | | - |
| | | |
| Er Initialize | | Clear |

Figure 13: Aurora Station/ Syringe Pump Tab

Syringe Pump Calibration Check

There are two methods to perform the calibration check procedure. The general sequence of aspirating and dispensing liquid for the calibration is AIR GAP ASPIRATION \rightarrow LIQUID ASPIRATION \rightarrow DISPENSE LIQUID.

1. **Auto Mode** – The auto mode runs the general sequence listed above automatically, incorporating delays in between each step.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit **Ouality Control Manual**

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

- Under the "Pump Calibration" section, type in the steps (1μL = 10 steps) for the air gap aspiration & sample aspiration and the number of seconds for the delay time.
- Click "Send". The instrument will now aspirate X steps of air, wait for Y seconds, aspirate
 Z steps of sample, wait for Y seconds, then dispense X + Z steps of volume.
 - During the <u>first</u> delay step, place the sample tube containing water underneath the pipette tip, making sure that the tip is submerged in the water.
 - During the <u>second</u> delay step, remove the sample tube and place the empty weigh boat underneath the pipette tip.
- 2. **Pump Control Mode** The pump control mode requires manual control of each step in the general sequence listed above.
 - Under the "Pump Control" section, select either the "Volume" or "Steps" option.
 - Volume option: Used for testing particular volumes of liquid to determine if the accurate volume of liquid is aspirated/dispensed
 - Steps option: Used for adjusting or creating a new calibration table
 - Select "Aspiration" as the function, then enter the desired amount of steps (X) for air gap aspiration (1µL ~ 10 steps).
 - Click "Send". The instrument will now aspirate the air gap.
 - Now enter the desired amount of steps (Z) for sample aspiration.
 - Place a sample tube containing water under the pipette tip. Click "Send". The instrument will now aspirate the sample.
 - Select "Dispensing" as the function, then enter the total amount of steps (X + Z) for the air gap aspiration and the sample aspiration.
 - Place an empty weigh boat underneath the pipette tip. Click "Send". The instrument will now dispense the air gap and the sample.

Prior to performing a syringe pump calibration check, prime the syringe pump to eliminate all air bubbles in the system. It is recommended to perform 8-10 cycles of priming to fill up the tubing with the system fluid and remove most of the air trapped within the system. For instructions on how to perform a syringe pump priming, refer to Section 8.3 – Syringe Pump Priming.

Switch to the *Robotic Arm Tab*, initialize the robotic arm by pressing the button between the X and Y axes, then move the robotic arm towards you by dragging the Y axis scroll bar down. This allows the user to have easier access to the syringe pump during the calibration check. Switch back to the *Syringe Pump Tab*.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

Manually engage a tip onto the first barrel. Use a 50µL tip for the 20-50µL range and a 1000µL tip for the 200-1000µL range. Initialize the pump by clicking the "Initialize" button on the bottom of the screen. Under the "Pump Calibration" section, select 4x1000µL as the syringe pump type. Select "Multiple Scale". Prepare a sample tube with water and an empty, pre-tared weigh boat. Using either the **Auto Mode** or the **Pump Control Mode**, aspirate and dispense the desired amount of liquid into the empty, pre-tared weigh boat. Weigh the weigh boat. (Note: When using the Pump Control Mode/Volume option, be sure to aspirate an air gap prior to aspirating the liquid. When dispensing, add an extra 50µL to the dispense volume to make sure that all the air and liquid is pushed out.)

In Aurora Station, click on the "Syringe" icon \checkmark . The calibration table screen should appear. Select the 4x1000µL pump type. Make sure that "Multiple Table" is checked. This allows for multiple calibration tables. Adjust either the existing calibration table values or create a new scale by clicking on an empty row under the "Scale" section. Record the sample aspiration step under the "Step" column and the volume measured in the "Volume" column (1mg = 1µL). Click "Apply", then "OK".

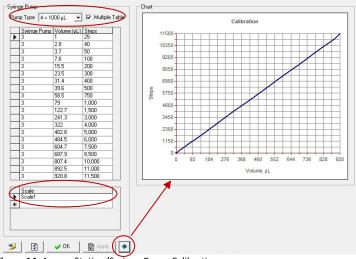


Figure 14: Aurora Station/Syringe Pump Calibration

Measure the volume at different steps by repeating the steps above. Cover the range from 40 - 11,500 steps (~3 - 800μ L).

Reagent drop calibration check

Calibration check of the reagent drop is performed using the PWM Pump. Refer to the Section 4.1 – Reagent Drop Calibration Check for instructions on how to perform a reagent drop calibration check.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

12.4.3 Cooler Block Tab

The Cooler Block Tab sets and monitors the temperature of the cooler/heater block in the range of $0 - 90^{\circ}$ C with 0.25°C increments. The tab allows the user to check or change COM ports or current temperature. The recommended temperature for the cooler/heater block is 4°C, which is also the default value. Unlock the COM port by click "Unlock" to observe readings of actual and current temperatures.

The equation that the instrument uses to calculate and set the temperature is:

Actual Temperature (°C) = [Parameter A x Set Temperature (°C)] + Parameter B

- Parameter A Usually set at 1
- Parameter B Adjusts for the difference between the temperature set on the instrument and the actual temperature in the sample. This might be necessary because the transfer of heat from the cooler/heater block may not be 100% efficient.

To change the current temperature, go to the "Temperature" field and input the new temperature. Click "Apply", then "Send". The current temperature of the cooler/heater block will be displayed in the "Temperature Monitor" section.

| | | Tools Options Help |
|----|---|--|
| | Gripper Level Sensing Command Log | obotic Arm Syringe Pump Cooler Block Shaker Tip Char |
| | Temperature Log | COM Port |
| * | 11:28:44 AM Address 2 < 25 20 11:28:44 AM Address 1 < 30 4 | EØ Open X Close |
| | | Temperature Control |
| - | | Parameter A 1 Serial Number |
| ^ | 11:54:27 AM Address 1> -1 -1 [Ch 1 & 2 read error] 11:54:27 AM Address 1> -1 -1 [Ch 1 & 2 read error] | Parameter B -10 FTTA4HRAB Enumber Actual remperature (*C) = A * Set Temperature (*C) Temperature (*C) 20 |
| Ŧ | 11:54:28 AM Address 1 → 3 - 1 [Lh 1 & 2 read error] 11:54:28 AM Address 1 → 3 - 1 [Lh 1 & 2 read error] 11:54:29 AM Address 1 → 3 - 1 [Lh 1 & 2 read error] 11:54:29 AM Address 1 → 3 - 1 [Lh 1 & 2 read error] 11:54:30 AM Address 1 → 3 - 1 [Lh 1 & 2 read error] | Temperature Monitor |
| ar | Ø Clear | Temperature (*C): N/A |
| | 11:54/2 AM Address 1 → 1 + 1, b1 1 & 2 read error 11:54/2 AM Address 1 → 1 + 1, b1 1 & 2 read error 11:54/2 AM Address 1 → 1 + 1, b1 1 & 2 read error 11:54/2 AM Address 1 → 1 + 1, b1 1 & 2 read error 11:54/2 AM Address 1 → 1 + 1, b1 1 & 2 read error 11:54/2 AM Address 1 → 1 + 1, b1 1 & 2 read error 11:54/2 AM Address 1 → 1 + 1, b1 1 & 2 read error | Temperature (°C) 20 |

Figure 15: Aurora Station/ Cooler Block Tab

12.4.4 Shaker Tab

The Shaker Tab allows the user to set shaker Com ports and test the speed of the shaker manually. Shaker speed can be tested between 100-2200rpm. Change "Speed" and "Time" settings, then click "Apply" to implement the settings. The new settings can now be tested by clicking the "Shake" button.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit

Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

| Pobotic Arm Syring | 10 - 10 - 10 - 10 | | ker Tip Changer | Gripper Leve | ISensing Comma | and Lo |
|----------------------|-------------------|---|-------------------|--------------|----------------|--------|
| - Shaker | | | | | | |
| Serial Port : | 13 | 1 | | | | |
| Address : | 0 | - | | | | |
| Speed (rpm) : | 1000 | - | | | | |
| Time (sec) : | 10 | 2 | | | | |
| | L | | | | | |
| | | | | | | |

Figure 16: Aurora Station/ Shaker Tab

12.4.5 Tip Changer Tab

The Tip Changer Tab will allow the user to command the instrument to release the tips that are currently engaged. The settings currently set do not need to be changed.

Initialize the instrument by clicking the "Initialize" button. Place a container under the tip barrels to catch the tips. Click "Send" to signal the instrument to release the tips.

| 😢 Aurora Station v1.20.53 | 1 |
|--|-------------|
| File Tools Options Help | |
| | |
| Robotic Arm Syringe Pump Cooler Block Shaker Tip Changer Gripper Level Sensing | Command Log |
| Tip Changer Settings | |
| COM Port 12 | |
| Axis 🔀 👻 | |
| Air Pump Device | |
| Unlock | |
| Tip Changer Control | |
| Start Speed (step/s) 50 | |
| End Speed (step/s) 1500 | |
| Acceleration (step/s ²) 10 | |
| Scale (mm/step) 0.0011 | |
| Z-Offset (step) 12000 (* | |
| Z-Distance (mm) 100 C | |
| Cycles 1 | |
| | |

Figure 17: Aurora Station/ Tip Changer Tab

12.4.6 Gripper Tab

The Gripper Tab displays all the settings for the gripper, including the speed settings and gripper control settings.

- **Gripper X-Offset** Determines where on the plate the gripper will pick up. This setting will be used to center the grip on the plate.
- **Grippe Y-Offset** Determines the Y-offset for the gripper to pick up the plate. Increasing the number brings the gripper towards the user.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

- **Gripper Z-Offset** Determines how far down the gripper will go to pick up the plate. Increasing the number makes the gripper go lower.
- **Engagement Off-set** The height where the gripper claw opens up. The number is the height above the plate surface
- **Gripper Safe Off-set** The height in which the gripper will lift the plate during transport. The number is the height above the plate surface
- Gripper Max Range The maximum z range the gripper can move up or down
- **Gripper Pad Clearance** The height that gripping of the plate occurs. 0 is the top surface of the plate.
- Gripper Plate Type Plate type used
- Source Position Deck position where the plate is initially located
- Target Position Deck position where the plate will be transferred to

To test the gripper, place a plate (96-well Slicprep[™] Plate) onto deck position 11. Select "11" as the "Source Position". Select "12" as the "Target Position". Initialize the robot by clicking the "Initialize" button". Click "Move" to move the plate from position 11 to 12 using the gripper.

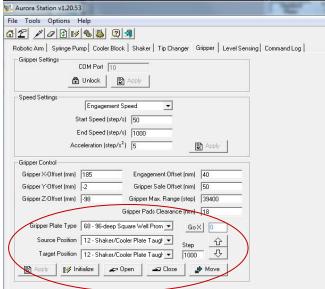


Figure 18: Aurora Station/ Gripper Tab

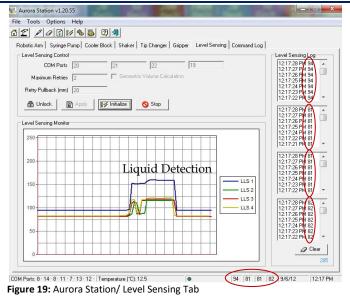
12.4.7 Level Sensing Tab

The Liquid Sensing Tab displays the liquid level sensing signals for all four channels. The signal from each channel is read every second and is recorded in the "Level Sensing Log" on the right. The signal of each channel is also displayed on the bottom right of the screen next to the date and time. A real-time graph of the log is displayed in the "Level Sensing Monitor". The signal is typically around 100 when no liquid is detected. Once a tip detects liquid, the signal will increase.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS



12.4.8 Command Log Tab

The Command Log screen displays the summary of all the executed steps created since the VERSAware was last opened. Click "Clear" to erase logged message once they have been identified and rectified.

12.5 Aurora Station Settings

Click on the "Aurora Station settings" icon 🌺 to configure settings of the system.

General Settings

The General Settings Tab can be used to assign deck positions, activate or deactivate various display icons or tabs. These settings are pre-configured and should optimize the performance of the instrument. They are specific to each workstation leaving Aurora's manufacturing facilities. Contact Aurora Biomed should changes need to be made. Ensure that you click "Apply" to implement any changes in the settings.

Advanced settings

In the Advance Settings tab, changes regarding Tip Engagement (speed), Cooling Block, Shaker (speed), Communication, Auto Recovery, Tip Disengagement, Syringe Pump Priming, Air Gap Adjustments, and etc. can be performed. However, it is strongly recommended not to change the pre-set parameters. In most cases, the users only need to use the "Test Position" function on the bottom left corner to perform testing and offset adjustments. Remember to click "Apply" to implement any changes made.



.

Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

Accessories Settings

The Tip Box positions, Chute, Pipetting Tip Types, Pin Groups, and Shaker configurations are tabulated in the Accessories Settings. Depending on the configuration of the system and the modules in the workstation, some of these options may not apply. These settings come pre-configured or your specific applications. Check with Aurora Biomed for application specific development.

Tip Availability can be change/adjusted in the "Tip Box Positions" section. Under the correct Tip Box Position, change the value for the "Next Row" and "Next Column". Since the instrument uses a 4-channel pipettor head, the only values used for the "Next Row" field should be 1 or 2. The values available for the "Next Column" field ranges from 1-13; 13 indicates that the tip box is empty.

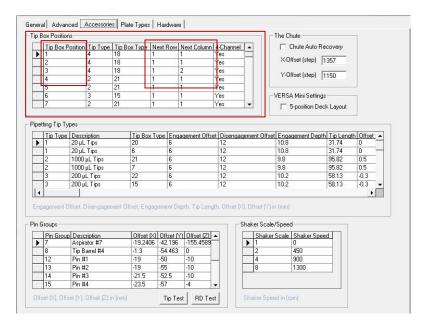


Plate Type Settings

All plate types configuration are tabulated in the Plate Type settings tab. Depending on the configuration of the system and the modules in the workstation, some of these options may not apply. Specific settings, including plate offsets, are recorded for each plate type. The column, row, and height offsets account for the differences between the 96-well teaching plate and the specific plate type. If the pipette tip is not centered after calibrating the teaching position, adjustments to the plate offsets can be made here.

Hardware Settings

In the Hardware Settings tab, the devices attached to the workstation along with the associated COM ports are configured here. Speed and acceleration steps of the robotic arm



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit **Ouality Control Manual**

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

and pump can also be configured. Maximum moving range of the Robotic Arm has already been set and configured. Click "Apply" to implement any changes made.

12.6 PWM Pump

The PWM Pump is a support interface that controls all of the liquid pumps, including the single channel syringe, 4-channel syringe, and reagent drop. All of the settings regarding the liquid pumps can be accessed here. Volume calibration checks can also be performed here. There are two ways to access the PMP Pump:

- Open the "Shell Status" Window which runs alongside VERSAware. Double-click on "DH01 [1]: 4292" and the PWM Pump will open from the background.
- 2. In VERSAware, go to "Tools", then click on "PWM Pump". A checkmark will appear next to the interfaces if it is already opened.

There are three modes in the PWM Pump:

- 1. A (Assay Mode) In order to run a protocol, the instrument must be in assay mode
- 2. **C (Control Mode)** This mode allows the user to gain access to manual control of the pump
- 3. D (Demo Mode)

12.7 Reagent Drop Calibration Check

Prior to performing a reagent drop calibration check, prime the reagent drop system by clicking the "Pump" icon icon on the VERSAware interface. Type "1000" into the Reagent Drop Priming Volume. Click on the "Reagent" button on the bottom.

On the PWM Pump interface, initialize the pump by clicking the "Initialize" button on the top left corner. To perform volume calibration check, click on the "C" icon to switch into control mode. When the pump is operational, the pressure can be observed by clicking the "Chart" button on the bottom right corner. A graphical pressure curve in real-time will appear, showing the user the current pressure maintained. The pressure should be maintained at about 10 psi.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit

Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

| eat Cycles: 1 |
|--------------------------|
| Aspiration (Dispensing |
| Aspiration (• Dispensing |
| Aspirate 💪 Max Min 🐓 |
| Dispense 👂 Max Min 🐓 |
| Pressure |
| |
| |
| · / / / / / |
| |

Click on the "Syringe" icon \swarrow on the top. This puts the instrument in calibration mode. When the calibration mode is selected, the values that the user inputs for volume is actually in terms of delay time, which is the length of time the value is opened for in micro-seconds (μ s).

Click on the "Pump" icon it open the pump calibration table. This is location where all of the calibration scales for the reagent drop is maintained. New calibration data will be recorded here. The volumes for the reagent drop calibration check can be adjusted in the "Dispensing" table. A new scale can be created instead by clicking on the empty row in the "Scales" table. Enter the date and the liquid used to perform the volume calibration check. Under the "Aspiration" table, enter the numbers 1 - 5 in the "Valves" column. Enter "0" in the "Volumes" column. Enter "1" in the "Cycles" column. Enter "0" in the "Pulse" column. Enter "0" in the "Delay" column. Click "Apply", then "OK"



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

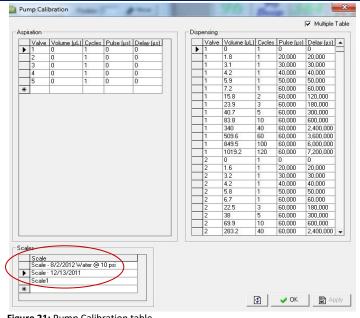
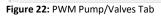


Figure 21: Pump Calibration table

In the PWM Pump main screen, select the "Valves" *Tab* in the "Valves" section. Select the pin valve to calibrate (*Only valves* 1 - 3 *are available on this instrument*). Type "50,000" in the "Volume" column. Make sure that the other valves have "0". Remember, in the calibration mode, this is actually the delay time in μ s that the valve will be opened for. Type "1" for the number of "Repeat Cycles" on the right. Make sure that "Dispensing" is selected. Place an empty, pre-tared weigh boat underneath the reagent drop valve, then click "Dispense". Weigh the volume and record in the pump calibration table.

| Volumes (µL): | Valv | ve Volum | ne Delay (µs) | | epeat Cycles: | 1 | | < l> | |
|---------------|------|----------|---------------|----|---------------|------|---------|------|---|
| voiumes (με). | 1 | 100 | 64,892 | | | | |) | |
| | 2 | 0 | 0 | | Aspiration | Disp | pensing | | |
| | 3 | 0 | 0 | | | 1 | _ | 1 | |
| | 4 | 0 | 0 | 4 | 순 Aspirate | S | Max | Min | 4 |
| 1 | 5 | 0 | 0 | 17 | ን Dispense |) 21 | | | 4 |



Click on the "Pump" icon \checkmark to go into the Pump Calibration screen. In the "Dispensing" table, type the pin valve number that is being calibrated in the "Valve" column. Type 0, 1, 0 in the "Volume, Cycles, Pulse" columns. In the next row, type "1" in the "Cycles" column and "100,000" in the "Pulse" column. The "Delay" will automatically be calculated using the equation: Cycles x Pulse = Delay. Record the volume that was measured in the weigh boat (1mg = 1µL).



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

Measure the volume at multiple cycles by changing the number of "Repeat Cycles" in the main screen. Cover the range from $100,000 - 6,000,000 \mu$ s (~ $10 - 750 \mu$ L). There is no need to do every cycle to reach 6,000,000. Measure an average of about 10 - 15 cycles. After calibration check of one pin valve is completed, repeat for the 2nd and 3rd valve. Enter 0, 1, 0 in the "Volume, Cycles, Pulse" columns for Valves 4 and 5. Click "Apply", then "OK". Switch back to the Assay Mode by clicking on the "A" icon when finished with the volume calibration checks.

12.8 Test Volume Accuracy

The PWM Pump can be used to manually dispense certain volumes of liquid. This function allows the user to periodically test to see if the pump is delivering the accurate volume of liquid.

In the PWM Pump main screen, click the "C" icon to go into Control Mode. Make sure the instrument is not in calibration mode – the "Syringe" icon should not be selected. Type "1" for the number of "Repeat Cycles" on the right. Type the volume of liquid to dispense in the "Volume" column next to the valve that is to be tested. (*Note: do not put the type the volume of liquid to dispense in the "Volume" box on the left*). Place an empty, pre-tared weigh boat below the reagent drop pins and click "Dispense". Weigh the weigh boat and determine if the instrument is accurately dispensing the volume of liquid. If it is not, a volume calibration check might need to be performed. Refer to **Figure 21**.

12.9 Versaware

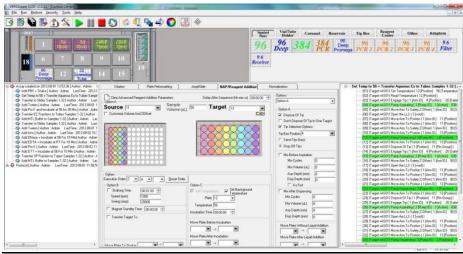


Figure 23: VERSAware interface

12.9.1 Icon Tool Bar

There are a total of 17 user icons available for one-click operations.

New assay 9 – Click to add a new assay. Enter new assay's name and click "OK". The user can then add any number of sequences to the assay.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit **Ouality Control Manual**

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

- New Sequence Click to add a new sequence to an assay. Sequence created can be saved to any existing assay by selecting/highlighting the assay present on the "Assay/Sequence Window" on the left side of the main interface screen.
- Save Current Sequence Click to save any changes made to any existing sequence. It is
 important to update any changes made to an existing sequence by clicking the "Save" icon,
 otherwise the changes will not take effect.
- Delete Click to delete a selected assay or sequence. Select an assay/sequence by highlighting it, then click the "Delete" icon.
- Restore Click to auto backup created assays/sequences or restore after deleting assays/sequences. Selected assay/sequence can be restored by highlighting it, then clicking the "Restore" icon.
- Options → Options Click to enter the VERSAware options. User can make changes to various settings related to the workstation. For further detailed instructions, see the section "Menu Drop-Downs → Options".
- Start > Click to start a selected assay/sequence.
- Pause Click to pause an assay/sequence. User can pause at any stage of the sequence.
 Unclick to resume the run. Sequence will continue form where it left off. The pause function can be used when changes need to be made or to refill tip boxes.
- Stop
 Click to stop an assay/sequence. Sequence will start again from the very beginning if user chooses to run the sequence again.
- Run Continuously Click to run an assay/sequence continuously. Assay/sequence will run continuously until the "Stop" icon is clicked.
- Home A click to send the robotic arm to the home position and to initialize all devices.
- **Pump** Click to prime the syringe pump system.
- Reload Tip Box Click to reload tip boxes. Used to reload tips when prompted with an audible buzz after the robotic arm has picked up its last tip from any box.
- Transfer Tip Click for single channel operation. Arm proceeds to transfer tips from the 8-channel tip box of specified position to the targeted single-channel tip box position for single channel use.
- Color Selector Click to select colors for samples. Color coding the samples will allow the user to follow where a particular sample has been transferred to during sample transferring steps or slide preparation steps.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

- **Restore Interface** Click to refresh the VERSAware main interface.

12.9.2 Drag-Drop Plate Library

Aurora Biomed has accounted for a wide array of plate types found in the market. These have been configured for use on the VERSA 1100 platform to allow users to aspirate from and dispense into. Offsets have also been preset during the manufacturing and testing process. Thus all plate types are ready to use without further user calibration check.

To use a particular plate, move the mouse cursor to that plate type's icon located in the "Plate Library" section on the top right side of the main screen. Click and hold onto that icon while dragging it over to the "Working Deck Configuration" section on the top left side of the main screen. Release to drop the icon onto any of the number position (1 - 15) on the deck.

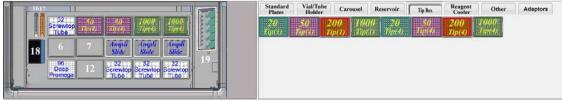


Figure 24: Position decks and plate type library

12.9.3 Menu Drop-Downs

File

The "File" drop-down menu can be used to add an assay/sequence, update a sequence, or delete an assay/sequence. Users can also export or import assays/sequences to/from different file formats. Click on "Export" to save a file or picture (screen shot) to a text (.txt) or picture (.bmp) file, respectively. Users can also print the present screen picture or sequence.

Run

The "Run" drop-down menu can be used to start an assay/sequence, to immediately start a newly created sequence on-screen, and to pause or stop any assay/sequence that is currently running.

Tools

The "Tools" drop-down menu can be used to access the various options that can be used to edit various system settings. The Aurora Station and Aurora PWM Pump can be accessed in this drop-down menu.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

Options

The Options window allows the user to edit or change various system/instrument/plate type settings according to their requirements. When the "Options" window is accessed while a sequence is opened, the changes made in the "Options" will only apply for that particular sequence and not for the entire system/instrument. It is important to click on the "Apply" button and click the "Save" icon for the changes to take effect.

Syringe Pump Setting

The option to prime the syringe pump before running each sequence to remove air bubbles from the tubing system is available. To do so, check the "Prime syringe pump before running each sequence" option on the very top.

Users can also set air gap volumes, mixing air gap volumes, extra aspiration/dispensing volumes for either the single 1000μ L pump or the 4-channel 1000μ L pump. Delays after aspiration/dispensing can also be added in the sequence. This is useful in cases where the solution is viscous. Pump aspiration/dispensing speeds for solutions and air gap aspiration speed can be set.

- Max Volume The maximum amount of volume that the syringe pump will aspirated.
- Air Gap Volume Volume of air that the tip will aspirate prior to aspirating the sample
- Extra Aspiration Volume Extra volume of liquid that will be aspirated for multiple dispense options
- Extra Dispensing Volume Extra volume of liquid that will be dispensed
- Priming Cycles Number of cycles to prime the syringe pump. 8-10 cycles is generally sufficient
- Back Aspiration Volume The volume of liquid the syringe pump uses to prime for each cycle.
- Mixing Air Gap Volume The volume of air that the tip will aspirate between each cycle during a mixing step.

| nge Pump Tip Boxes Plate Types | Reagent Drop 0 | ther | |
|--|----------------|---------|--|
| ^o rime syringe pump before running each | sequence | > | |
| | 1000 uL 4× | 1000 uL | |
| Tip Volume | | | |
| Max. Volume (uL) | 900 | 900 | |
| Switch Volume (uL) | 900 | 900 | |
| Extra Volume | | | |
| Air Gap Volume (uL) | 10 | 50 | |
| Extra Aspiration Volume (uL) | 30 | 30 | |
| Extra Dispensing Volume (uL) | 20 | 20 | |
| Delay | | | |
| Delay After Aspiration (s) | 0 | 0 | |
| Delay After Dispensing (s) | 0 | 0 | |
| Priming | | | |
| Duincine Ourles | 0 | 0 | |

Figure 25: VERSAware/Tools/Options/Syringe Pump Tab



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

Tip Boxes Setting

The Tip Box tab includes the safe Z-offset for safe arm movement above the tip boxes to avoid hitting it. The values set here are set as default data. No change is necessary. The maximum volume which can be aspirated/dispensed for each tip type can also be set here.

Plate Type Settings

The Plate Type tab allows the user to change Z-offsets for any particular plate type. This tab also displays the plate types available for this system that have been pre-specified by the manufacturer. Any changes made here will only affect the current sequence and not the whole system.

The "Aspiration and Dispensing Z-Offset" specifies the height at which the pipette tip will aspirate or dispense. An offset of 0mm is equivalent to the surface of the plate. If the tip dispenses liquid **too far from the bottom** of the well of a plate, **increase** the Z-Offset for dispense by increments of 1 or 2mm first, click "Apply, then click the "Save" icon. Run the sequence again to test if the tip is going far down enough. The same applies for aspiration.

The "Movement Z-offset" specifies the height in which the robotic arm will move above the plate type. **Decreasing the Z-offset** will make the arm move at a position **closer to the plate**. This will save some time during multiple dispensing.

Likewise, the Reagent/Cooler Block Z-offsets can be adjusted here. These can be changed for each sequence depending upon the volumes in the tubes.

| je Pump∣ Tip Boxes Plate Types e Types | Reagent Dro | p Other | | |
|---|--------------------------------|--------------------------------|------------------------------|----------------|
| Plate Type | Aspiration Z-Offset (mm) | Dispensing Z-Offset (mm) | Mo∨ement Z-Offset (mm) | Volume (uL) |
| 96-Well Plate | 10 | 10 | 15 | 350 |
| 384-Well Plate | 7 | 5 | 15 | 120 |
| 12-Column Reservoir | 11 | 10 | 15 | 40000 |
| AmpliSlide | -1 | -0.1 | 8 | 100 |
| 96-Deep Well Plate | 39 | 35 | 15 | 1000 |
| 96-Well PCR Plate | 16 | 12 | 20 | 300 |
| 384-Well PCR Plate | 12 | 10 | 25 | 120 |
| 12-Deep Column Reservoir | 23 | 20 | 15 | 40000 |
| 8-Deep Column Reservoir | 23 | 20 | 15 | 40000 |

Figure 26: VERSAware/Tools/Options/Plate Types Tab

Reagent Drop Settings

The priming volume for the reagent drop can be changed here, along with its dispensing Z-offset. The dispensing Z-offset is the height above the plate type in which the reagent drop



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

will dispense liquid. **Increasing** the "Dispensing Z-offset" will make the reagent drop dispense **further from the surface** of the well.

| Syringe Pump Tip Boxes | Plate Types Reagent Drop Other | |
|--------------------------|--------------------------------|----|
| Reagent Drop Priming | | |
| | Volume (uL) | 10 |
| Reagent Drop Z-Offset | | |
| | Dispensing Z-Offset (mm) | 3 |

Figure 27: VERSAware/Tools/Options/Reagent Drop Tab

Other Settings

The options in this tab allow the user to set different Z-offsets for mixing, air gap, and arm movement from one position to another. These settings, if used properly, reduce the total time of an assay. Arm speed for dispensing and handling waste can be set here. Liquid Level Sensing (LLS) can be activated here for each sequence. Arm initialization options for before and after any sequence can be adjusted here.

| yringe Pump Tip Boxes Plate Ty | pes Heagent Di | | |
|--------------------------------------|--------------------|--------------------------|-------------------------------------|
| Arm Speed after Dispensing [Z-A: | dis] | | |
| | art Speed (step/s) | End Speed (step/s) | Acceleration (step/s ² |
| | 50 | 3000 | 20 |
| Plate Mover | | | |
| | Safe Z-Offset for | Movement: Source> | Target (mm) 100 |
| Mixing | | | |
| | | Mixing Safe Z | -Offset (mm) 10 |
| Air Gap Aspiration | | | |
| | Safe | Z-Offset for Air Gap Asp | piration (mm) 15 |
| Arm Movement from One Position to | Another | | |
| | | Safe Z | -Offset (mm) 90 |
| Handle Waste Liquid Method | | | |
| | Select th | e method 0 Dispensi | ing At Waste 🔄 💌 |
| All Pump Speed Handle Waste L | iquid Method | | |
| Sta | rt Speed (step/s) | End Speed (step/s) | Acceleration (step/s ²) |
| Dispensing At Waste | 10 | 800 | 10 |
| Dispensing At Source | 50 | 300 | 5 |
| Dispensing At Target | 10 | 800 | 10 |
| Liquid Level Sensing | | | |
| 🔽 Open Level Sensing 🛛 🔽 | Regular LLS | Z-Offs | et (mm) 3 |
| 🔲 Initialize Before Sequence | 🔽 Initialize After | Sequence 🔽 S | afe Arm Movement |
| Initialize 4-channel Pump Before | Aspiration | | |
| 🔲 Initialize Z-axis After Tip Engage | ment | | |

Figure 28: VERSAware/Tools/Options/Others Tab



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

Configuration

The Configurations window specifies basic settings/accessories for the instrument. The instrument type is set to "VERSA 1100". The "Shaker" position is set to "12". The "Reagent/Cooler Block" position is set to "12". No Magnetic Stand position is specified as it does not exist in this instrument platform. The "Plate Mover" is set to "Gripper". The "Reagent Drop Pins" is set to "2-5".

Help

The "Help" drop-down menu provides details of the software version type for the VERSAware 1K. For further assistance regarding this software, please contact Aurora's service center.

12.9.4 Application Tabs

Plate Reformatting

This application tab allows user to transfer from one plate type to another. For example, samples from a 96-well plate can be reformatted/transferred to a 32-sample tube block (4x8). The ability to transfer to/from a 6x8 sample tube block exists but will be in a single-channel mode. Other options include dilution with buffer from the reservoir/reagent cooler block, mixing of the diluted target sample, and delays before and after the application run. Advance options include plate replication.

To perform a plate reformatting from a 96-well plate to a 32-sample tube block, follow the steps below:

- 1. Drag and drop the plate/tube block type from the "Plate Library" on the top right side to the "Deck Configuration" on the top left side to their corresponding positions. Also drag the necessary 4-channel pipette tips into the tip positions. (*The 4-channel tip boxes are indicated with a 4 in parentheses*).
- 2. Select the position of the source from the "Source" drop-down menu. (In this case, it will be the 96-well plate).
- 3. Select the position of the target from the "Target" drop-down menu. (In this case, it will be the 32-sample tube block).
- 4. Make sure that the 4-channel pump is selected in the "Single/Four Channel" icon 4. In the source section, select the wells to be transferred. Then in the target section, select the wells for the samples to be transferred into.
- 5. In the target section under the "Sample Volume" field, input the volume of the sample to be transferred.
- 6. Other options are available which can be included in the sequence (mixing, delays, tip disposal after every dispense, plate replication)

PABLARD

Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

7. Remember to save your created sequence by clicking on the "New Sequence" icon. If this is an addition to an existing assay, highlight the assay name of the left screen and then proceed to click the "New Sequence" icon. You would be given the option to enter the new sequence name.

If a new assay has not yet been created, then proceed to click the "New Assay" icon, name the assay, then click "OK". Then, click on the "New Sequence" icon and rename the sequence, then click "OK".

If dilution is required, drag and drop a diluent source (reservoir or cooling block) onto the deck interface, and select it under the "Reservoir Position" field. A "Final Volume" field will appear under the target section which you will then input the final amount for each well.

The plate replication option allows the user to reformat from one source plate to 4 similar target plate types.

AmpliSlide

Plate Reformatting

This application tab allows the user to set up a sequence in which reagents are transferred onto a microscope slide. One slide adaptor can hold up to 4 microscope slides.

NAP/Reagent Addition

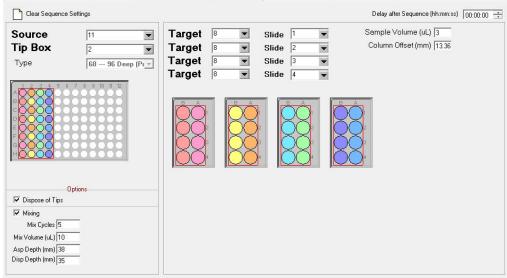


Figure 29: VERSAware/AmpliSlide Tab

To create an AmpliSlide sequence, follow the steps below:

AmpliSlide

1. Drag and drop the AmpliSlide adaptors and any other plate/tube block type from the "Plate Library" on the top right side to the "Deck Configuration" on the top left side to their corresponding positions. Also drag the necessary 4-channel pipette tips into the tip positions. (*The 4-channel tip boxes are indicated with a 4 in parentheses*).



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit **Ouality Control Manual**

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

- 2. Select the position of the source from the "Source" drop-down menu. (In this case, it will be the 96-well plate).
- 3. Select the position of the target from the "Target" drop-down menu. (In this case, it will be the AmpliSlide). The target position and the slide position will need to be selected for each of the four slides on the AmpliSlide adaptor.
- 4. Make sure that the 4-channel pump is selected in the "Single/Four Channel" icon . In the source section, select the wells from which the samples will be transferred. Then in the target section, select the wells for the samples to be transferred into.
- 5. In the target section under the "Target Volume" field, input the volume of the sample to be transferred.
- 6. Other options are available which can be included in the sequence (mixing, delays, tip disposal after every dispense)
- 7. Remember to save your created sequence by clicking on the "New Sequence" icon. If this is an addition to an existing assay, highlight the assay name of the left screen and then proceed to click the "New Sequence" icon. You would be given the option to enter the new sequence name.

If a new assay has not yet been created, then proceed to click the "New Assay" icon, name the assay, then click "OK". Then, click on the "New Sequence" icon and rename the sequence, then click "OK".

The mixing parameters to resuspend the sperm pellet can be changed.

- Mixing Cycles The number of mixing cycles
- Mix Volume The volume aspirated and dispensed during the mixing cycle
- · Asp Depth The depth the pipette tip will go down to do aspirate the sample to mix
- Disp Depth The depth the pipette tip will go down to dispense the mixed sample

(<u>Note</u>: the aspiration and dispense depth in the mixing is separate from the aspiration and dispense depth in the options menu, which specifies the depth to aspirate and dispense the sample for transferring from the plate to slides)

NAP/Reagent Addition

This application tab allows the user to set up the workstation for multi-dispensing reagents from reservoir/96-well plates to target plates. This application tab also allows the user incorporate the shaker and the cooler/heater block. The order of execution can be specified under the "Options" section. Options A, B, or C can be selected in the drop-down menus. To change the order, click the "Reset Order" button.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

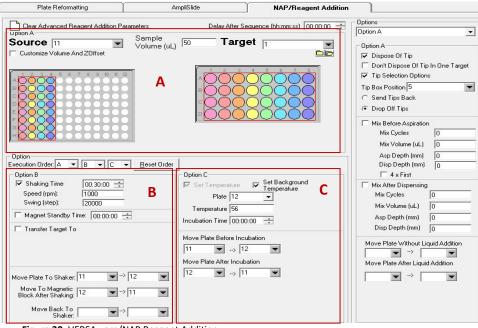
PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

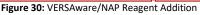
- **Option A** Liquid transfer
- Option B Shaker

Select the shaking time, speed, and swing. A plate can be moved from its original position to the shaker and back by selecting the positions on the bottom of the Option B section.

• **Option C** – Cooler/Heater Block

This option allows for incubation steps. The temperature and incubation time can be set. Make sure that position 12 is selected for the "Plate" field, as this is where the cooler/heater block is located. A plate can be moved from its original position to the cooler/heater block and back by selecting the positions on the bottom of the Option C section.





To create a NAP/Reagent Addition sequence, follow the steps below:

- 1. Drag and drop the plate/tube block type from the "Plate Library" on the top right side to the "Deck Configuration" on the top left side to their corresponding positions. Also drag the necessary 4-channel pipette tips into the tip positions. (*The 4-channel tip boxes are indicated with a 4 in parentheses*).
- 2. Select the position of the source from the "Source" drop-down menu. To use the Reagent Drop, select position 19.
- 3. Select the position of the target from the "Target" drop-down menu.
- 4. Make sure that the 4-channel pump is selected in the "Single/Four Channel" icon . In the source section, select the wells from which the samples will be transferred. Then in the target section, select the wells for the samples to be transferred into.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

- 5. In the "Sample Volume" field, input the volume of the sample to be transferred.
- 6. Other options are available which can be included in the sequence (mixing, delays, tip disposal after every dispense)
- 7. Remember to save your created sequence by clicking on the "New Sequence" icon. If this is an addition to an existing assay, highlight the assay name of the left screen and then proceed to click the "New Sequence" icon. You would be given the option to enter the new sequence name.

12.9.5 Assay/Sequence Screen

The Assay/Sequence screen is located on the left side of the main interface screen. It contains all of the available assays (indicated by a red arrow). Click on the assay to display all of the sequences within the assay (indicated by a blue arrow). To start running an assay, highlight the assay/sequence in this screen, then click the "Start" icon. The assay/sequences can be exported by highlighting it, then clicking "File \rightarrow Export \rightarrow Export Assay/Sequence". Assays can also be imported by clicking "File \rightarrow Import".





12.9.6 Sequence Steps Screen

The Sequence Steps screen is located on the right side of the main interface screen. When an assay/sequence is selected, it will display every single step or action that the instrument will take during that particular assay/sequence. Make sure that the assay/sequence is displayed on the Sequence Steps Screen before starting a run. A particular sequence can be resumed by right click on the sequence, then clicking "Resume the step".



Figure 32: Sequence steps screen



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

12.10 Liquid Level Sensing

12.10.1

Liquid Level Sensing Modes

There are two liquid level sensing (LLS) mode capabilities on this instrument: Regular LLS and Reverse LLS.

- Regular LLS In this LLS mode, the syringe pump will only start aspirating once the final pipette tip in the 4-channel pump detects sufficient liquid. If one or more wells do not have sufficient liquid, an error message will occur, prompting the user to add more liquid. This LLS mode will be turned on throughout all sequence except steps that involve transferring all but "XµL" liquid to a sample tube.
- Reverse LLS In this LLS mode, the syringe pump will start aspirating once the first pipette tip in the 4-channel pump detects liquid. Once liquid is detected, the pump will start to slowly aspirating liquid while moving down until it has reached the height of the volume to be remained in the well. This LLS mode is used for steps that involve transferring the supernatant to a separate tube without disturbing the pellet on the bottom of the well.

To use the LLS functions, go to the VERSAware interface \rightarrow Options *icon* \rightarrow Others *tab*. On the bottom of the screen under the "Liquid Level Sensing" section, select "Open Level Sensing". This turns on the liquid level sensing function for the instrument. If the "Regular LLS" option is selected, the instrument will go to the Regular LLS mode. If the "Regular LLS" option is not selected, the Reverse LLS mode will be used instead.

| Initialize Before Sequence | 🔽 Initialize After Sequence | 🔽 Safe Arm Mo | ovement |
|----------------------------------|-----------------------------|---------------|---------|
| Initialize 4-channel Pump Bef | ore Aspiration | | |
| Initialize Z-axis After Tip Enga | gement | | |

Figure 33: VERSAware/Options/Others tab

12.10.2

Checks & Calibrations (Single Channel)

This section deals with both manual check and calibration check of the liquid level sensor equipped with the VERSAware workstation. You are advised to manually check the sensor's operation before or after calibration check. It is good practice to manually check the sensor's operation periodically to ensure it is in good working condition.

Manual Check for LLS Operational Capability

- 1. Move arm to an empty position anywhere on the deck
- 2. Open the Aurora Station interface and click on the "Level Sensing" tab
- 3. Click "Initialize". A pop-up dialog will appear saying, "initializing in progress"

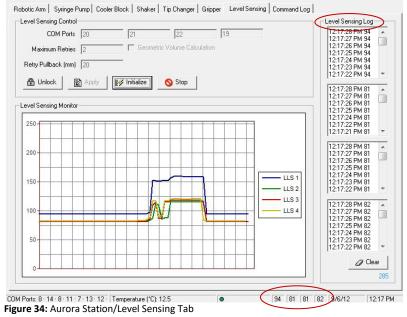


Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

- 4. The "Level Sensing Log" on the right side will show the signal levels following the time at various refreshments rates
- 5. Place your finger slightly below the syringe/tip barrel (without a tip)
- 6. Note the jump of the signal from ~100 to ~200
- 7. Insert a black, conductive tip into the barrel
- Place a tube with ~5-7mL distilled water underneath the tip until the tip is slightly submerged
- 9. Not the signal level changing from ~100 to ~200

If the above are observed when performing steps 1 - 9, then the liquid sensor is working as it should. Proceed to calibrate or check COM ports if you observe no change in the signal level.



LLS Calibration Check for a Current Plate Type

- 1. Open the Aurora Station interface and click on the "Robotic Arm *tab*"
- Select an empty row in the bottom of the table, type in a random position number (100) and a comment (LLS Check – Surface Position). Leave all the other fields empty and highlight the new row entry.

| | Position | Step (X) | Step (Y) | Step (Z) | Comment | |
|---|----------|----------|----------|----------|-----------------------|------|
| - | 14 | 7837 | 2525 | 7737 | 1000 μL Tip Box/Plate | |
| | 15 | 10233 | 2526 | 7756 | 20 μL Tip Box/Plate | |
| - | 16 | 0 | 98 | 7367 | Priming Position | |
| - | 17 | 0 | 1331 | 7132 | Waste Position | |
| - | 18 | 0 | 2568 | 6937 | The Chute | T.A. |
| * | | S - 3 | | 2 5 | | |

Figure 35: Robotic Arm Tab/Position record table

3. Click on the "Settings" *icon* 上 in the top menu, then the "Advanced" *tab*.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

4. On the bottom left corner under "Test Position", select the position to test. To the right under "Plate Type", select the plate type to test.

| osition | 15 - 20 μL Tip Box/Plate | - |
|---------|--------------------------|---|

Figure 36: Aurora Station Settings/Advanced Tab

- 5. Click on the "Plate Types" tab.
- 6. Under the "Symmetrical Plates" section, select the same plate type by highlighting the field.
- 7. In the "Liquid Level Sensing" table to the right, also select the corresponding plate type (refer to the plate type number). There will be several entries of the same plate type with different depth & volume. Select the entry with the lowest volume (not including 0).

| (| Plate Typ | e Description | Columns | Rows | Column Distance | • | Plate Type) | Depth | Volume |
|---|--------------|--|---------|------|-----------------|---|-------------|---------|--------|
| | \checkmark | 96-well Plate | 12 | 8 | 9 | | - | 10.8504 | 0 |
| | 2 | 384-well Plate | 24 | 16 | 4.5 | | 1 | 10.3572 | 20 |
| | 3 | 1536-well Plate | 48 | 32 | 2.25 | | 1 | 9.6174 | 40 |
| | 4 | 12-column Reservoir | 12 | 1 | 9 | | 1 | 8.631 | 60 |
| | 5 | 4-glass Slide Tray (X: 13.2066, Y: 18. | 4 | 1 | 31.0784 | | 1 | 7.6446 | 100 |
| | 6 | 20 μL Tip Box (1-channel) | 12 | 8 | 9 | - | 1 | 5.9184 | 140 |
| | | | | | • | | 1 | 4.6854 | 180 |

- 8. Using a manual pipette, dispense an equal amount of that volume into the top left well (A1) of the testing plate. For example, if 10µL was selected in the table, then there should be 10µL of liquid in the well.
- 9. Manually insert a black, conductive tip into the first barrel.
- 10. Click the "Test" icon II. The robot will move to well A1 position just above the surface of the plate.
- 11. Click on the "Robotic Arm" tab.
- 12. Ensure that the coordinates of the current robotic arm position is present in the "Go X, Go Y, Go Z" fields above the table.

| GoX 0 | GoY | GoZO | Go XYZ |
|---------------|------------------|----------------|--------|
| Figure 38: Au | urora Station/Ro | obotic Arm Tab | |

- 13. Select the new entry that was created (Position 100) by highlighting it, then click the "Save" button. The current coordinates should now be saved onto the entry. This is the plate surface coordinates.
- 14. In the "Arm Control" section on the bottom left, enter the "10" in the "Steps" field and check "No Z Up".

Figure 37: Aurora Station Settings/Plate Type Tab

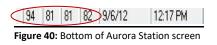
Oakland Police Department Criminalistics Laboratory Forensic Biology Unit **Ouality Control Manual**

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS



Figure 39: Aurora Station/Robotic Arm Tab

- 15. Note the liquid level sensing signal on the bottom right corner of the interface next to the date and time. After making a visual record of this value, attempt to move the tip down with the step arrow controls. Move down until the tip barely touches the surface of the 10µL liquid. You will notice the signal increasing as the tip moves down.
 - The difference in signal detection from the plate surface to the surface of the liquid (10µL) is the "Detection Range" in the "Plate Types" *tab*, "Liquid Level Sensing" section.
 - <u>Detection Range</u>: The lowest point that the robot will move down to detect liquid level. During liquid level sensing, the difference in signal must be greater than the detection range for the instrument to register that there is sufficient liquid. If the difference in signal is less than the detection range, an insufficient liquid message will pop up.
 - <u>Base Offset:</u> A safety mechanism to prevent the instrument from hitting the bottom of the tube/plate. If the instrument reaches the base offset depth, an insufficient liquid message will pop up.
 - This should be similar to what is detected currently. For example, if the signal was 142 at the plate surface and was 154 at the liquid surface, then the difference is 12±1 for the detection range.
 - The value in the "Detection Range" field for the plate type should be equal to or slightly greater than the "Depth" field for Volume 0.



- ^{16.} To check the depth offset at the 10μ L surface, click on an empty row in the "Robotic Arm" *tab.* Make sure that the tip is touching the surface of the liquid.
- 17. The new coordinates should be present in the "Go X, Go Y, Go Z" fields above the table.
- 18. Click on the "Offset" button to view the "Offset Calculator".
- 19. Under the "Height Difference" section in the "Offset" field, the value is the height difference from the plate surface to the liquid level surface. This value should correspond to or be similar to the "Depth" value of the 10µL volume in the "Aurora Station Settings → Plate Types *tab*". If it isn't, change or edit to the updated value.

Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

| Height Difference | S |
|-------------------|----------|
| Z1 (step) | 7132 |
| Z2 (step) | 7801 |
| Difference (mm) | -21.4481 |
| Offset (mm) | 21.4481 |

| | Plate Type | Depth | Volume | |
|---|------------|---------|--------|---|
| • | 1 | 21.4481 | 10 | - |
| | 1 | 10.3572 | 20 | |
| | 1 | 9.6174 | 40 | |
| | 1 | 8.631 | 60 | |
| | 1 | 7.6446 | 100 | |
| | 1 | 5.9184 | 140 | |
| | 1 | 4.6854 | 180 | |

Figure 41: Aurora Station/Robotic Arm Tab/Offset Calculator

Figure 42: Aurora Station Settings/Plate Types Tab

- 20. Next, check the minimum level sensing at "0" depth.
- In the "Robotic Arm" tab, move the tip further down with the step arrow controls until the tip surface barely touches the bottom of the well. The signal value should be similar to the 10μL liquid surface value.
- ^{22.} Repeat steps 16 19 for the 0μ L volume and depth.
- ^{23.} Perform the same steps as above to check for the 20μ L volume and depth. Remember to manually pipette an additional 10μ L of liquid to the same well of the plate.

Check the 30µL volume using the same steps as above and so on. If the checks seem within range of the depths listed in the "Plate Types" *tab*, "Liquid Level Sensing" section, discontinue the calibration check procedures for the rest of the volumes. A rule of thumb would be to perform checks for the volumes used most frequently regarding a specific plate type. Remember to have the right amount of liquid in the well when testing for that volume.

12.10.3

Adjusting the Depth to Match Remaining Volume

For the Reverse LLS method, if the actual remaining volume is less than the targeted remaining volume, the following steps should be taken to correct the difference.

- Check the teaching position for the source plate (Refer to Section 3.1.1.1 Calibrate a Position)
- 2. Check the plate type offsets (Refer to Section 3.1.1.3 Adjust Plate Type Offset)
- 3. If the teaching position and plate type offsets are correct and the actual remaining volume is still less than the targeted remaining volume, the depth in the "Aurora Station Settings Liquid Level Sensing" can be adjusted.
 - In the Aurora Station interface, click on the "Settings" *icon*, then the "Plate Types" *tab*.
 - On the right under the "Liquid Level Sensing" section, find the plate type of the source plate.
 - Adjust the depth of the corresponding volume. The value entered in for "Depth" is how far below the surface of the plate that the pipette will go down to to leave the

Oakland Police Department Criminalistics Laboratory Forensic Biology Unit **Ouality Control Manual**

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

corresponding volume of liquid. To leave more volume, decrease the value for "Depth" and vice versa. If the targeted volume in the sequence does not correspond to any volume in the table, the depth will be calculated via a linear relation to the volume.

 \cdot When finished, click on another cell to switch records, click "Apply", then "OK".

| | Plate Type | Depth | Volume | |
|----|------------|---------|--------|---|
| • | 1 | 10.8504 | 0 | = |
| Π. | 1 | 10.3572 | 20 | |
| | 1 | 9.6174 | 40 | |
| | 1 | 8.631 | 60 | |
| | 1 | 7.6446 | 100 | |
| | 1 | 5.9184 | 140 | |
| | 1 | 4.6854 | 180 | |

Figure 43: Aurora Station Settings/Plate Types Tab

12.11 Setting Up A Run

The VERSAware interface allows the option to set up runs with various options and tasks. Only the sequences that will be used for the automated differential digestion protocol will be described. To set up an assay/sequence, go to the VERSAware interface and click on one of the "Application Tabs". After setting up a sequence by following the steps below, click the "Add Sequence" button. If this is the very first sequence in an assay, the software will prompt for you to name the assay, then the sequence. To add more sequences to the same assay, make sure the assay is selected prior to clicking the "Add Sequence" button. If any changes/updates are made after adding the sequence, make sure to click the "Save Current Sequence" icon to save those changes.

The following are instructions and parameters on how to set-up the various sequences used:

| APPLICATION TAB – NAP/REAGENT ADDITION | | | | | | | | |
|--|---------|--|--|--|--|--|--|--|
| Option B | | | | | | | | |
| Shaking Time (min) | 30 | | | | | | | |
| Shaking Speed | 1,000 | | | | | | | |
| Shaking Swing | 20,000 | | | | | | | |
| Move Plate to Shaker | 11 → 12 | | | | | | | |
| Delay After Sequence | 9 hr | | | | | | | |
| Execution Order | В | | | | | | | |

Shake



-

Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

Transfer Aqueous Extract to Tubes (1-32) & Set Background Temp to 56°C

| APPLICATION TAB – NAP/REAGENT ADDITION | | | | | | | | |
|--|-----|--|--|--|--|--|--|--|
| Option A | | | | | | | | |
| Source | 11 | | | | | | | |
| Target | 13 | | | | | | | |
| Remaining Vol. (µL) | 50 | | | | | | | |
| Dispose of Tip | Yes | | | | | | | |
| Tip Selection Option | 5 | | | | | | | |
| Drop Off Tips | Yes | | | | | | | |
| Execution Order A | | | | | | | | |

• Select wells A1 – H4 on the source plate and wells A1 – D8 on the target plate

| OPTIONS TAB | | | | | | | | | | | |
|--------------|-----|-------------|------------|------------|--|-------------|-----|--|--|--|--|
| Syringe Pum | р | Plate Types | Aspiration | Dispensing | | Other | | | | | |
| (4 x 1000µL) | | | Offset | Offset | | | | | | | |
| Air Gap (µL) | 250 | 96 Deep | 36 | 8 | | Open Level | Yes | | | | |
| | | (Promega) | | | | Sensing | | | | | |
| | | 32 Screwtop | 10 | 8 | | Regular LLS | No | | | | |
| | | Tube Holder | | | | | | | | | |

- Transfer Aqueous Extract to Tubes (33-64)
 - Same as Transfer Aqueous to Tubes (1-32), except select position #14 as target.
 - Select wells A5 H8 on the source plate and wells A1 D8 on the target plate
- Transfer Aqueous Extract to Tubes (65-96)
 - Same as Transfer Aqueous to Tubes (1-32), except select position #15 as target and add Options B and C.
 - Select wells A9 H12 on the source plate and wells A1 D8 on the target plate

| | APPLICATION TAB – NAP/REAGENT ADDITION | | | | | | | | | | |
|-------------------------|--|--|---|---------|--|------------------------------------|-----|--|--|--|--|
| Option A | | | Option B | | | Option C | | | | | |
| Source | 11 | | Shaking Time (min) | 2 | | Set Temperature (°C) | Yes | | | | |
| Target | 13 | | Shaking Speed | 1,000 | | Set Background Temperature (°C) | Yes | | | | |
| Remaining Vol. (μL) | 50 | | Shaking Swing | 20,000 | | Plate | 12 | | | | |
| Dispose of Tip | Yes | | Move Plate to Shaker | 11 → 12 | | Temperature | 56 | | | | |
| Tip Selection Option | 5 | | Move to Magnetic Block After Shaking | 12 → 11 | | | | | | | |
| Drop Off Tips | Yes | | | | | | | | | | |
| | Execution Order A, B, C | | | | | | | | | | |



-

Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

Transfer to Slides (1-32)

| APPLICATION TAB – AMPLISLIDE | | | | | | | | | |
|------------------------------|-------|--|-----------------|-----|--|--|--|--|--|
| Source | 11 | | Mixing | Yes | | | | | |
| Тір Вох | 2 | | Mix Cycles | 3 | | | | | |
| Target | 8 | | Mix Volume(μL) | 20 | | | | | |
| Slides | 1 - 4 | | Asp Depth (mm) | 38 | | | | | |
| Sample Volume (µL) | 5 | | Disp Depth (mm) | 30 | | | | | |
| Dispose of Tips | Yes | | | | | | | | |

• Select wells A1 – H4 on the source plate and wells A1 – B4 for all four slides.

| Options Tab | | | | | | | | | | |
|------------------|----|--|----------------------|----------------------|----------------------|--|--------------------------|----|--|--|
| Syringe Pump | | | Plate Types | Aspiration Offset | Dispensing Offset | | Other | | | |
| Air Gap (μL) | 20 | | 96 Deep (Promega) | 38 | 8 | | Open Level Sensing | No | | |
| Mix Air Gap (μL) | 15 | | AmpliSlide | -5 | -5 | | Regular LLS | No | | |

Transfer to Slides (33-64)

- Same as Transfer to Slides (1-32), except select position #9 as target
- Select wells A5 H8 on the source plate and wells A1 B4 for all four slides

Transfer to Slides (65-96)

- Same as Transfer to Slides (1-32), except select position #10 as target
- Select wells A9 H12 on the source plate and wells A1 B4 for all four slides
- · Add Delay After Sequence: 9 hr

Add Tween

| APPLICATION TAB - NAP/REAGENT ADDITION | | | | | | | |
|--|-----|--|--|--|--|--|--|
| Option A | | | | | | | |
| Source | 19 | | | | | | |
| Target | 12 | | | | | | |
| Sample Volume (µL) | 510 | | | | | | |
| Execution Order | A | | | | | | |
| | | | | | | | |

- Make sure single channel mode 👖 is selected
- Select valve #2 on the source section and select samples wells A1 H12 on target plate



.

•

Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

Add Pro K & Incubate at 56°C for 30 Min

| APPLICATION TAB – NAP/REAGENT ADDITION | | | | | | | | | |
|--|-------|-----|----------------------|---------|--|--|--|--|--|
| Option A | | | Option B | | | | | | |
| Source | 1 | | Shaking Time (min) | 30 | | | | | |
| Target | 11 | | Shaking Speed | 1,000 | | | | | |
| Sample Volume 10 | | | Shaking Swing | 20,000 | | | | | |
| (μL) | | | | | | | | | |
| Dispose of Tip | Yes | | Move Plate to Shaker | 11 → 12 | | | | | |
| Tip Selection | 2 | | Move to Magnetic | 12 → 11 | | | | | |
| Option | | | Block After Shaking | | | | | | |
| Drop Off Tips | Yes | | | | | | | | |
| Delay After | 9 hr | | | | | | | | |
| Sequence | | | | | | | | | |
| | Execu | tio | n Order A, B | | | | | | |

• Select wells A8 – D8 on the source plate and wells A1 – H12 on the target plat

| OPTIONS TAB | | | | | | | | | | |
|--------------|----|--|------------------|------------|------------|--|-------------|----|--|--|
| Syringe Pump | | | Plate Types | Aspiration | Dispensing | | Other | | | |
| (4 x 1000µL) | | | | Offset | Offset | | | | | |
| Air Gap (μL) | 30 | | 96 Deep | 36 | 28 | | Open Level | No | | |
| | | | (Promega) | | | | Sensing | | | |
| | | | 32 Screwtop Tube | 43 | 8 | | Regular LLS | No | | |
| | | | Holder | | | | | | | |

Transfer EC Fractions to Tubes (1-32)

| APPLICATION TAB – NAP/REAGENT | | | | | | | | |
|-------------------------------|-----|--|--|--|--|--|--|--|
| Addition | | | | | | | | |
| Option A | | | | | | | | |
| Source | 11 | | | | | | | |
| Target | 13 | | | | | | | |
| Remaining Vol. | 50 | | | | | | | |
| (μL) | | | | | | | | |
| Dispose of Tip | Yes | | | | | | | |
| Tip Selection | 5 | | | | | | | |
| Option | | | | | | | | |
| Drop Off Tips | Yes | | | | | | | |
| Execution Order A | | | | | | | | |



.

Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

Select wells A1 – H4 on the source plate and wells A1 – D8 on the target plate

| OPTIONS TAB | | | | | | | | | | | |
|--------------|-----|-------------|------------|------------|--|-------------|-----|--|--|--|--|
| Syringe Pump | | Plate Types | Aspiration | Dispensing | | Other | | | | | |
| | - | | Offset | Offset | | | | | | | |
| Air Gap (µL) | 250 | 96 Deep | 36 | 8 | | Open Level | Yes | | | | |
| | | (Promega) | | | | Sensing | | | | | |
| | | 32 Screwtop | 10 | 8 | | Regular LLS | No | | | | |
| | | Tube Holder | | | | | | | | | |

Transfer EC Fractions to Tubes (33-64)

- · Same as Transfer EC Fractions to Tubes (1-32), except select position #14 as target
- Select wells A5 H8 on the source plate and wells A1 D8 on the target plate

Transfer EC Fractions to Tubes (65-96)

- Same as Transfer EC Fractions to Tubes (1-32), except select position #15 as target
- Select wells A9 H12 on the source plate and wells A1 D8 on the target plate

• Add MTL Buffer (1-32)

| Application Tab – NAP/Reagent Addition | | | | | | |
|---|-----|--|--|--|--|--|
| Option A | | | | | | |
| Source | 19 | | | | | |
| Target | 13 | | | | | |
| Sample | 400 | | | | | |
| Volume (μL) | | | | | | |
| Execution Order A | | | | | | |

- Make sure single channel mode I is selected
- Select valve #3 on the source section and select samples wells A1 D8 on target plate

Add MTL Buffer (33-64)

· Same as Add MTL Buffer (1-32), except select position #14 for target

03-DEC-12

04-JAN-15

23-JUN-14



.

Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

Add MTL Buffer (65-96)

Same as Add MTL Buffer (1-32), except select position #15 for target and add Option B.

| APPLICATION TAB – NAP/REAGENT ADDITION | | | | | | |
|--|-------|-----|----------------------|---------------------|--|--|
| Option | n A | | Option B | | | |
| Source | 19 | | Shaking Time (min) | 2 | | |
| Target | 13 | | Shaking Speed | 1,000 | | |
| Sample | 400 | | Shaking Swing | 20,000 | | |
| Volume (µL) | | | | | | |
| | | | Move Plate to Shaker | $11 \rightarrow 12$ | | |
| | | | Move to Magnetic | 12 → 11 | | |
| | | | Block After Shaking | | | |
| | Execu | tio | n Order A, B | | | |

Transfer to Slides (1-32)

| APPLICATION TAB – AMPLISLIDE | | | | | | | |
|------------------------------|-------|--|-----------------|-----|--|--|--|
| Source | 11 | | Mixing | Yes | | | |
| Тір Вох | 2 | | Mix Cycles | 3 | | | |
| Target | 8 | | Mix Volume(µL) | 20 | | | |
| Slides | 1 - 4 | | Asp Depth (mm) | 38 | | | |
| Sample Volume (µL) | 5 | | Disp Depth (mm) | 30 | | | |
| Dispose of Tips | Yes | | | | | | |

Select wells A1 – H4 on the source plate and wells A1 – B4 for all four slides.

| Options Tab | | | | | | | | |
|--------------|----|--|-------------|------------|------------|--|-------------|----|
| Syringe Pump | | | Plate Types | Aspiration | Dispensing | | Other | |
| | | | | Offset | Offset | | | |
| Air Gap (μL) | 20 | | 96 Deep | 38 | 8 | | Open Level | No |
| | | | (Promega) | | | | Sensing | |
| Mix Air Gap | 15 | | AmpliSlide | -5 | -5 | | Regular LLS | No |

Transfer to Slides (33-64)

- Same as Transfer to Slides (1-32), except select position #9 as target
- Select wells A5 H8 on the source plate and wells A1 B4 for all four slides

Transfer to Slides (65-96)

- Same as Transfer to Slides (1-32), except select position #10 as target
- Select wells A9 H12 on the source plate and wells A1 B4 for all four slides
- · Add Delay After Sequence: 9 hr



.

Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

Add Tween

| APPLICATION TAB – NAP/REAGENT ADDITION | | | | | | | |
|--|--|--|--|--|--|--|--|
| Option A | | | | | | | |
| 19 | | | | | | | |
| 12 | | | | | | | |
| 290 | | | | | | | |
| | | | | | | | |
| А | | | | | | | |
| | | | | | | | |

- Make sure single channel mode I is selected
- Select valve #2 on the source section and select samples wells A1 H12 on target plate

Add Mg/Ca Salts

| APPLICATION TAB – NAP/REAGENT ADDITION | | | | | | | |
|--|-----------|--|--|--|--|--|--|
| Option A | | | | | | | |
| Source | 1 | | | | | | |
| Target | 11 | | | | | | |
| Sample Volume | 25 | | | | | | |
| (μL) | | | | | | | |
| Dispose of Tip | Yes | | | | | | |
| Tip Selection | 2 | | | | | | |
| Option | | | | | | | |
| Drop Off Tips | Yes | | | | | | |
| Executio | n Order A | | | | | | |

- Select wells A7 D7 on the source plate and wells A1 H12 on the target plate
- Select the option "Prime syringe pump before running sequence".

| OPTIONS TAB | | | | | | | | |
|------------------------------|-----|--|----------------------------|----------------------|----------------------|--|-----------------------|----|
| Syringe Pump (4 x 1000µL) | | | Plate Types | Aspiration Offset | Dispensing Offset | | Other | |
| Air Gap (μL) | 20 | | 96 Deep (Promega) | 36 | 38 | | Open Level Sensing | No |
| Priming Cycles | 8 | | 32 Screwtop Tube Holder | 43 | 8 | | Regular LLS | No |
| Back Aspiration (µL) | 100 | | | | | | | |



.

Oakland Police Department Criminalistics Laboratory Forensic Biology Unit **Quality Control Manual**

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

Add DNase & Incubate at 56°C for 15 min

| APPLICATION TAB – NAP/REAGENT ADDITION | | | | | | | |
|--|--------|-----|-------------------|---------|--|--|--|
| Option A | | | Option C | | | | |
| Source | 1 | | Set Temperature | Yes | | | |
| Target | 11 | | Set Background | No | | | |
| | | | Temperature | | | | |
| Sample Volume | 15 | | Plate | 12 | | | |
| (μL) | | | | | | | |
| Dispose of Tip | Yes | | Temperature (°C) | 56 | | | |
| Tip Selection | 2 | | Incubation Time | 15 | | | |
| Option | | | (min) | | | | |
| Drop Off Tips | Yes | | Move Plate Before | 11 → 12 | | | |
| | | | Incubation | | | | |
| Mix After | Yes | | Move Plate After | 12 → 11 | | | |
| Dispensing | | | Incubation | | | | |
| Mix Cycle | 1 | | | | | | |
| Mix Volume (µL) | 30 | | | | | | |
| Asp Depth (mm) | 36 | | | | | | |
| Disp Depth (mm) | 15 | | | | | | |
| | Execut | tio | n Order: A, C | | | | |

• Select wells A6 – D6 on the source plate and wells A1 – H12 on the target plate

| Options Tab | | | | | | | | |
|----------------|----|-------------|------------|------------|-------------|----|--|--|
| Syringe Pump | | Plate Types | Aspiration | Dispensing | Other | | | |
| (4 x 1000μL) | | | Offset | Offset | | | | |
| Air Gap (μL) | 30 | 96 Deep | 36 | 38 | Open Level | No | | |
| | | (Promega) | | | Sensing | | | |
| Mixing Air Gap | 15 | 32 Screwtop | 43 | 8 | Regular LLS | No | | |
| (μL) | | Tube Holder | | | | | | |



.

Oakland Police Department Criminalistics Laboratory Forensic Biology Unit **Quality Control Manual**

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

Add EDTA & delay for 10 min

| Application Tab – NAP/Reagent Addition | | | | | | | |
|--|-----------|----------------------|-----|--|--|--|--|
| Option A | | | | | | | |
| Source | 1 | Mix After Dispensing | Yes | | | | |
| Target | 11 | Mix Cycle | 2 | | | | |
| Sample Volume | 20 | Mix Volume (μL) | 30 | | | | |
| (μL) | | | | | | | |
| Dispose of Tip | Yes | Asp Depth (mm) | 36 | | | | |
| Tip Selection | 2 | Disp Depth (mm) | 15 | | | | |
| Option | | | | | | | |
| Drop Off Tips | Yes | | | | | | |
| Delay After | 10 min | | | | | | |
| Sequence | | | | | | | |
| | Execution | Order: A | | | | | |

• Select wells A5 – D5 on the source plate and wells A1 – H12 on the target plate

| OPTIONS TAB | | | | | | | | |
|--------------|-------|--|------------|------------|--------|-------|-------------|----|
| Syringe | Plate | | Aspiration | Dispensing | | Other | | |
| Pump | | | Types | Offset | Offset | | | |
| (4 x 1000µL) | | | | | | | | |
| Air Gap (μL) | 20 | | 96 Deep | 36 | 38 | | Open Level | No |
| | | | (Promega) | | | | Sensing | |
| Mixing Air | 15 | | 32 | 43 | 8 | | Regular LLS | No |
| Gap (µL) | | | Screwtop | | | | | |
| | | | Tube | | | | | |
| | | | Holder | | | | | |

Add Pro K

.

| APPLICATION TAB – NAP/REAGENT ADDITION | | | | | | |
|--|-------|--|--|--|--|--|
| Option A | | | | | | |
| Source | 1 | | | | | |
| Target | 11 | | | | | |
| Sample Volume (µL) | 10 | | | | | |
| Dispose of Tip | Yes | | | | | |
| Tip Selection Option | 2 | | | | | |
| Drop Off Tips | Yes | | | | | |
| Execution Ord | er: A | | | | | |

• Select wells A8 – D8 on the source plate and wells A1 – H12 on the target plate



.

Oakland Police Department Criminalistics Laboratory Forensic Biology Unit **Quality Control Manual**

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

| Options Tab | | | | | | | |
|------------------------------|----|--|----------------------------|----------------------|----------------------|-----------------------|----|
| Syringe Pump (4 x 1000µL) | | | Plate Types | Aspiration Offset | Dispensing Offset | Other | |
| Air Gap (μL) | 30 | | 96 Deep (Promega) | 36 | 38 | Open Level Sensing | No |
| | | | 32 Screwtop Tube Holder | 43 | 8 | Regular LLS | No |

Add DTT & Incubate at 56°C for 15 min

| Applicat | APPLICATION TAB – NAP/REAGENT ADDITION | | | | |
|-----------------------|--|--|-------------------|---------------------|--|
| Option A | | | Option C | | |
| Source | 1 | | Set Temperature | Yes | |
| Target | 11 | | Set Background | No | |
| | | | Temperature | | |
| Sample Volume | 20 | | Plate | 12 | |
| (μL) | | | | | |
| Dispose of Tip | Yes | | Temperature (°C) | 56 | |
| Tip Selection | 2 | | Incubation Time | 15 | |
| Option | | | (min) | | |
| Drop Off Tips | Yes | | Move Plate Before | $11 \rightarrow 12$ | |
| | | | Incubation | | |
| | | | Move Plate After | $12 \rightarrow 11$ | |
| | | | Incubation | | |
| Execution Order: A, C | | | | | |

• Select wells A4 – D4 on the source plate and wells A1 – H12 on the target plate

| | | C | PTIONS TAB | | | |
|------------------------------|----|----------------------------|----------------------|----------------------|----------------------|------|
| Syringe Pump (4 x 1000µL) | | Plate Types | Aspiration Offset | Dispensing Offset | Other | |
| Air Gap (µL) | 20 | 96 Deep (Promega) | 36 | 38 | Open Leve Sensing | l No |
| | | 32 Screwtop Tube Holder | 43 | 8 | Regular LLS | S No |



.

Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

Transfer SP Fraction to Tubes (1-32)

| - | | | |
|-------------------|--|--|--|
| 6 | | | |
| 0 | | | |
| S | | | |
| | | | |
| | | | |
| S | | | |
| Execution Order A | | | |
| | | | |

• Select wells A1 – H4 on the source plate and wells A1 – D8 on the target plate

| Ορτιονς Ταβ | | | | | | |
|--------------|-----|-------------|----------------------|----------------------|-------------|----|
| Syringe Pum | р | Plate Types | Aspiration Offset | Dispensing Offset | Other | |
| Air Gap (µL) | 200 | 96 Deep | 38 | 35 | Open Level | No |
| | | (Promega) | | | Sensing | |
| Delay After | 4 | 32 Screwtop | 10 | 8 | Regular LLS | No |
| Aspiration | | Tube Holder | | | | |

Transfer SP Fractions to Tubes (33-64)

- Same as Transfer SP Fractions to Tubes (1-32), except select position #14 as target
- Select wells A5 H8 on the source plate and wells A1 D8 on the target plate

Transfer SP Fractions to Tubes (65-96)

- Same as Transfer SP Fractions to Tubes (1-32), except select position #15 as target
- Select wells A9 H12 on the source plate and wells A1 D8 on the target plate



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit **Quality Control Manual**

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

Add MTL Buffer (1-32)

| APPLICATION TAB – NAP/REAGENT | | | | |
|-------------------------------|-------|--|--|--|
| Addition | | | | |
| Option A | | | | |
| Source | 19 | | | |
| Target | 13 | | | |
| Sample Volume | 400 | | | |
| (μL) | | | | |
| Execution Order A | | | | |
| | 2/- 6 | | | |

- Make sure single channel mode ¹/₁ is selected
- Select valve #3 on the source section and select samples wells A1 D8 on target plate

Add MTL Buffer (33-64)

- · Same as Add MTL Buffer (1-32), except select position #14 for target
- Add MTL Buffer (65-96)
 - · Same as Add MTL Buffer (1-32), except select position #15 for target
 - Set background temperature to 15°C.
 - Set Execution order to be "A, C".

12.12 Running A Protocol

Start-up

Start the VERSAware software by double-clicking on the VERSAware 1100 icon on the desktop. Turn on the robot by turning clockwise the red button on the button right corner of the robot.



Initializing

Each component of the instrument (syringe pump, robotic arm, shaker, etc.) must be

initialized before it can function. The "Home" *icon* will initialize all devices, drop off any tips that are engaged, and return the robotic arm to its safe position. It is a good practice to "home" the robot once it is turned on.

Syringe Pump Priming

The syringe pump must be primed before each run. This will remove any air leaks or air bubbles in the tubing system, which may cause inaccurate pipetting volumes. To do so, click



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

on the "Syringe Pump" *icon* [], then the "4x1000µL" *tab*. Check the "Priming" option, and type in "8" and "100" for the "Priming Cycles" and "Back Aspiration Volume", respectively. Click the "Prime" button to start.

| 🗖 Primin | g | | |
|-----------|-------------------|-----|----|
| | Priming Cycles | 10 | -÷ |
| Back Aspi | ation Volume (uL) | 100 | _ |

Figure 44: Syringe Pump Priming

Reagent Drop Priming

At the end of a run, the reagent drop tubings will be filled with water to prevent crystallization within the tubings. Prior to starting a run, these tubings must be filled with the appropriate buffers for the protocol. To distinguish between water and buffers, the water in the tubings will first be flushed out with air, then filled with buffer.

Place a container under position 6 to catch the liquid. Remove the two red bottle caps from the deionized water bottles and place them in empty bottles. Click on the "Syringe Pump"

icon I. In the "Reagent Drop Priming" section, type in "2000" for the "Priming Volume". Click on the "Reagent" button to start priming. This will remove any water in the tubes and fill it with air. After the run is finished, place each of the caps in their corresponding reagent bottle (Bottle 2: Tween 80 ; Bottle 3: MTL Buffer). In the "Reagent Drop Priming" section, type in "4000" for the "Priming Volume". Click on the "Reagent" button to start. The first 1000 – 2000µL will be just air while the system is beginning to fill itself with the reagents. When liquid is dispensed from the reagent drop valves, this indicates that the tubes are now filled with the reagent and is ready for use.

| Reagent Drop Priming — | | |
|------------------------|-----------------|---------|
| Pri | ming Volume (uL |) 2000 |
| | | |
| (P) Reagent | 1 Prime | 🗙 Close |
| Treagent | AP . INTO 1 | < CI030 |

Figure 45: Reagent Drop Priming

Starting an assay/sequence

In the VERSAware interface on the left side of the screen, click on the assay/sequence to run. To run an entire assay, click on the assay. To run a specific sequence, click on the sequence. Make sure that the assay/sequence is displayed in the "Sequence Steps Screen" on the very right.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit **Quality Control Manual**

PART 2. GENERAL APPROACH TO QUALITY CONTROL **OF EQUIPMENT USED IN DNA ANALYSIS**

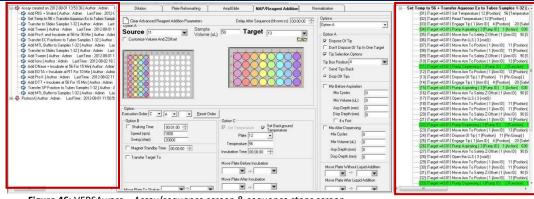


Figure 46: VERSAware – Assay/sequence screen & sequence steps screen

Resuming from the middle of an assay/sequence

An assay/sequence can be resumed from any step. Prior to resuming a step, "home" ²² the robot first to ensure that the robotic arm is in a safe position. In the "Sequence Steps Screen", right-click on the step to resume from, and click "Resume the step". If this is a pipetting step, resume from its previous "Engage Tip" step.

Emergency stop button

The red button on the bottom right corner of the instrument can be pushed anytime to completely stop the instrument. This should be used when it is observed that the robotic arm might crash into something. After pushing the emergency stop button, the robot will be turned off. The software must also then be turned off, restarted, then the robot turned on again so that the software can be synced with the robot.



End of run priming

Prior to turning off the instrument at the end of the run, prime the reagent drop valves with water. The reagents that are used, especially the MTL Buffer, have salts in the solution that might crystallize and plug up the tubings. To prevent this, the reagents in the reagent drop valves must be flushed out after every run and filled with water instead. To do so, remove the caps from the reagent bottles and place them into the deionized water bottles. Click on the "Syringe Pump" icon. In the "Reagent Drop Priming" section, type "4000" for the "Priming Volume". Click the "Reagent" button to start.

12.13 UV/HEPA Bio-Containment Hood

The bio-containment hood is designed to provide sterile air quality for the assay sequence workspace by utilizing a high efficiency particulate air filter (HEPA). By performing filtration of the air within the workspace, the hood prevents contamination of the agents used during any



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

given sequence. In addition, cross-contamination by harmful particulate or microbes in the air surrounding the workspace is reduced with the built in UV lamp.

- UV Switch Turns the UV light source on and off. Used to de-contaminate the deck.
- **Fan Switch** Turns on and off the containment hood's fan to draw external air inward. With the fan running, air is filtered as it enters the hood.
- Light Switch Turns on and off the containment hood's fluorescent light, which allows for a brighter workspace environment.
- UV Timer Control Along with the UV switch being turned on, the UV Timer Control can be used to set the duration of the UV light source. It can be set for different time intervals (e.g. 5, 15, and 30 minutes)

12.14 Maintenance

This section will discuss how to provide maintenance for tubing, how to handle system fluid and waste bottles, and how to replace syringes.

12.14.1 General Guidelines

It is important to follow the general guidelines and instructions describe in this manual in order to maintain the proper function of the VERSA Workstation.

Use only clean vessels. Do not leave vessels exposed to dust and dirt overnight. It is recommended to use sterile pipetting tips with filter barrier. Run additional priming sequence after the PCR application sequence is finished to avoid air bubble from forming. Use only distilled water or deionized water as the system fluid. It is recommended to use degassed system fluid to avoid excess air bubbles in the system.

12.14.2 Tubing

All tubes should be tightly connected to adaptors and should not be twisted or bent. All tubing is made of durable Teflon which cannot be easily ruptured or bent. When aspirating or dispensing viscous liquids, please prime the instrument more frequently to remove build-up in the tubes and lines.

12.14.3 System Fluid

System fluid and waste liquid bottles are pressurized. Therefore the caps should be tightly sealed to avoid accidental pressure/vacuum release. All tubing should be inserted into the bottles as described in the "Hardware Installation and Set-up" section of this manual.

Only distilled or deionized water should be used as the system fluid. It is highly recommended to use degassed system fluid to avoid excess air bubbles in the system.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

It is very important that the waste liquid bottle does not get full. Otherwise, the waste liquid may fill the vacuum tube and cause damage to the vacuum pump.

12.14.4 Internal Calibration Checks

Position and volume calibration checks should be performed semi-annually.

Instructions on how to perform position calibration checks are found in Section 3.1.1 – Position Calibration Check. Each deck position, except position #5 and 6, should be tested/calibrated to determine if slight offsets may have occurred over the time. Accurate position calibrations will provide increased pipetting accuracy.

Instructions on how to perform volume calibration checks on the syringe pump and reagent drop are found in Section 3.2.1 – Syringe Pump Calibration Check and Section 4.1 – Reagent Drop Calibration Check. Instructions on how to perform volume calibration checks for liquid level sensing are found in Section 6.2.2 – LLS Calibration check for a current plate type. The volumes that are frequently used in the protocols should be tested by instructing the robot to manually dispense liquid. If the actual volume dispensed is inaccurate, additional steps should be taken to created/adjust the calibration table. However, if the volume dispensed is accurate, no further calibration is needed.

12.14.5 Cleaning

The instrument deck surface should be routinely cleaned with water and ethanol to remove any contaminants. The plate adaptor blocks should be cleaned at least quarterly with soap water and ethanol.

12.15 Trouble Shooting

This section will discuss the following potential problems users might encounter with the VERSA 1100 workstation.

| VERSA 1100 Tro | VERSA 1100 Troubleshooting | | | |
|----------------|---|--|--|--|
| Problem 1 | Power is off | | | |
| Problem 2 | No communication with the VERS | | | |
| Problem 3 | Aurora Arm does not respond to operator's command | | | |
| Problem 4 | Aurora Arm does not move to correct positions | | | |
| Problem 5 | Aurora Arm stops during application sequence run | | | |
| Problem 6 | Syringe pumps do not respond to operator's command | | | |
| Problem 7 | Syringe pumps do not aspirate or dispense any reagent or buffer | | | |
| Problem 8 | Syringe pumps do not aspirate or dispense accurate volume | | | |
| Problem 9 | VERSA producing unusual noise | | | |
| Problem 10 | Pipetting tips are damaged or bent | | | |
| Problem 11 | Excessive air bubbles are introduced into the system tubing | | | |



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

| Problem 12 | Pressure and vacuum pumps are not working |
|------------|---|
| Problem 13 | Syringes are leaking or broken |
| Problem 14 | While running the sequence, a hanging drop is formed outside of the tip |
| Problem 15 | The pipetting tip does not aspirate the master mix in the reagent block |
| Problem 16 | Pipetting tips do not aspirate or dispense accurate volume |
| Problem 17 | Pipetting tips do not dispense small volumes (1-5µL) |
| Problem 18 | VERSA stops working suddenly or operation hangs midway |

The VERSAware software provides advance error messaging and a detailed log for both Aurora Arm and Syringe Pumps. Most common problems and solutions are discussed below.

1. Problem – Power is off

Solution – Please check if power cable is properly connected to the VERSA and AC outlet. Make sure that the power switch is on.

2. Problem – No communication with the VERSA

Solution – Please ensure that USB cable is tightly connected to the VERSA and computer USB port. Please check correct COMP port configurations in MS Windows XP/2000.

Start \rightarrow Settings \rightarrow Control Panel \rightarrow System \rightarrow Hardware \rightarrow Device Manager \rightarrow Ports Device status of COM ports should read: "This device is working properly". All COM port numbers not exceed 16.

3. Problem – Aurora Arm does not respond to operator's command

Solution – Please ensure that the arm is initialized in Aurora Station software. Make sure that the COM port settings are correct in the Aurora Station software. If the problem still remains, try to shut down and restart the VERSA and initialize the robotic arm once again.

- Problem Aurora Arm does not move to correct positions Solution – Please refer to Section 3.1.1 – Position Calibration Check to adjust or repeat the teaching procedure for all positions. If the problem still remains, try to initialize the robotic arm again.
- 5. Problem Aurora Arm stops during application sequence run

Solution – Please refer to the Section 3.9 – Aurora Station Settings to decrease robotic arm speed and acceleration settings for every axis (X, Y, and Z). It is recommended to gradually reduce the end speed by 500 or 1000 steps/sec. Acceleration should be reduced to 1 or 3 steps/sec². The user can start the sequence from the step it last stopped at by left clicking the step and clicking "Resume this step".



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

- Problem Syringe pumps do not respond to operator's command
 Solution Please ensure that both syringe pumps are initialized. Make sure that the COM port settings are correct. If the problem still remains, try to shut down and restart the VERSA 1K software and initialize the syringe pump one more time.
- Problem Syringe pumps do not aspirate or dispense any reagent or buffer
 Solution Please visually confirm that the plunger of the syringe pump is moving down for the aspiration function or moving up for the dispensing function. If the plunger is moving, consult Section 1 – Hardware Installation and Set-up to check for proper syringe pump tubing connections. Ensure there is no air bubbles observed in the syringe or tubes.
- 8. Problem Syringe pumps do not aspirate or dispense accurate volume Solution – Check that the priming bottle is tightly sealed. Usually if the bottle is over-turned, no liquid should be leaking from the bottle cap. If it is, the seal is open and the user should open and re-align the rubber seal along with the screw cap before closing again. Please also refer to Section 3.2.1 – Syringe Pump Calibration Check section of this manual and perform new calibration check procedures if necessary.
- 9. Problem VERSA producing unusual noise

Solution – This is normal. During the priming sequence, pressure and vacuum pumps start working and produce unusual noises. The purpose of the pressure pump is to remove air bubbles from the system's syringes and tubing. The vacuum pump is used to remove waste liquid from the priming station.

- Problem Pipetting tips are damaged or bent
 Solution In case of accidental tip damage, press the "Home" icon in the VERSAware software to initialize the robotic and disengage the damaged tip.
- Problem Excessive air bubbles are introduced into the system tubing Solution – Prime the syringe pumps to remove air bubbles.
- Problem Pressure and vacuum pumps are not working Solution – Please contact Aurora Biomed to obtain new pressure and vacuum pumps and instructions on how to install them or request technical assistance.
- 13. Problem Syringes are leaking or broken

Solution – Please contact Aurora Biomed to obtain new pressure and vacuum pumps and instructions on how to install them or request technical assistance.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

- 14. Problem While running the sequence, a hanging drop is formed outside of the tip Solution – The engaged pipetting tip is probably loose. Check the position calibration of that tip box. Also, check to see if the tip box is place in the correct orientation by verifying that the white dot on the tip box is on the upper left corner. Putting in the tip box in an incorrect orientation can cause the position calibration to be slightly off, causing an imperfect engagement of the tip barrel and the tip. After engagement, tip should be tightly fitted to the barrel.
- 15. Problem The pipetting tip does not aspirate the master mix in the reagent block Solution – The pipetting tip probably touches the bottom of the 7 mol vial. Please refer to Section 5.3.3.1 – Options/Plate Type Settings to decrease the Master Mix Block Depth (mm). Or, the pipetting tip might be above the master mix volume level. Increase the Master Mix Block Depth (mm) in this case. Alternatively, click "Pause" when the tip goes to aspirate the solution and subsequently check/fix the Z-offset (calculate with Z-Offset calculator).
- 16. Problem Pipetting tips do not aspirate or dispense accurate volume Solution – Check if there are air bubbles in the tubing. If so, prime the syringe pumps to remove the air bubbles from the syringes and system tubing. Another reason might be that the engaged pipetting tip is loose. Please teach the related tip box positions approximately 20-30 steps lower (Z-axis) as described in Section 3.1.1 – Position Calibration Check. The syringes installed within the syringe pump might be loose as well. Contact Aurora Biomed for assistance.
- 17. Problem Pipetting tips do not dispense small volumes (1-5μL) Solution – The pipetting tip should slightly touch the bottom of the micro plate. Please check the Z-offset in the VERSAware option for that particular plate type and increase/decrease the plate's Z-offset (mm) for any application tab.
- 18. Problem VERSA stops working suddenly or operation hangs midway Solution – Hibernation, standby, or sleep mode is enabled on system software. To change these settings, refer to the "Power Savings Settings" section of the physical manual. Try closing and re-opening the software again. If the problem persists, restart the PC and reopen the software.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

12.16 Certification Exercise

Before the acceptance of a new or reconditioned VERSA liquid handler, the following certification exercise will be carried out. This will consist of setting up and performing the selective degradative differential digestion on multiple known samples as described in the laboratory's Chemical Batch quality control (i.e. known blood, NIST standard, differential digestion fractions, associated reagent blanks). The reagent kit(s) utilized should be previously QC'ed and certified for use.

Materials:

- VERSA Liquid Handler
- Previously QC'ed and certified for use: PBS, Tween Buffer (TwB), MTL Buffer, Pro K, DTT, DNase I, Mg/Ca Salts and EDTA.
- Laboratory QC samples and controls.

Method(s):

- 1. Set up the VERSA and perform the selective degradative differential digestion according to laboratory protocol.
- 2. Extract, quantify, and type the samples according to the standard laboratory protocol.
- 3. Examine the DNA quantitation and STR typing results obtained.

12.17 Conclusion of Certification Process

If the new or reconditioned VERSA 1100 passes installation, internal calibration checks, protocol setup and a certification exercise, it will be placed into service in the DNA laboratory. If noticeable differences are found, repeat the procedure. If there are still significant differences, contact Aurora Biomed for resolution. Do not use the new VERSA until this process has yielded acceptable results.

12.18 Documentation

Place all data in the appropriate VERSA Use Log under the "Certification" section.

CALLARD CALLARD

Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

13.0 Maintenance Procedures for Aurora Biomed VERSA 1100

13.1 Scope

To describe the internal calibration checks and maintenance procedures for the VERSA 1100 liquid handler.

13.2 References

VERSA 1100 Operation Manual

13.3 Test equipment and material

- Alcohol solution
- Neutral soap solution
- Deionized water
- Kimwipes
- 50µL and 1000µL pipette tips
- AmpliSlide adaptors, 32 Sample blocks
- 96-well teaching plate
- SlicPrep[™] Plate

13.4 Summary of the tests and frequencies

| Test | Frequency |
|---------------------------------------|-----------------------------------|
| Clean worktable, plate adaptors, and | Weekly Clean-up/annual |
| instrument surfaces. NO BLEACH | |
| UV Decontamination | Weekly Clean-up/ annual |
| Empty/fill system fluid bottles | As needed |
| Annual Preventative Maintenance Visit | Annual Maintenance – Conducted by |
| | Service Engineer |
| Position Calibration Check | Annual Maintenance – Conducted by |
| | Service Engineer |
| Volume Calibration Check | Annual Maintenance – Conducted by |
| | Service Engineer |

13.5 Procedure

There are two cleaning procedures: Cleaning the VERSA and UV Decontamination.

There are two internal calibration check tests: position and volume. The position calibration check test needs to be conducted first using a 96-well teaching plate. The appropriate adaptor blocks, plates, and tubes are then calibrated. The volume calibration check includes the syringe pump, reagent drop, and liquid level sensing.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit **Quality Control Manual**

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

If the manufacturer or design of consumable parts (96-well plates, reagent tubes, sample tubes) is changed, run the position calibration check test prior to use in casework.

13.6 Empty/Fill System Fluid Bottles

It is very important that the waste liquid bottle does not get full. Otherwise, the waste liquid may fill the vacuum tube and cause damage to the vacuum pump. Periodically empty the waste bottle to prevent the liquid volume from becoming too high.

The priming liquid bottle is used to prime the syringe pumps. The priming liquid should not reach below the tubing at any time. Otherwise, air will be pumped through the syringe pumps. Periodically fill the priming liquid bottle with sterile deionized water.

13.7 Clean

The instrument deck surface should be wiped down with water and ethanol to remove any contaminants. The plate adaptor blocks should be cleaned weekly with soap water and ethanol.

13.8 UV Decontamination

UV decontamination is performed by turning on the UV light source. The UV time control can be used to set the duration of the UV light for different time intervals. The bio-containment hood of the instrument is made of plexiglass and protects the user against UV radiation.

13.9 Position Calibration Check

Each deck position, except position #6 and 7, should be tested/calibrated to determine if slight offsets may have occurred over the time. Accurate position calibration checks will provide increased pipetting accuracy.

All the deck positions are taught with a 96-well plate. The shaker position and the reagent cooler block positions are taught as is. All positions should be taught to locate the surface of the upper left well (A1) of the 96-well teaching plate. The X & Y coordinates should be adjusted so the tip is positioned in the center of the well. For calibration check of the Z coordinate, a piece of paper can be placed in between the tip barrel and the surface of the 96-well teaching plate. Fine adjustments are made until the tip barrel just touches the paper. Slight resistance should be felt when inserting or removing the paper. Upon completion of all position calibration check, the position setting for all other plate types which are available in the Labware library will be automatically calibrated with respect to the 96-well teaching plate.

<u>For semi-annual check calibration check</u>, first test the various adaptors, plate types, and tubes in their corresponding deck positions to determine if the current calibration check is still accurate. Follow the instructions on "TESTING PLATE TYPES". Check to see if the pipette tip that is engaged is right above the surface of the plate/tube. A piece of paper should be able to slide snuggly between the tip and the plate. Also check to see if the pipette tip is centered in the well or tube. If the current calibration check is still accurate, no further calibration check is needed for that particular



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

position. If the current calibration check is off, then either the position (1) wasn't calibrated correctly or the plate type off-set is not calibrated correctly. Test that particular plate type on a different position (2). If the tip is now centered, then that indicates that the position (1) was calibrated incorrectly. Re-calibrate the position (1) by following the steps on how to "CALIBRATE A POSITION".

If the tip is still off-centered, then it indicates that the plate type off-set is not calibrated correctly. To adjust the plate type off-set, following the steps below on how to "ADJUST PLATE TYPE OFF-SET".

All position calibrations are performed in the Aurora Station interface. There are two ways to access the Aurora Station:

- Open the "Shell Status" Window which runs alongside VERSAware. Double-click on "ASO1 [1]: 1172" and Aurora Station will open from the background.
- 2. In VERSAware, go to "Tools", then click on "Aurora Station". A checkmark will appear next to the interfaces if it is already opened.

*Initialize the instrument by clicking the "Home"

Calibrate a Position

To calibrate or teach a new plate type, go to the "Robotic Arm Tab" and double-click on the position you want to teach in the record selector. No tip should be engaged. Place a 96-well teaching plate on the deck. Set the Z coordinate to 0 in the "Go Z" text box. Click "Go X, Y, Z". If necessary, adjust the X and Y coordinates. Click on the down arrow to adjust the Z coordinates. Reduce the steps of the arm control to 5 or 10 steps for more precise and safe control of the arm movement. The tip barrel should be directly above the teaching plate so that a piece of paper should be able to pass through between the teaching plate and the barrel tip with slight resistance. Click "Save".

Note: If a tip was engaged to calibrate a position, make sure that the **"Tip Calibration"** box is checked. This informs the robot to account for the height differences of a tip.

<u> Tip</u>

To engage a tip, go to the "Robotic Arm Tab" and double-click on the record selector of the position from which the tip will be engaged. Positions 2 & 3 hold 50μ L tips; positions 4 & 5 hold 1000μ L tips. Click on "Tip" to have the arm move to the tip position and engage a tip.

Testing Plate Types

Aurora Station allows you to test previously or newly taught positions for all plate types. It is a good practice to test positions periodically to ensure that the calibration checks for a particular plate type and position sis still accurate.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit **Ouality Control Manual**

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

First, engage a tip following the instruction above on "Tip". Place the plate type (tube/slide/plate) onto the position to be tested. For the SlicPrep[™] plate, only use the base plate; do not include the insert. To test the position with that particular plate type, go to "Options → Aurora Station

Settings" or click on the "Aurora Station settings" icon . Click the "Advanced" tab. On the bottom left corner of the screen under "Test Position [Plate Type]", select the position to test (ignore the description of the position). Click "Apply".

| eneral Advanced Accessories Plate Types I | | |
|--|--|---|
| Tip Engagement [Robotic Arm] | Shaker | Syringe Pump |
| Start Speed (step/s) 50 | Start Speed (step/s) 100 | Pump Connected to Arm |
| End Speed (step/s) 500 | Acceleration (step/s ²) 10 | Pump Device 0 |
| Acceleration (step/s ²) | | Device Address (hex) 31 |
| | Communication | |
| Reagent/Cooler Block | Step Loss Error Count 10 | Positions [Exclude X, Y, Z-Offset] |
| Cooler Address 1 💌 Channel 1 | Time Out Error Count 10 | Position * |
| Position 12 - Shaker/Cooler Plate Taught using | • 1st Time Out (s) 60 | |
| Cooler Control Delay (ms) 10000 | 2nd Time Out (s) 240 | |
| | Command Delay (ms) 100 | |
| Source Temperature | Arm Address (hex) 31 | |
| Source 1 Address 2 - Channel 2 | Device Address (hex) 38 | PI Auto Recovery |
| Position 13 - Source/Target Plate | - | Remove from Initialization |
| | | Double PI Auto Recovery |
| | Auto Recovery | |
| Position 9 - Source/Target Plate | X-Offset (step) 2400 | Syringe Pump 100 μL Small Syringe Pump |
| Chute Orientation | Tip Disengagement | 250 µL Small Syringe Pump |
| ☞ Y-Axis ⊂ X-Axis | Y-Offset (step) 800 | Small Syringe Pump Only |
| Test Position [Plate Type] | Plate Type [Teaching Positions] | Position Test Mode |
| Position 15 - 20 µL Tip Box/Plate | ▼ Plate Type 1 - 96-well Plate ▼ | 🖂 Single Channel Test |
| | | |

Figure 1: Aurora Station settings/Advanced tab.

Next, click on the "Plate Types" tab. Under the "Symmetrical Plates" section, select the plate type that you want to test in that position by highlighting the selection. Click on the icon with a small red square on the top left corner to test the top left corner of the plate type or click on the icon with a small red square on the bottom right corner to test the bottom right corner of the plate type.

- Slides: Plate type #5
- · 50µL Tips: Plate type #18
- · 1000μL Tips: Plate type #21
- · SlicPrep[™] Plate: Plate type #68
- 32-well sample block and reagent cooler block: Plate type #70
 (Testing the 32-well sample block includes the height of the samples tubes)



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit **Quality Control Manual**

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

| Disto Tur | e Description | | Column | . Pour | Column | Distance 🔺 | | Plate Type | Donth | Volume | |
|------------------|------------------------------------|-------------------|--------------|----------|--------------|---------------|---------|-----------------------|------------|---------------------|---|
| | 96-well Plate | | 12 | 8 | 9 | | | | 10.8504 | 1 Volume | |
| 2 | 384-well Plate | | 24 | 16 | 4.5 | | 1 - | 1 | 10.3572 | 20 | |
| 3 | 1536-well Plate | | 48 | 32 | 2.25 | | | 1 | 9.6174 | 40 | |
| 4 | 12-column Reserve | pir | 12 | 1 | 9 | | | 1 | 8.631 | 60 | |
| 5 | 4-glass Slide Tray (| X: 13.2066, Y: | 18.4 | 1 | 31.0784 | | | 1 | 7.6446 | 100 | |
| 6 | 20 uL Tip Box (1-cl | nannel) | 12 | 8 | 9 | - | | 1 | 5.9184 | 140 | |
| | 1.1.1.1.1.1.1.1 | | 1 | -1 | 1.52 | • | | 1 | 4.6954 | 180 | |
| Plate Typ 100 | e Description 35-well Reagent/C | ooler Block (T1 | Column | | Height Diffi | erence 🔺 | | Plate Type 0 100 1 | Column R | ow Depth 19.9746 | - |
| | | | | | | | | | ~ | \sim | |
| | ates [Plate Types: 100 | 3 • [33] | | | | | | Level Sensir | - | | |
| | e Description | 1 01 1 774 | Column | | | erence 🔺 | | | Column R | | - |
| 100 | 35-well Reagent/C | | | | ,) | | | 100 1 | 1 | 18.495 | _ |
| 100 | 35-well Reagent/C | | | | , 1 | | | 100 1 | | 16.435 | |
| 100 | 35-well Reagent/C | | | | ,) | | | 100 1 | | 13,563 | - |
| 100 | 35-well Reagent/C | | | | , , | - | | 100 1 | | 12.33 | - |
| 1.1 | 100 Weinhedgenie ei | obici biocit [1 5 | a 1. I | 10 10 | | | | | - P. | 112.00 | |
| | | | | | | | U_L | | | | |
| ight Differer | nce, Column Offset, Ri | ow Offset, LLS | Compensatio | on, Basi | e Offset, D | epth in (mm), | Volum | e in (μL) | | 0 | 4 |
| | | | | | | | | | | - | |
| nd Plates (F | Plate Types: 200 - 299 | 9] | | | | | | | | | |
| Plate Typ | e Description | Diameter | Circle Dista | nce Ci | rcles Well | s Height Dif | ference | e Offset (X) | Offset (Y) | Adjustment | |
| 200 | Carousel A | 88.57 | 0 | 1 | 32 | -9.1489 | | 47.7595 | -13.3931 | 0 | |
| 201 | Carousel B | 88.57 | 0 | 1 | 32 | -9.0256 | | 48.1514 | -12.467 | 0 | 1 |
| 202 | Rotor G-72 A | 119.28 | 0 | 1 | 72 | 17.111 | | 49.4516 | -49.5522 | 0.8 | |
| | Rotor G-100 A | 118.37 | 0 | 1 | 100 | 17.021 | | 48 | -50 | 0.3 | - |
| 203 | | | | | | | | | | • | |
| 203 | | | | | | | | | | | |

Figure 2: Aurora Station settings/Plate Types tab.

The tip should be in the center of the plate type. If the tip isn't in the center of the plate, then either the position (1) wasn't calibrated correctly or the plate type off-set is not calibrated correctly. Test that particular plate type on a different position (2) by repeating the steps above. If the tip is now centered, then that indicates that the position (1) was calibrated incorrectly. Recalibrate the position (1) by following the steps on how to "Calibrate a Position".

If the tip is still off-centered, then it indicates that the plate type off-set is not calibrated correctly. To adjust the plate type off-set, following the steps below on how to "Adjust Plate Type Off-set".

Adjusting Plate Type Offset

Sometimes, the plate type off-sets that are saved in the Labware library can be slightly off. If that plate type is applied to a position, the tip will not be centered above a well but will instead be off-centered, depending on the severity. An off-centered calibration check can result in inaccurate liquid pipetting or potential crashing of the robotic arm in severe cases.

To adjust the plate type off-set, bring the robotic arm to the calibrated plate type position by following the steps above on how to "Test Plate Position". Close the "Aurora Station Settings" screen. The X, Y, Z coordinates on the top left corner of the screen (in red, green, and blue numbers) indicates the current position of the robotic arm.

| Robotic Arm | Syringe Pump | Cooler Block | k Shaker |
|-------------|--------------|--------------|------------|
| | x -1 | -1 -1 | \sum |
| 0 | Y C | | |



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit **Quality Control Manual**

PART 2. GENERAL APPROACH TO QUALITY CONTROL **OF EQUIPMENT USED IN DNA ANALYSIS**

Go to a new row on the record selector table, indicated with an "*". Type in an arbitrary position number, such as "100", to distinguish from an actual position. Under the comments column, type "Original". Select the new position by highlighting the selection, then click "Save". The current robotic arm coordinates are now saved onto this new position.

| | Position | Step (X) | Step (Y) | Step (Z) | Comment | |
|---|----------|----------|----------|----------|-----------------------|--|
| | 14 | 7837 | 2525 | 7737 | 1000 μL Tip Box/Plate | |
| | 15 | 10233 | 2526 | 7756 | 20 μL Tip Box/Plate | |
| | 16 | 0 | 98 | 7367 | Priming Position | |
| | 17 | 0 | 1331 | 7132 | Waste Position | |
| | 18 | 0 | 2568 | 6937 | The Chute | |
| * | | | | | | |

Figure 4: The position records table.

Adjust the robotic arm using the "Step/Arrow Buttons" until the tip is in the center of the well. Create a new row on the record selector table. Type in an arbitrary position number, such as "101". Under the comments column, type "Adjusted". Select the new position by highlighting the selection, then click "Save". The adjusted robotic arm coordinates are now saved onto this new position.

Double-click on the "Adjusted" position record, then click on the "Original" position record, then click "Offset". The "Offset Calculator" screen will appear, showing the X, Y, and Z steps of both records and the difference between the two records will appear in the light blue numbers in millimeters (mm). Record the "Offset" value. Click "OK" to close.

| Offset Calcula | tor 🗾 |
|-------------------|--------------|
| - Column Distance | |
| ×1 (step) | 0 |
| ×2 (step) | 662 |
| Total Columns | 2 |
| Distance (mm) | 37.6843 |
| Offset (mm) | 37.6843 |
| Row Distance | |
| Y1 (step) | 1331 |
| Y2 (step) | 42 |
| Total Rows | 2 |
| Distance (mm) | 99.253 |
| Offset (mm) | -99.253 |
| Height Difference | • |
| Z1 (step) | 7132 |
| Z2 (step) | 7801 |
| Difference (mm) | -21.4481 |
| Offset (mm) | 21.4481 |
| Tip Calibration | 🗸 🗸 🗸 |
| Figure 5: Offse | t calculator |

Figure 5: Offset calculator

Go to "Options \rightarrow Aurora Station Settings". Click on the "Plate Types" tab and select the plate type to be adjusted by highlighting the selection. Scroll to the right until you see the "Height Difference", "Column Offset", and "Row Offset" columns. Adjust the offsets by adding/subtracting the absolute value(s) recorded from the "Offset Calculator". Click "Apply", then "OK" to close.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

| | Coordinate | Positive (+) Value | Negative (-) Value |
|-------------------|------------|--------------------|--------------------|
| Column Distance | Х | To the right | To the left |
| Row Distance | Y | Towards user | Away from User |
| Height Difference | Z | Up | Down |

Example: Height difference offset: 21.4481. The current position is too low and you want to bring the z-axis up. According to the table, to bring the z-axis up, the height difference should become more positive so you would add 21.4481 to the original value.

Heater/Shaker Unit Position Calibration Check

The heater/shaker unit should be calibrated with the plate type used (SlicPrep[™] Plate)

Reagent Drop Pin Position Calibration Check

To calibrate the reagent drop pin, click "Options \rightarrow Aurora Station Settings". Click on the "Advanced" tab. In the bottom left corner under "Test Position [Plate Type]", select the test position. To the right under "Plate Type [Teaching Position]", select "1 – 96 well plate" and click "Apply". Place the 96-well teaching plate in that position. Click on the "Accessories" tab. Under the "Pin Groups" section on the bottom, select the pin number to test by double-clicking. (Only Pin 2 and 3 are used). Click "RD Test". The robotic arm will go to that position and align the reagent drop pin on the surface of the A1 well of the 96-well teaching plate.

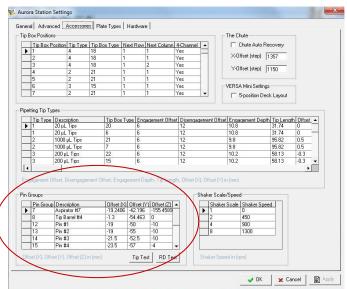


Figure 6: Aurora Station settings/Accessories tab.

To check if the pin is centered on the well, dispense some solution (e.g. 100μ L) manually using the PWM Pump. In the VERSAware interface, go to "Tools \rightarrow PWM Pump". Click on the "C" icon to go into the control mode. Under the "Valves" section, type "100" in the "Volume" column under the desired valve (Valve 1 for Pin 1, etc.). Watch the pin while it dispenses the liquid. If the pin is not

Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

dispensing in the center of the well, change the X and Y Offsets in the "Aurora Station Settings \rightarrow Accessories tab \rightarrow Pin Groups" to center the pin.

- · Negative value in the X-offset moves the robotic arm/pin to the left side
- Negative value in the Y-offset moves the robotic arm/pin away from the user

When finished, go to the PWM Pump interface and click on the "A" icon to change back to assay mode.

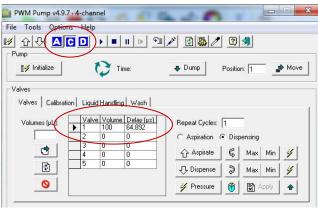


Figure 7: PWM Pump/C Mode.

13.10 Volume Calibration Check

There are three volume calibration checks that are performed: Syringe Pump, Reagent Drop, and Liquid Level Sensing. The volumes that are frequently used in the protocols should be tested by instructing the robot to manually dispense liquid. If the actual volume dispensed is inaccurate, additional steps should be taken to created/adjust the calibration table. However, if the volume dispensed is accurate, no further calibration check is needed. The acceptable range of the actual dispensed liquid volume is within 10% of the targeted volume.

All volume calibrations are performed in either the Aurora Station or PWM Pump interface. There are two ways to access the Aurora Station:

- Open the "Shell Status" Window which runs alongside VERSAware. Double-click on either "ASO1 [1]: 316" or "DH01 [1]: 5616" to open either the Aurora Station or PWM Pump from the background.
- 2. In VERSAware, go to "Tools", then click on either "Aurora Station" or "PWM Pump". A checkmark will appear next to the interfaces if it is already opened.

Syringe Pump Calibration Check

There are two methods to perform the calibration check procedure. The general sequence of aspirating and dispensing liquid for the calibration check is AIR GAP ASPIRATION \rightarrow LIQUID ASPIRATION \rightarrow DISPENSE LIQUID.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit **Ouality Control Manual**

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

- 1. Auto Mode The auto mode runs the general sequence listed above automatically, incorporating delays in between each step.
 - Under the "Pump Calibration" section, type in the steps (1µL = 10 steps) for the air gap aspiration & sample aspiration and the number of seconds for the delay time.
 - Click "Send". The instrument will now aspirate X steps of air, wait for Y seconds, aspirate Z steps of sample, wait for Y seconds, then dispense X + Z steps of volume.
 - During the <u>first</u> delay step, place the sample tube containing water underneath the pipette tip, making sure that the tip is submerged in the water.
 - During the <u>second</u> delay step, remove the sample tube and place the empty weigh boat underneath the pipette tip.

*The Auto Mode should be used for creating new calibration data or adjusting existing data

- 2. **Pump Control Mode** The pump control mode requires manual control of each step in the general sequence listed above.
 - Under the "Pump Control" section, select either the "Volume" or "Steps" option.
 - Volume option: Used for testing particular volumes of liquid to determine if the accurate volume of liquid is aspirated/dispensed
 - · Steps option: Used for adjusting or creating a new calibration table
 - Select "Aspiration" as the function, then enter the desired amount of steps for air gap aspiration (1µL ~ 10 steps).
 - Click "Send". The instrument will now aspirate the air gap.
 - Now enter the desired amount of steps for sample aspiration.
 - Place a sample tube containing water under the pipette tip. Click "Send". The instrument will now aspirate the sample.
 - Select "Dispensing" as the function, then enter the total amount of steps for the air gap aspiration and the sample aspiration.
 - Place an empty weigh boat underneath the pipette tip. Click "Send". The instrument will now dispense the air gap and the sample.

* The Pump Control Mode should be used during normal quarterly checks where the goal is to check if the instrument is dispensing the correct volume of liquid.

Prior to performing a syringe pump calibration check, prime the syringe pump to eliminate all air bubbles in the system. It is recommended to perform 8-10 cycles of priming to fill up the tubing with the system fluid and remove most of the air trapped within the system. For instructions on how to perform a syringe pump priming, refer to section 8: Syringe Pump Priming.



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit **Quality Control Manual**

PART 2. GENERAL APPROACH TO QUALITY CONTROL **OF EQUIPMENT USED IN DNA ANALYSIS**

Switch to the *Robotic Arm Tab*, initialize the robotic arm by pressing the button between the X and Y axes, then move the robotic arm towards you by dragging the Y axis down. This allows the user to have easier access to the syringe pump during the calibration check. Switch back to the Syringe Pump Tab.

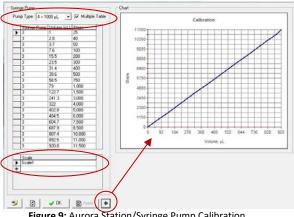
Checking Volume Dispense

Manually engage a tip onto the first barrel. Use a 50µL tip for the 20-50µL range and a 1000µL tip for the 200-1000µL range. Initialize the pump by clicking the "Initialize" button on the bottom of the screen. Under the "Pump Calibration" section, select 4x1000µL as the syringe pump type. Select "Multiple Scale". Prepare a sample tube with water and an empty, pre-tared weigh boat. Use the Pump Control Mode, select the "volume" option, and aspirate and dispense the desired amount of liquid into the empty, pre-tared weigh boat. Weigh the weigh boat. (Note: When using the Pump Control Mode/Volume option, be sure to aspirate an air gap prior to aspirating the liquid. When dispensing, add an extra 50µL to the dispense volume to make sure that all the air and liquid is pushed out.) Multiple the value by 1000 to get the volume $(1mg = 1\mu L)$. Record this value.

Measure the volume 5, 10, 15, 20, 25, and 550µL by repeating the steps above. If the actual volume is significantly different from the targeted volume adjusted the record in the calibration table. However, if all of the actual volumes are significantly off from the targeted volume, create a new calibration table and measure the volume from 3 – 1000µL (~40 – 11,500 steps). Follow instructions below for adjusting or creating a new calibration table.

Adjusting/Creating a New Calibration Table

In Aurora Station, click on the "Syringe" icon 🖄. The calibration table screen should appear. Select the 4x1000µL pump type. Make sure that "Multiple Table" is checked. This allows for multiple calibration tables. Use the Auto Mode or the Pump Control Mode (step option). Aspirate and dispense the desired amount of liquid into the empty, pre-tared weigh boat. Weigh the weigh boat. Adjust either the existing calibration table values or create a new scale by clicking on an empty row under the "Scale" section. Record the sample aspiration step under the "Step" column and the volume measured in the "Volume" column (1mg = 1μ L). Click "Apply", then "OK".





Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

Reagent Drop Calibration Check

Prior to performing a reagent drop calibration check, prime the reagent drop system by clicking the "Pump" icon icon on the VERSAware interface. Type "1000" into the Reagent Drop Priming Volume. Click on the "Reagent" button on the bottom.

On the PWM Pump interface, initialize the pump by clicking the "Initialize" button on the top left corner. To perform volume calibration check, click on the "C" icon to switch into control mode. When the pump is operational, the pressure can be observed by clicking the "Chart" button on the bottom right corner. A graphical pressure curve in real-time will appear, showing the user the current pressure maintained. The pressure should be maintained at about 10 psi.

| | Valve Volume Delay [µs] 1 100 64,892 2 0 0 3 0 0 4 0 0 5 0 0 |
|---|--|
| Volumes (μL): Valve Volume Delay (μs) Repeat Cycles: 1 2 0 0 C Aspiration © Dispensing 3 0 0 C Aspirate C Max Min | Valve Volume Delay [µs] 1 100 64.892 2 0 0 3 0 0 4 0 0 5 0 0 |
| I 100 64,892 ∩ ∩ Aspiration © Dispensing 2 0 0 | 1 100 64,892 2 0 0 3 0 0 4 0 0 5 0 0 |
| 2 0 C Aspiration Ispensing 3 0 0 | 2 0 0 C Aspiration © Dispensing 3 0 0 1 1 Image: Aspirate in the spirate in |
| 4 0 0 Aspirate S Max Min | 4 0 0 5 0 0 ↓ Aspirate € Max Min ¥ 5 0 0 ↓ Dispense ▷ Max Min ¥ |
| | 5 0 0 V Dispense Max Min 4 |
| | Dispense 3 Max Min 4 |
| 5 0 0 | 4 Pressure 1 1 En Apply |
| S Pressure 😗 🛃 Apply | |
| | |
| nt/Received | |

Make sure the instrument is not in calibration mode – the "Syringe" icon is should not be selected. Type "1" for the number of "Repeat Cycles" on the right. Type the volume of liquid to dispense in the "Volume" column next to the valve that is to be tested (290, 400, 510, and 650µL), then click on a different field for the software to refresh and update. (*Note: do not put the type the volume of liquid to dispense in the "Volume" box on the left*). Place an empty, pre-tared weigh boat below the reagent drop pins and click "Dispense". Weigh the weigh boat and determine if the instrument is accurately dispensing the volume of liquid. If the volume dispensed is accurate, no further calibration check is needed. If it is not, a volume calibration check might need to be performed by following the instructions below.

Click on the "Syringe" icon \swarrow on the top. This puts the instrument in calibration mode. When the calibration mode is selected, the values that the user inputs for volume is actually in terms of delay time, which is the length of time the valve is opened for in micro-seconds (μ s).



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit Quality Control Manual

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

Click on the "Pump" icon it o open the pump calibration table. This is location where all of the calibration scales for the reagent drop is maintained. New calibration data will be recorded here. The volumes for the reagent drop calibration check can be adjusted in the "Dispensing" table. A new scale can be created instead by clicking on the empty row in the "Scales" table. Enter the date and the liquid used to perform the volume calibration check. Under the "Aspiration" table, enter the numbers 1 - 5 in the "Valves" column. Enter "0" in the "Volumes" column. Enter "1" in the "Cycles" column. Enter "0" in the "Pulse" column. Enter "0" in the "Delay" column. Click "Apply", then "OK"

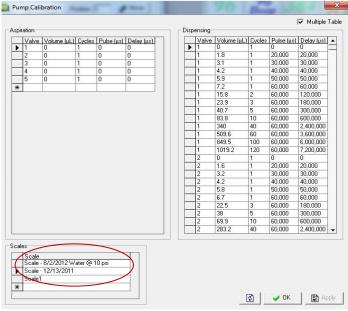


Figure 1: Pump Calibration table

In the PWM Pump main screen, select the "Valves" *Tab* in the "Valves" section. Select the pin valve to calibrate (*Only valves* 1 - 3 *are available on this instrument*). Type "50,000" in the "Volume" column. Make sure that the other valves have "0". Remember, in the calibration mode, this is actually the delay time in μ s that the valve will be opened for. Type "1" for the number of "Repeat Cycles" on the right. Make sure that "Dispensing" is selected. Place an empty, pre-tared weigh boat underneath the reagent drop valve, then click "Dispense". Weigh the volume and record in the pump calibration table.

| Volumes (µL): | Val | ve Volum | ne Delay (µs) | Repeat Cyc | les: 1 | - | |
|---------------|-----|----------|---------------|---------------|-----------|---------|-----|
| volumes (µL). | *1 | 100 | 64,892 | (Thepeak Cyc | 103. [] | | |
| | 2 | 0 | 0 | C Aspiratio | on 💽 Disj | pensing | |
| 1 | 3 | 0 | 0 | | | | 1.1 |
| | 4 | 0 | 0 | ☆ Aspira | te 🔍 | Max Min | |
| 1 | 5 | 0 | 0 | 다. Disper | ise 5 | Max Min | |

Figure 2: PWM Pump/Valves Tab



Oakland Police Department Criminalistics Laboratory Forensic Biology Unit **Ouality Control Manual**

PART 2. GENERAL APPROACH TO QUALITY CONTROL OF EQUIPMENT USED IN DNA ANALYSIS

Click on the "Pump" icon ito go into the Pump Calibration screen. In the "Dispensing" table, type the pin valve number that is being calibrated in the "Valve" column. Type 0, 1, 0 in the "Volume, Cycles, Pulse" columns. In the next row, type "1" in the "Cycles" column and "100,000" in the "Pulse" column. The "Delay" will automatically be calculated using the equation: Cycles x Pulse = Delay. Record the volume that was measured in the weigh boat (1mg = 1 μ L).

Measure the volume at multiple cycles by changing the number of "Repeat Cycles" in the main screen. Cover the range from $100,000 - 6,000,000 \mu s$ (~ $10 - 750 \mu L$). There is no need to do every cycle to reach 6,000,000. Measure an average of about 10 - 15 cycles. After calibration check of one pin valve is completed, repeat for the 2nd and 3rd valve. Enter 0, 1, 0 in the "Volume, Cycles, Pulse" columns for Valves 4 and 5. Click "Apply", then "OK". Switch back to the Assay Mode by clicking on the "A" icon when finished with the volume calibration checks.



Table of Contents

| 1. | Table | e of Contents | |
|----|-------|---|----|
| 2. | Abo | ut This Manual | 3 |
| 3. | Disc | laimer | 3 |
| 4. | War | ranty | 3 |
| 5. | Safe | ty Precautions | 4 |
| 6. | Syst | em Overview | 5 |
| 7. | Hard | dware Installation | 7 |
| | 7.1. | Workbench Unpacking & Preparing for Installation | 7 |
| | 7.2. | Tubing and Bottles | 7 |
| | 7.3. | External Equipment Connections | 9 |
| | 7.4. | Power & USB Connection | 9 |
| 8. | Soft | ware Installation | 11 |
| | 8.1. | VERSAware Installation | 11 |
| | 8.2. | COM Ports – Changing or Reassigning | 15 |
| | 8.3. | Changing COM Ports in Control Panel for Windows Vista | 16 |
| | 8.4. | Power Options and User Accounts | 19 |
| | 8.5. | Software Upgrading (Optional) | 21 |
| 9. | VER | SA1100 Set up - Aurora Station | 21 |
| | 9.1. | Robotic Arm Tab | 22 |
| | 9.2. | Teaching Positions | 26 |
| | 9.3. | Testing New and Default Plate Types | 30 |
| | 9.4. | Reagent Drop Pin Position Teaching | 35 |
| | 9.5. | Reagent Drop Calibration (PWM PUMP) | 40 |
| | 9.6. | Single Channel Barrel Position Teaching | 49 |
| | 9.7. | Syringe Pump Tab | 49 |
| | 9.8. | Calibration of Syringe Pumps (8-channel x 1000µL) | 51 |
| | 9.9. | Reagent Cooler Block Tab | 63 |
| | 9.10. | Source Temperature Tab | 65 |
| | 9.11. | Shaker Tab | 65 |
| | 9.12. | Gripper & Aspirator Tab | 66 |
| | 9.13. | Vacuum Tab | 68 |



| 9.14 | 4. | Command Log Tab | 69 |
|------|------|---|-----|
| 9.15 | 5. | Liquid level Sensing (Optional-Single Channel - LLS Hardware Required). | 69 |
| 9.16 | 6. | Aurora Station Settings | 90 |
| 10. | VER | SA 1100 Main Interface | 95 |
| 10.1 | 1. | VERSAware Drag-Drop Plate Library | 97 |
| 10.2 | 2. | VERSAware 1100 Drop-down Menu | 104 |
| 10.3 | 3. | VERSAware 1100 Options | 107 |
| 11. | VER | SA Application Tabs | 118 |
| 11.1 | 1. | Startup | 118 |
| 11.2 | 2. | Basics | 118 |
| 11.3 | 3. | Folder Assays and Sequences | 119 |
| 11.4 | 4. | Add New Assay Icon | 121 |
| 11.5 | 5. | Serial Dilution Application Tab | 122 |
| 11.6 | 6. | Plate Reformatting Application Tab | 124 |
| 11.7 | 7. | NAP/Advanced Reagent Addition Application Tab | 126 |
| 11.8 | 8. | Slide Tab | 131 |
| 12. | UV/ | HEPA Hood | 132 |
| 13. | Wor | kstation Maintenance | 133 |
| 13.1 | 1. | General Guidelines | 133 |
| 13.2 | 2. | Tubing | 133 |
| 13.3 | 3. | Waste Bottles | 133 |
| 14. | Trou | ubleshooting | 135 |
| 15. | Spec | cifications | 140 |
| 16. | Syst | em Requirements | 141 |
| 17. | Prod | duct Service and Customer Support | 142 |



2. About This Manual

Important: Prior to the initial operation of the instrument, please read these operating instructions carefully to make sure you prevent possible damage to the instrument.

Instructions for the VERSA 1100 workstation include the following general areas:

- ✓ Installing the VERSA1100 System
- ✓ Configuration the VERSA hardware for specific application requirements
- ✓ Creating or modifying assays
- ✓ Running assays
- ✓ Performing preventive maintenance

3. Disclaimer

Application of this system for analytical purposes, utilizing third party, or in-house methods, remains the professional responsibility of the end user. The system is not intended to diagnose, mitigate, prescribe, treat, cure, or prevent any disease or illness or symptoms when used in any analytical procedure.

Aurora Biomed Inc., Aurora Instruments Ltd. or any of their employees, shall not be held liable in any way for problems encountered by the use of this product or procedures performed on this product outside of its intended purpose.

4. Warranty

The warranty, where applicable, only covers defects arising from normal usage of the instrument and does not cover malfunction or failures resulting from misuse, abuse, neglect, alteration, modification, erratic AC power, natural disasters or repairs by someone other than an authorized Service Representative. The Warranty includes unlimited telephone and e-mail access to our Service Engineers between our standard hours of operation. Please refer to your purchase agreement for details of your warranty coverage.



5. Safety Precautions

Use this product only in the manner described in this manual. When used in a manner other than specified, user safety may be jeopardized.

Arm Safety

Attention: Always keep body parts, hair, jewelry and clothing away from the robotic arm while it is operating. Failure to do so may result in injury.

Deck units

Attention: Some deck unit modules can be set at high temperatures. When operating the instrument be aware of these units to prevent accidental burns.

Some deck unit modules are replaceable. Strictly follow the instructions in this manual when replacing them.

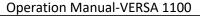
Some deck unit modules include a motor. Never try to physically stop them or use an object to interfere with their action. Press the emergency stop bottom in the event of any unexpected situations.

Station Safety

Caution: Risk of electric shock. To reduce the risk of electric shock, do not remove the cover on the back of the instrument. There are no user-serviceable parts inside.

Never force any component to fit if it does not do so easily.

Attention: Be sure that the workstation and all its deck components are assembled and in their proper positions before beginning operation. Failure to do so may result in injury and/or damage to the equipment.





Pump Safety

Caution: The Pump is equipped with both positive-pressure and a vacuum that is controlled by the system's software. Please keep the caps of the buffer bottles tightened in order to avoid pressure/vacuum release.

Solvents & Reagent Drop

The VERSA 1100 Reagent Drop valve is equipped to handle most organic solvents. However special care should be taken with some solvents. Please consult Aurora representative regarding solvent use if you are unsure. Aurora is not responsible for damage incurred to the valves / tubing if the Reagent Drop is used with strong solvents. Contact Aurora for more information prior to use.

Attention: Reagent box is under pressure; take an extra care while opening this box. Always release pressure from the pressure release valve before opening.

6. System Overview

The VERSA1100 is an automated liquid handler which can be used to fully automate the following applications upon requested:

Serial Dilution Plate Reformatting Nucleic Acid Preparation (NAP)

AmpliSlide

The VERSA 1100 (*Figure 6-1 Front View*) is a multichannel system with an arm equipped with 8 barrels, a plate gripper to move the plate from one position to another, and up to 5 reagent drop pins for bulk dispensing of reagents. There are 15 deck positions which have been customized for the specific needs of the user(*Figure 6-2 VERSA 1100 Deck Layout*).





Figure 6-1 Front View



Figure 6-2 VERSA 1100 Deck Layout



7. Hardware Installation

7.1. Workbench Unpacking & Preparing for Installation

The VERSA 1100 is approximately 920W x 615L x 999H (mm) including the bio-safety hood. However, we recommend that the user also provide additional space on all sides of the instrument (especially at the back where the Waste Bottles and Reagent Box will be situated). The workbench should be stable, vibration free and capable of handling up to 100 kg.

The VERSA 1100 instrument will arrive securely packaged in a wooden crate specially sized for this instrument. Open the wooden crate, and remove the instrument carefully and place on a sturdy work bench. After removing the cellophane wrapping (*Figure 7-1 VERSA 1100 with cellophane wrapping*), carefully remove the packing material from all sides of the arm (as well as the track that the arm moves along). After clearing the instrument of all packing material, move the arm manually to the far left corner. Connect all the tubings to waste bottles & pressure box as shown below.



Figure 7-1 VERSA 1100 with cellophane wrapping

7.2. Tubing and Bottles

There are two tubing connections to be made on the VERSA 1100. See the picture below(*Figure 7-2 Reagent drop tubing Connections*) to familiarize yourself with all the tubing connections for pressure, vacuum and waste (Please note that depending on your application your unit may not have all the below features and connections).

General Waste: This bottle collects the waste coming from the protocols run on this system. This is directly connected from the waste position # 17 to the waste bottle. There is no vacuum or pressure required for this tubing.





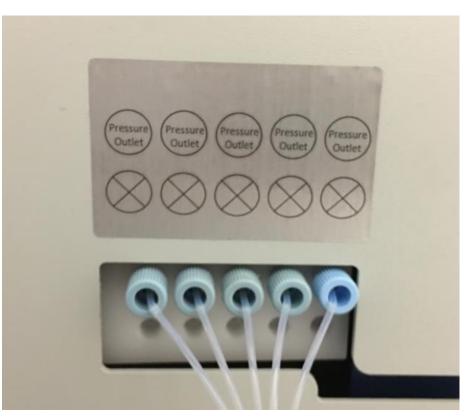
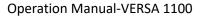


Figure 7-2 Reagent drop tubing Connections



Figure 7-3 Reagent Bottles for reagent drop pins





7.3. External Equipment Connections

The VERSA 1100 has two external devices to be connected to the main unit; the UV/HEPA cover(*Figure 7-4 UV/HEPA power cable connection*) and the vacuum pump for the 96 channel aspirator.



Figure 7-4 UV/HEPA power cable connection

7.4. Power & USB Connection

The connection to the computer is via a USB cable(*Figure 7-5 USB Cable Connections*). Please plug the cable into the USB port at the back panel near the power outlet and on the personal computer. The power cable should then be plugged into the power source. The power switch is located above the power cable connection (*Figure 7-6 VERSA and Vacuum pump Power Connections*). Connect the vacuum pump power connection too if the unit is equipped with 96 channel aspirator or vacuum modules for DNA/RNA extraction protocols.

Switch on the instrument. There is an emergency switch in front of the unit which can be used to turn the instrument off quickly in an emergency(*Figure 7-7 Emergency Switch*). Switch Ensure this emergency switch is not tripped when turning on the system.







Figure 7-5 USB Cable Connections



Figure 7-6 VERSA and Vacuum pump Power Connections



Figure 7-7 Emergency Switch

Note: In case of any emergency, if the instrument is turned off from this emergency switch, remember to pull the switch back out when ready to restart the instrument.



8. Software Installation

The software will come pre-installed on the computer that is shipped with your instrument, therefore once switching on the computer look for the software shortcut icon titled "VERSAware" on the desktop.

Double click on the icon to open the software. There is no password set to open the software (just click ENTER), a password can be set at a later time if desired. Once the software opens proceed to next section.

If however you are installing the software on a new computer from the CD, please follow the instructions as below.

8.1. VERSAware Installation

1. Log on to Windows with the Administrator Account or any account (local or domain) that belongs to the Administrator group to install and run the VERSAware 1100A software.

2. Disable User Account Control: In "Control Panel \rightarrow User Accounts \rightarrow Change User Account Control settings \rightarrow set Never Notify".

Restart the computer.

3. Following restart, go to "Control Panel \rightarrow Power Options \rightarrow Change plan settings". Select the current power plan.

"Put the computer to sleep \rightarrow Never".

Go to "Control Panel \rightarrow Power Options \rightarrow Change plan settings \rightarrow Change advanced power settings".

"Hard disk \rightarrow Turn off hard disk after \rightarrow Never".

"Sleep \rightarrow Sleep after \rightarrow Never".

"Allow hybrid sleep \rightarrow Off".

"Hibernate after \rightarrow Never".

"Allow wake timers \rightarrow Disable".

"Power buttons and lid \rightarrow Power button action \rightarrow Shut down".

4. If this or any previous version the VERSAware software is installed on the computer, please rename the previous VERSAware 1100A software folder if available:

C:\Program Files\Aurora Biomed\VERSAware 1100A

to C:\Program Files\Aurora Biomed\VERSAware 1100A_old

("C:\Program Files (x86)\Aurora Biomed\VERSAware 1100A" in case of Windows Vista (64-bit), Windows 7, Windows 8)



5. Copy the entire contents of the installation CD to any local hard drive folder before installation. Install the software by running "Setup.exe" from local hard drive folder (Figure 8-1VERSAWare 1100A Installation Folder Selection-click Setup.exe).

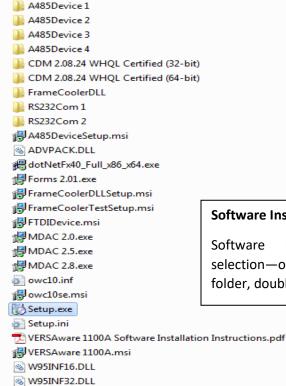
Follow the installation process. Press "Finish" and/or "Close" buttons each time after RS232Com and A485Device component installation windows request user input.

Do not press the "Cancel" button during the installation process.

Choose "Repair" options for libraries and components.

Wait until Microsoft .NET Framework 4 is fully installed.

Total software installation time should be between 1 - 5 min. depending on the computer speed.(Figure 8-3 VERSAWare 1100A Software installed successfully window)



Software Installation:

Software installation folder selection—open release package folder, double click "Setup.exe"

Figure 8-1VERSAWare 1100A Installation Folder Selection-click Setup.exe



| A485Device1 | |
|---------------------------|--|
| A485Device2 | |
| A485Device3 | |
| A485Device4 | |
| CDM 2.08.24 WHQL Cert | ified (32-bit) |
| CDM 2.08.24 WHQL Cert | ified (64-bit) |
| FrameCoolerDLL | |
| RS232Com1 | |
| RS232Com2 | |
| RS232Com3 | |
| A485DeviceSetup.msi | |
| ADVPACK.DLL | |
| 🕂 dotNetFx40_Full_x86_x6 | VERSAware 1100A |
| 🚰 fm2paste.exe | Please wait while Windows configures VERSAware 1100A |
| FrameCoolerDLLSetup. | |
| FrameCoolerTestSetup. | |
| FTDIDevice.msi | Time remaining: 0 seconds |
| MDAC_TYP2.0.EXE | Cancel |
| MDAC_TYP2.1.EXE | |
| MDAC_TYP2.5.EXE | |
| MDAC_TYP2.8.EXE | |
| owc10.inf | |
| 🔂 owc10se.msi | |
| 🔀 Setup.exe | |
| 🗿 Setup.ini | |
| 😼 UltrasonicDeviceSetup.m | nsi |
| TVERSAware 1100A Softwa | are Installation Instructions.pdf |
| 🛃 VERSAware 1100A.msi | |
| W95INF16.DLL | |
| W95INF32.DLL | |
| | |

Figure 8-2 VERSAWare 1100A Software installation window

| A485Device1 | | | | | | |
|-------------------------|--|--|--|--|--|--|
| A485Device2 | | | | | | |
| A485Device3 | | | | | | |
| A485Device4 | | | | | | |
| 🐌 CDM 2.08.24 WHQL Ce | ertified (32-bit) | | | | | |
| 🐌 CDM 2.08.24 WHQL Ce | ertified (64-bit) | | | | | |
|] FrameCoolerDLL | | | | | | |
|] RS232Com1 | | | | | | |
| 📙 RS232Com2 | | | | | | |
| 🐌 RS232Com3 | | | | | | |
| 🛃 A485DeviceSetup.msi | | | | | | |
| ADVPACK.DLL | | | | | | |
| 🚜 dotNetFx40_Full_x86_x | 64.exe | | | | | |
| 🚰 fm2paste.exe | | | | | | |
| FrameCoolerDL | SAware 1100A | | | | | |
| FrameCoolerTes | | | | | | |
| FTDIDevice.msi | FTDIDevice.msi | | | | | |
| MDAC_TYP2.0.E | 8 ⁷ | | | | | |
| MDAC_TYP2.1.E | thering required information | | | | | |
| GIMDAC_TYP2.5.6 | | | | | | |
| MDAC_TYP2.8.E | Cancel | | | | | |
| 🗑 owc10.inf | | | | | | |
| 🔂 owc10se.msi | VERSAware 1100A | | | | | |
| 🔀 Setup.exe | VERSAWare 1100A | | | | | |
| 🗑 Setup.ini | | | | | | |
| 🛃 UltrasonicDeviceSetup | .msi VERSAware 1100A Setup completed successfully. | | | | | |
| TVERSAware 1100A Soft | ware Installati | | | | | |
| 🔁 VERSAware 1100A.msi | | | | | | |
| W95INF16.DLL | ОК | | | | | |
| 🚳 W95INF32.DLL | | | | | | |
| | | | | | | |

Figure 8-3 VERSAWare 1100A Software installed successfully window



After the software is installed successfully, software shortcut icon will appear on the monitor screen (*Figure 8-4 VERSAware1100 software shortcut icon on the screen*).





Software folder will be created at C drive-program files(x86) Aurora Biomed as shown below:

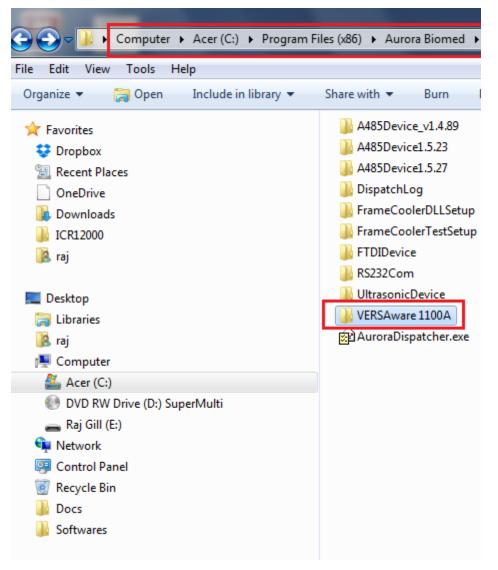


Figure 8-5 VERSAware1100 software installed folder



| Solution Scer (C:) > Pro | gram Files (x86) 🕨 Aurora Biomed 🕨 VERSAw. | are 1100A 🔸 | | | |
|-------------------------------------|--|-----------------|--------------------|------------|--------------|
| ile Edit View Tools Help | | | | | |
| Organize Include in library Share | vith 🔻 Burn Compatibility files N | lew folder | | | |
| ☆ Favorites | Name | Date modified | Туре | Size | File version |
| 😌 Dropbox | 퉬 Img | 5/5/17 11:46 AM | File folder | | |
| 📃 Recent Places | VersaWare.mdb | 1/18/17 9:57 AM | Microsoft Access | 161,312 KB | |
| OneDrive | AS.bmp | 1/18/17 9:57 AM | Bitmap image | 34 KB | |
| 〕 Downloads | S.exe | 1/18/17 9:57 AM | Application | 24,524 KB | 1.20.0.97 |
| JCR12000 | VERSAware 1100A.exe | 1/18/17 9:57 AM | Application | 25,488 KB | 3.6.0.63 |
| 🥦 raj | 🔄 VERSAware 1100A.ico | 1/18/17 9:57 AM | Icon | 4 KB | |
| | 🛐 AS.gif | 1/18/17 9:57 AM | GIF image | 464 KB | |
| 📃 Desktop | 🖅 AS.ico | 1/18/17 9:57 AM | Icon | 3 KB | |
| 🥽 Libraries | AuroraArms.ini | 1/18/17 9:57 AM | Configuration sett | 4 KB | |
| 🥦 raj | 🛃 DH.bmp | 1/18/17 9:57 AM | Bitmap image | 24 KB | |
| 🖳 Computer | 💼 DH.exe | 1/18/17 9:57 AM | Application | 1,696 KB | 4.10.0.6 |
| 🏭 Acer (C:) | 🔚 DH.gif | 1/18/17 9:57 AM | GIF image | 464 KB | |
| 💿 DVD RW Drive (D:) SuperMulti | 💼 DH.ico | 1/18/17 9:57 AM | Icon | 3 KB | |
| 👝 Raj Gill (E:) | Software.ini | 1/18/17 9:57 AM | Configuration sett | 2 KB | |
| 🗣 Network | AS.mdb | 1/18/17 9:57 AM | Microsoft Access | 2,732 KB | |
| 😝 Control Panel | 📰 c.ini | 1/18/17 9:57 AM | Configuration sett | 2 KB | |
| 🗑 Recycle Bin | PWMPump.pwm | 1/18/17 9:57 AM | PWM File | 728 KB | |
| 퉬 Docs | DH.mdb | 1/18/17 9:57 AM | Microsoft Access | 232 KB | |
| 鷆 Softwares | | | | | |

Figure 8-6 VERSAware1100 – Open VERSAware1100 software to see all files

Restart the computer after the VERSAware 1100A software installation.

7. Connect the instrument using the USB cable, and turn the instrument power on.

If the computer is connected to the Internet, confirm that COM ports are automatically installed one by one in "Control Panel \rightarrow Device Manager \rightarrow Ports (COM & LPT)".

If no Internet connection is available, install the FTDI USB-to-RS232 driver for each "Control Panel \rightarrow Device Manager \rightarrow Other devices \rightarrow USB Serial Port \rightarrow right-mouse click \rightarrow Properties \rightarrow Driver \rightarrow Update Driver..." from one of the folders located on the installation CD:

"CDM 2.08.24 WHQL Certified (32-bit)" in case of Windows XP, Windows Vista (32-bit)

"CDM 2.08.24 WHQL Certified (64-bit)" in case of Windows Vista (64-bit), Windows 7, Windows

8.2. COM Ports – Changing or Reassigning

Usually, if the above mentioned steps are followed, COM ports should be assigned correctly and automatically. Make sure all comports are working first under Control Panel. If necessary, COM ports can be reassigned correctly under the associated directories as follows:

For Windows XP (Start --> Control Panel --> System --> Hardware --> Device Manager)

For Windows Vista (Start --> Control Panel --> Device Manager):

Change or adjust COM port numbers (if necessary) in Control Panel as displayed in table below(*Figure 8-7 COM Ports Allocation*) :



| L. | Device | Description | COM Port | | | Range (Y) | Range (Z) | Start Speed (X) | |
|----------|--------|----------------------------|----------|-----------|-------|-----------|-----------|-----------------|------|
| | U | Syringe Pump (1000 µL) | 4 | FTT7Q0V4A | 20000 | | | 10 | 1000 |
| | 1 | Robotic Arm | 3 | C | 12100 | 2700 | 7800 | 50 | 1500 |
| | 3 | Syringe Pump (8 × 1000 μL) | 4 | FTTA4HRAC | 20000 | | | 10 | 1000 |
| | 4 | Gripper Arm | 12 | FTT7Q0V4C | 46000 | | | 100 | 2000 |
| * | | | | | | | | | |
| <u> </u> | | 1 | 1 | 1 | 1 | I | | 1 | 1 |

Figure 8-7 COM Ports Allocation

8.3. Changing COM Ports in Control Panel for Windows Vista

The below section will discuss how to change COM port numbers in the Control Panel for Windows Vista. COM port numbers should be adjusted in such way that they match COM ports configured in Aurora Station(*Figure 8-8 Aurora Station Settings*) and Device Manager DH (if the instrument features the Reagent Drop).

Please check COM port configuration in Aurora Station .

Aurora Station \rightarrow Aurora Station Settings \rightarrow Hardware

| | | | | | | | pes india. | inced Accessories Plate Ty | n Auva | nore |
|---------|---------------|-----------------|-----------|-----------|-----------|---------------|------------|----------------------------|--------|-------|
| | | | | | | | | | es |)evid |
| eed (X) | End Speed (X) | Start Speed (X) | Range (Z) | Range (Y) | Range (X) | Serial Number | COM Port | Description | Device | |
| | 1000 | 10 | | | 20000 | FTT7Q0V4A | 4 | Syringe Pump (1000 µL) | 0 | • |
| | 1500 | 50 | 7800 | 2700 | 12100 | С | 3 | Robotic Arm | 1 | |
| | 1000 | 10 | | | 20000 | FTTA4HRAC | 4 | Syringe Pump (8 × 1000 μL) | 3 | |
| | 2000 | 100 | | | 46000 | FTT7Q0V4C | 12 | Gripper Arm | 4 | |
| | | | | | | | | | | * |
| | | | | | | | | | | |
| _ | | | | | | | | | 3 4 | * |

Figure 8-8 Aurora Station Settings

COM port numbers should be adjusted in Control Panel (*Figure 8-9 Windows Vista Control Panel*) of Windows Vista starting with the COM port for the robotic arm :

Start \rightarrow Control Panel \rightarrow Device Manager

| Control Panel + | | | | | earch | | ٩ |
|----------------------------------|---------------------|------------------------|-------------|-------------------------|---------------------|------------------|------------|
| <u>Eile Edit View Tools Help</u> | | | - 🍓 E | incrypt File 🏼 🍳 | 👌 Decrypt File | e 🥪 Oper | /Close PSD |
| Control Panel Home | Name | Category | | | | | |
| Classic View | Add Handware | Administrat Tools | AutoPlay | Backup and Restore C | Color Management | Date and Time | = |
| | Default Programs | De View and Manager | Copdate you | r hardware's s | A ettings and driv | E software. | |
| | ricgiuns | Wanege | Access | options | | concroners | - |
| 1 item selected | | | | | | | .d |

Figure 8-9 Windows Vista Control Panel





Display available COM ports in Device Manager of Windows Vista as shown in below Figure (*Figure 8-10 Windows Vista Device Manager*).

| 🚔 Device Manager | |
|---|---|
| File Action View Help | |
| | |
| a aurora-PC-test | |
| D P Computer | |
| Disk drives | |
| b Number of the second seco | |
| DVD/CD-ROM drives | |
| D - Compared Television Description of the second secon | |
| b — Keyboards | |
| Mice and other pointing devices | |
| Monitors | |
| b - 1 Network adapters | |
| Portable Devices | |
| a TP Ports (COM & LPT) | E |
| 11 USB Serial Port (COM10) | |
| - 🦉 USB Serial Port (COM11) | |
| USB Serial Port (COM12) | |
| | |
| USB Serial Port (COM2) | |
| USB Serial Port (COM3) | |
| USB Serial Port (COM4) | |
| 🖤 USB Serial Port (COM5) | |
| USB Serial Port (COM6) | |
| USB Serial Port (COM7) | |
| USB Serial Port (COM8) | |
| USB Serial Port (COM9) | |
| Processors | |
| b al Sound video and name controllers | |
| | |

Figure 8-10 Windows Vista Device Manager

This example will illustrate how to change one particular COM port 3 to COM port 11 (as an example) and this process can be applied to all other COM ports.

COM port numbers in Device Manager should match the COM ports in Aurora Station and Device Manager DH (if the system features the Reagent Drop).

Standard COM port configuration in Device Manager might have 4, 8 or 12 individual COM ports (Prolific USB-to-Serial Bridge).

Any existent COM port should only be changed to the new COM port number which is not available in Device Manager to avoid communication errors. All COM port numbers that are featured in Device Manager should not exceed 16. This is one of the basic requirements for the software configuration. Use left double-click with your mouse to display COM port properties as shown in below Figure *8-11 COM Port Properties*).

| Prolific US | SB-to-Serial Bridg | e (COM3) Properties | 8 X | | | |
|-------------|----------------------------------|--------------------------|--------|--|--|--|
| General | Port Settings D | river Details | | | | |
| | Prolific USB-to-S | erial Bridge (COM3) | | | | |
| | Device type: | Ports (COM & LPT) | | | | |
| | Manufacturer: | Prolific Technology Inc. | | | | |
| | Location: | Port_#0001.Hub_#0005 | | | | |
| Devi | ce status | | | | | |
| This | This device is working properly. | | | | | |
| | | | ~ | | | |
| | | | | | | |
| | | ОК | Cancel | | | |

Figure 8-11 COM Port Properties



Please switch to 'Port Settings' tab as displayed in the below Figure (*Figure 8-12 COM Port Settings*).

| Prolific USB-to-Serial Bridge (COM3) Properties | | | | | | |
|---|--|--|--|--|--|--|
| General Port Settings Driver Details | | | | | | |
| | | | | | | |
| Bits per second: 9600 | | | | | | |
| Data bits: 8 | | | | | | |
| Parity: None | | | | | | |
| <u>S</u> top bits: 1 ▼ | | | | | | |
| Elow control: None | | | | | | |
| Advanced Restore Defaults | | | | | | |
| | | | | | | |
| | | | | | | |
| | | | | | | |
| | | | | | | |
| OK Cancel | | | | | | |

Figure 8-12 COM Port Settings

Click 'Advanced' button as shown in the below Figure (Figure 8-13 Advanced COM Port Settings).

| Advanced Settings for COM3 | | X |
|---|----------------|------------------|
| ☑ ∐se FIFO buffers (requires 16550 compatible UART) | | OK |
| Select lower settings to correct connection problems. | | Cancel |
| Select higher settings for faster performance | | |
| Receive Buller. Low (1) | High (14) (14) | <u>D</u> cfaulta |
| Transmit Euffer: Low (1) | High (16) (15) | |
| CON Port Number: COM3 | | |

Figure 8-13 Advanced COM Port Settings

Change COM port number to 11 (just for this example) as displayed in below Figure(*Figure 8-14 COM Port Number*) and press 'OK' button.

| | ires 16550 compatible UART) o correct connection problems. | | | OK Cancel |
|------------------------|---|----------------------------|--------------|--------------|
| Select nigner setungs | , | High (14) High (16) | (14) (16) | Defaults |
| COM Port Number: COM11 | | | | |

Figure 8-14 COM Port Number



The new COM port number will appear in Windows Vista Aurora Station shown in below Figure(*Figure 8-15 Windows Vista Device Manager*). Please perform the same procedure for all COM ports that need to be adjusted.

| Device Manager | |
|--|--|
| ile Action View Help | |
| • 🔿 🖬 🖬 🖬 💐 | |
| aurora-PC-test | |
| ⊳ - I Computer | |
| Disk drives | |
| Display adapters | |
| DVD/CD-ROM drives | |
| IDE ATA/ATAPI controllers | |
| >- Keyboards | |
| Mice and other pointing devices | |
| Monitors | |
| Network adapters | |
| Portable Devices | |
| a 🌁 Ports (COM & LPT) | |
| USB Serial Port (COM10) | |
| USB Serial Port (COM11) | |
| | |
| USB Serial Port (COM13) | |
| USB Serial Port (COM2) | |
| USB Serial Port (COM3) | |
| | |
| USB Serial Port (COM5) | |
| USB Serial Port (COM6) | |
| T USB Serial Port (COM7) | |
| | |
| USB Serial Port (COM9) | |
| Processors | |
| b all Sound video and game controllers | |

Figure 8-15 Windows Vista Device Manager

8.4. Power Options and User Accounts

To reduce the probability of robotic interruption during operation, it is strongly advised that you disable any screen savers, hibernation or standby features.

Power Saving Settings (Windows XP):

These settings should be incorporated for VERSAWare to run without interruptions and be compatible to Windows XP

Go to:

Control Panel --> Power Options --> Power Schemes:

Set the following options for the:

1. Settings for power scheme:

Turn off monitor: Never

Turn off hard disks: Never

System standby: Never

Control Panel --> Power Options --> Hibernate:

2. Disable hibernation/ Uncheck hibernation

Power Saving Settings (Windows Vista):

These settings should be changed for VERSAWare to run without interruptions and be compatible to Windows Vista

Go to:



Control Panel --> User Accounts --> Turn User Account on or off Use User Account Control to help protect your computer (Not checked) Control Panel --> Power Options --> Change plan settings --> Put the computer to sleep: Never Control Panel --> Power Options --> Change plan settings --> Change advanced power settings Set the following options for the:

1. Hard disk

Turn off hard disk after On battery: Never Plugged in: Never

- 2. Sleep
 - Sleep after

On battery: Never

Plugged in: Never

Allow hybrid sleep

On battery: Off

Plugged in: Off

Hibernate after

On battery: Never

Plugged in: Never

3. Power buttons and lid

Lid close action

On battery: Do nothing

Plugged in: Do nothing

Power button action

On battery: Shut down

Plugged in: Shut down

Start menu power button

On battery: Shut down

Plugged in: Shut down

4. Battery

Critical battery action On battery: Shut down



Plugged in: Do nothing

Low battery action

On battery: Do nothing

Plugged in: Do nothing

8.5. Software Upgrading (Optional)

Aurora advises the following when performing an upgrade or software change. Clients or users will be informed through email or by phone of the upgrade being made available and be given instructions of how to download the upgraded version from Aurora's FTP site or by mail.

To install or upgrade to a new version, please follow the instructions below:

- Backup all necessary sequences or assays by opening the current version. In the main interface screen, highlight the first assay you want backed up by clicking on the "file" drop down menu and clicking the 'export file' option. If you do not wish to keep the assays or sequences created, skip this step and proceed to step 3).
- 2) A new window will appear to confirm the location of the exported file. Click save and note the location of the backed-up assay file. Renaming can be performed once you import into the new software version.
- 3) Proceed then to rename the folder containing the current software in your PC. This is performed if you still want to keep the old version. If you do not wish to keep it, just delete without renaming. If you do not perform this step, the new version will attempt to save over the old and file types may conflict. Remember the location of the saved assay files if you want to still import them into the new software later.
- 4) Next, ensure that the new version is compatible to your workstation. Download the new software or install the received CD version into your PC. We strongly advise that you install the software into the same PC that came with the workstation.
- 5) After the installation procedure is completed, you may then want to import the files back into the new version by first adding an assay. Then by highlighting the created assay, right clicking and selecting 'import assay'. A new window will appear to prompt you to select the location of the .txt assay file previously saved. After locating the file, complete the import of data. Your old assays along with the sequences attached should now be imported.
- 6) You can now rename the assays. Sequence names should have remained from the previous version and shouldn't need renaming.

9. VERSA1100 Set up - Aurora Station

This chapter will discuss how to set up and teach positions using Aurora Station and VERSAware, and how to set up, calibrate and prime the tubes with wash buffer and/or reagent.



NOTE: Aurora Station usually runs alongside VERSAware. Do not attempt to close Aurora Station but instead minimize the interface. In case of closure, follow the steps below:



Figure 9-1 Shell Status

Shell Status

- 1) Open shell status window (*Figure 9-1 Shell Status*) (which runs alongside VERSAware), double click onto AS01 (1): 1564 and Aurora Station will reopen. Do not attempt to close shell status window whenever VERSAware is running.
- 2) Alternatively, under VERSAware tools, <click> onto the Aurora Station option to reopen the interface. To close, click again.

9.1. Robotic Arm Tab

This section will discuss how to set up and teach the robotic arm positions. Please start VERSAware 1100 software by selecting:

Start \rightarrow All Programs \rightarrow Aurora Biomed \rightarrow VERSAware1100

Switch to Aurora Station application by selecting the following menu option:

Tools \rightarrow Aurora Station

The Aurora Station software should appear on the screen. Switch to the 'Robotic Arm' tab Press the unlabeled button (*Figure 9-2 Initialize Button*) between X and Y-axes to initialize all axes of the robotic arm. The robotic arm should travel towards the upper left corner of the workstation.

Caution Please ensure there are no obstructions in the path of the robotic arm!!!



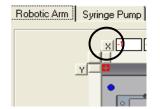


Figure 9-2 Initialize Button

Switch to the Robotic Arm tab(*Figure 9-3 Aurora Station Robotic Arm Control*). The Figure below explains how to control Aurora Arm. Use the scroll bars to control X, Y, Z-axes separately. The current arm coordinates will be displayed in text boxes in the upper left corner.

Every scroll bar shows the maximum range of this axis.

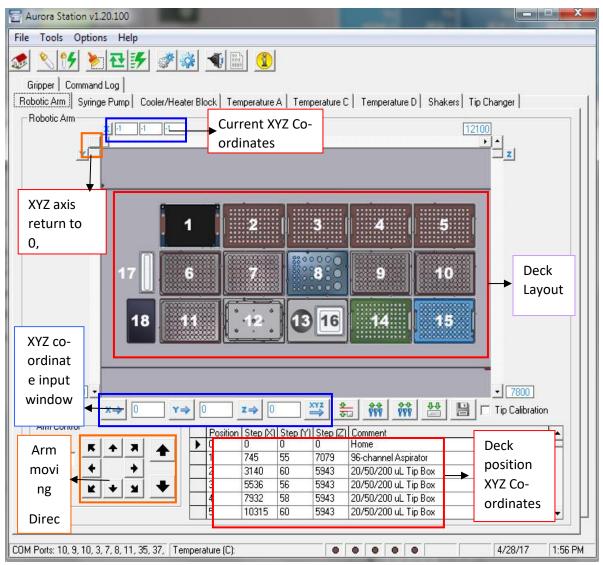


Figure 9-3 Aurora Station Robotic Arm Control



Aurora Station position teaching icons:

Click XYZ - $x \Rightarrow 6205$ $Y \Rightarrow 1986$ $z \Rightarrow 6104$ $x \Rightarrow --$ Arm will go to the loaded XYZ co-ordinates.

Click this icon Tip to pick tips from any tip box position on the deck to teach positions

After picking tips, Click this icon Test to test the any position on the deck

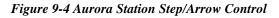
After teaching position, click on this icon Save Tip Calibration to save the position (check on Tip calibration)

This icon is used to calculate the XYZ off sets

Please use the scroll bars to control X, Y, Z-axes independently. The current robotic arm coordinates will be displayed in text boxes in the upper left corner. Each scroll bar shows the maximum travel range for this axis. X, Y, and Z buttons will initialize every individual axis. There are maximum ranges for X, Y, and Z coordinate – for e.g. for the Z axis, the maximum range is 60000 steps.

Another option to control the Aurora Arm would be to use the step/arrow control (*Figure 9-4 Aurora Station Step/Arrow Control*). Enter a step value from 1 to 1,000 and use one of the eight arrows on the left side to control horizontal X and Y-axes. Two arrows on the extreme right side will control vertical Z-axis.





VERSA 1100 workstation features 15 positions for various lab ware types, tips, blocks, tubes, reservoirs etc. Positions 16 & 17 are the waste & chute positions respectively. All the positions are taught with a 96 well plate(*Figure 9-5 Plate Teaching Positions*) accept reagent cooler block position which is taught as is. Once taught, the robotic arm will be automatically calibrated for liquid handling of all other plate types which are stored in the VERSAWare plate library.



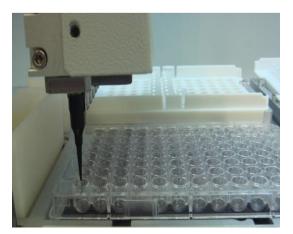


Figure 9-5 Plate Teaching Positions

In order to test previously saved default teaching positions; please double-click the record selector of the desired position as displayed in below Figure (*Figure 9-6 Aurora Station Teaching Positions*). The X, Y, Z-coordinates will be displayed in text boxes GoX, GoY, and GoZ. Next, <Click> on "Go XYZ" to have the arm move to the default position set by the manufacturer to confirm correct teach position has been set.

To recalibrate or teach a new plate type, click on the position you want to teach, place a 96-well plate on that position on the deck, set the step (Z) coordinate to "0" and press "Go XYZ". If the XY positions are right, click the down arrow until desired Z position is reached. Please note to reduce the steps of the arm control to 5 or 10 for more precise and safe control of arm movement. Once syringe barrel (w/o tip) is close to the top left corner first well of the 96 well plate, correct position is taught or determined by passing through a paper in between the 96-well plate and the barrel tip barely touching it.

Similarly check for all other positions. Adjust the other positions if necessary and save the new coordinates.

| GoX 0 GoY | 40 | Go | Z 0 | Go > | (YZ Of | fset Tip Test Save 🗖 Tip Ca | alibration |
|-------------------|----|----------|----------|----------|----------|-----------------------------|------------|
| Arm Control | | Position | Step (X) | Step (Y) | Step (Z) | Comment | • |
| Step | | 16 | 1000 | 1000 | 3000 | Priming Position | |
| | | 17 | 30 | 1370 | 6000 | Waste Position | 1 |
| + + | | 18 | 0 | 2550 | 5000 | The Chute | 1 |
| 🔽 No Z Up 😰 🛨 🛨 🛨 | | 100 | 8794 | 2652 | 7184 | | 1 |
| | Ð | ¥ | | | | | |

Figure 9-6 Aurora Station Teaching Positions

Gaution Inaccurate robotic arm positions may cause damage to liquid handling head and tip barrels!!



9.2. Teaching Positions

The VERSA 1100 Workstation uses a standard 96-well plate for teaching all positions except the Reagent Cooler Block. Only the reagent block, chute and waste positions are taught as as shown below. All other positions should be taught on the surface of the upper left well of the standard 96-well micro-plate as shown in the figures below.

Initialize the robotic arm by pressing the button between X and Y-axes (Robotic Arm tab). The top left well A1 (column 1, row 1) should be taught on the surface of the plate. Move the arm towards you and manually (with your hands) engage a 20 μ L tip to barrel # 1(outer one).

This tip can be clear or black liquid level sensing tip if available. Place a small sheet of paper (~4 x 4 mm) on top of the 96-well plate. Move the arm down to slightly touch this sheet of paper with the tip as shown in *Figure 9-6 Aurora Station Teaching Positions*. Remove the sheet of paper and align the arm in the center of the well (X and Y-axes) without changing Z-axis.





Figure 9-7 Aurora Station Chute Position Teaching Figure 9-8 Aurora Station Waste Position Teaching

Open the position to be taught by double clicking from AS e.g. position # 6 (*Figure 9-9 Aurora Station- Position Teaching for # 6 deck position*). Make the Z co-ordinate 0 and then click 'Test'. The arm will execute the command and go to position # 6 but very high as Z is set zero.

The 20μ L tip should be positioned exactly on the surface level of the extreme left row of the standard 96-well micro-plate and positioned at the centre of each well (X-axis & Y-axis alignment).

For verification of z-axis positioning, a piece of paper can be placed in between the tip and the well of the 96-well micro-plate (*Figure 9-10 96-well Micro-plate Teaching Position*). Fine adjustment is done by commanding the z-axis robotic arm in descending movement till the



barrel tips just touching the surface of the paper (*Figure 9-11 96-well Micro-plate Teaching Position*).

Slight resistance is felt when inserting or removing the paper. After setting all the co-ordinates to make the tip in the center of the wells, save this position by clicking 'Tip Calibration' as shown in *Figure 9-12 Aurora Station- Saving Position*.

Teach all other position same way.

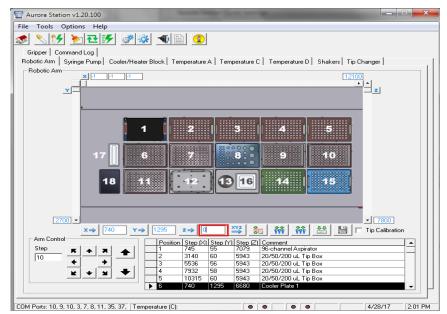


Figure 9-9 Aurora Station- Position Teaching for # 6 deck position

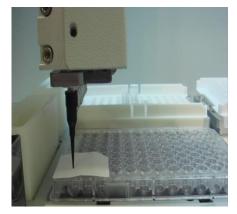
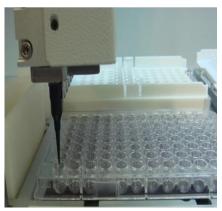


Figure 9-10 96-well Micro-plate Teaching Position Figure 9-11 96-well Micro-plate Teaching Position







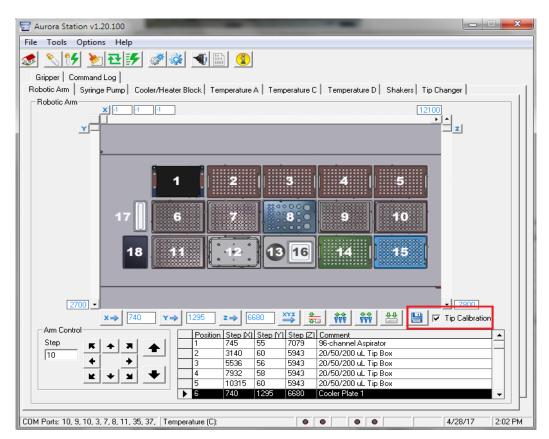


Figure 9-12 Aurora Station- Saving Position

In the VERSAware software interface, drag the 20ul tip box on to the deck (e.g. position # 2), put one 20ul tip in this box (A1 well), click that position from AS & click tip. Arm will go to position # 2 to pick the tips or tip.

Double click the cooler block position, make Z co-ordinate zero, and click 'Test'. Arm will go to T1 column of the block, adjust X Y Z co-ordinates to position the tip on the surface and the centre of the tube as shown in *Figure 9-13 Aurora Station- Picking 20ul tip from position #2*.

The z-axis height position can be checked with a piece of paper in such a way that it can pass under the tip with slight resistance. After adjusting it in the center of the T1 tube, save the position by clicking 'Tip Calibration'.



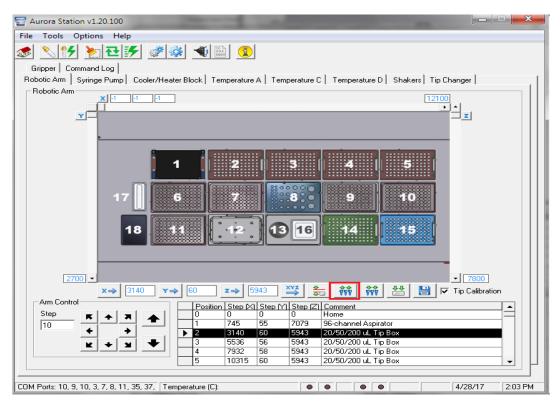


Figure 9-13 Aurora Station- Picking 20ul tip from position #2

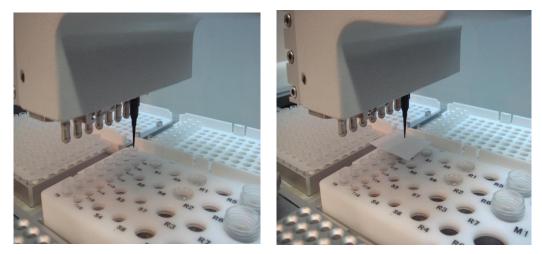


Figure 9-14 Reagent Cooler Block Teaching Position Figure 9-15 Reagent Cooler Block Teaching Position

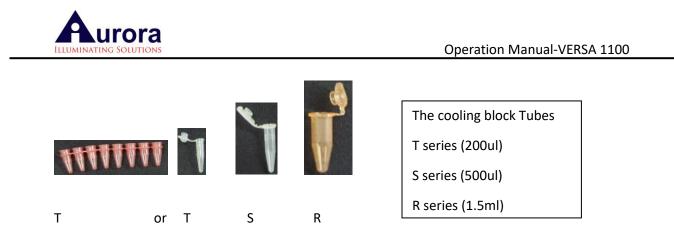


Figure 9-16 Reagent Cooler Block Tubes

Once you are done teaching the positions for the 8-Channel Head, the system is ready to run the application tabs.

Vacuum Positions: These positions (Filter & Receiver) are taught on the surface of the filter plate on top of both positions (Filter & Receiver positions) as shown in Figure 9-17 Vacuum Wash & Sample Collection Positions.



Figure 9-17 Vacuum Wash & Sample Collection Positions

9.3. Testing New and Default Plate Types

Aurora Station allows you to test previously or newly taught positions for all lab-ware types. It is a good practice to test positions periodically to ensure that the arm calibrated for a particular plate type and position is still intact.

To test any position on the deck, enter Aurora Station settings and <click> on the Advanced Options tab as depicted below (*Figure 9-18 Aurora Station Settings Main Interface – Advanced Settings Tab*). Next, on the bottom left corner of the interface screen, select the position to test. After which you'd want to select the plate type or some other listed lab-ware to test on that position. <Click> onto the Plate Type settings tab and select for a listed plate type by highlighting the selection.



| Tip Engagement [Robotic Arm] | Shaker | Syringe Pump |
|--|-------------------------------------|--|
| Start Speed (step/s) 50 | Start Speed (step/s) 100 | Pump Connected to Arm |
| End Speed (step/s) 500 | Acceleration (step/s ²) | Pump Device 0 |
| Acceleration (step/s ²) | | Device Address (hex) 31 |
| | Communication | |
| Cooler/Heater Block | Step Loss Error Count 10 | Positions [Exclude X, Y, Z-Offset] |
| Cooler: Address 1 💌 Channel 1 💌 | Time Out Error Count 10 | Position ▶ 13 |
| Position 14 - Reagent Cooler Block 💌 | 1st Time Out (s) 60 | * |
| Heater: Address 1 🗸 Channel 2 🗸 | 2nd Time Out (s) 240 | Chute Orientation |
| Position 12 - Heater Shaker/96-deep Well Plate 🔻 | Command Delay (ms) 100 | • Y-Axis C X-Axis |
| Temperature Control Delay (ms) 10000 | Arm Address (hex) 31 | |
| Temperature control Peray (ins) | Device Address (hex) 38 | PI Auto Recovery Remove from Initialization |
| Source Temperature A | Cooler Time Out (s) 90 | Double PI Auto Recovery |
| Source 1: Address 1 - Channel 1 - | Auto Recovery | |
| Position 7 - Cooler Plate 1 | X-Offset (step) 2400 | Syringe Pump |
| Source 2: Address 1 Channel 2 | | 🔲 100 uL Small Syringe Pump |
| Position 8 - Cooler Block | Tip Disengagement | 250 uL Small Syringe Pump |
| | Y-Offset (step) 800 | 🔲 Small Syringe Pump Only |
| Test Position [Plate Type] | Plate Type [Teaching Positions] | Position Test Mode |
| Position 10 - Source/Target Plate | Plate Type 1 - 96-well Plate 💌 | 🔲 Single Channel Test |

Figure 9-18 Aurora Station Settings Main Interface – Advanced Settings Tab

To pick up a 200μ L Tip for teaching position verification, ensure you have selected Single-Channel operation mode, and then go to the Aurora Station main screen to select position (for this example we will use position 15.

To let the software know that you have a full tip-box you must "reload the tip boxes" by dragging and dropping the correct size of tip box in the software to the location where it exists on the deck (*Figure 9-19 Aurora Station –Reload Tip Box*). In the VERSA1100 main interface menu, drag 200 Tip (1) representing single channel 200µL Tip Box to position 15. Or under Reload Tip Boxes mode, drag 200Tip (1) to position 15.



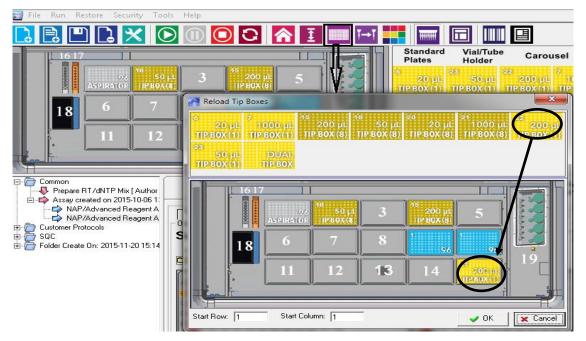


Figure 9-19 Aurora Station –Reload Tip Box

To ask the software to pick up a single tip, in single channel mode simply click Tip. The robotic arm will execute the command to pick up the extreme top left corner tip(*Figure 9-20 Aurora Station –Pick Tip*). Black tips have been used in this example(*Figure 9-21 Aurora Station –Picking Tip*) for better photo illustration, however clear tips can also be used to check positions.

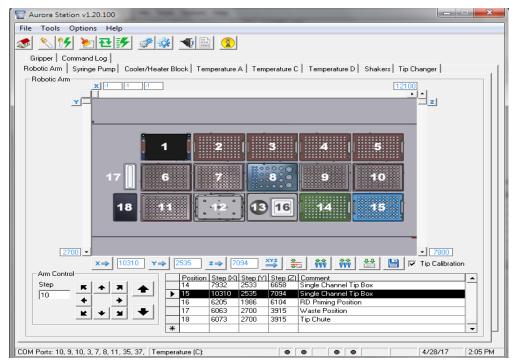


Figure 9-20 Aurora Station –Pick Tip



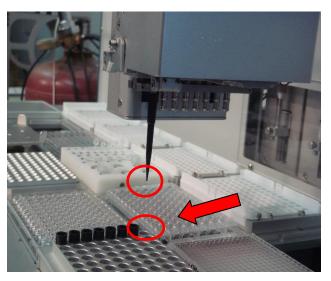


Figure 9-21 Aurora Station –Picking Tip

In Aurora Station Settings, all the parameters for various plates are tabulated as shown below (*Figure 9-22 Aurora Station Settings Main Interface – Plate Types Settings Tab*) and these settings are used for verification and fine adjustment of position.

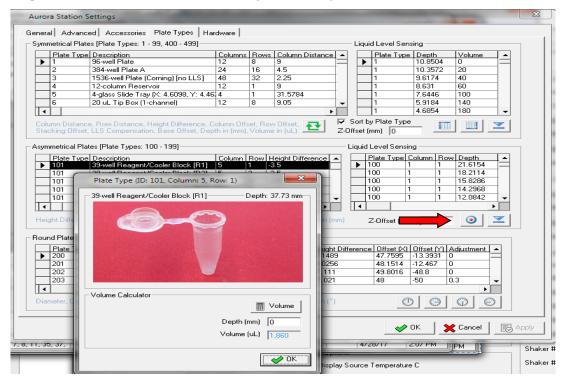


Figure 9-22 Aurora Station Settings Main Interface – Plate Types Settings Tab

To select a plate type: (in this example a 39-well Reagent/Cooler Block is used) double click to highlight the desired position (highlighted in black) as shown in the above screen shot (*Figure 9-22 Aurora Station Settings Main Interface – Plate Types Settings Tab*). Press the centre



position icon (test button red arrow) & the arm will go to T1 position of the reagent cooler block. Check if the tip is in the center of T1 position tube, (shown below, *Figure 9-23 39 Well Reagent cooler Block-Testing T1 Position*)



Figure 9-23 39 Well Reagent cooler Block-Testing T1 Position

Likewise, you can perform other location verification such as W position.

Scroll down the table to select Plate type 101: 39-well Reagent/Cooler Block (W).

Press the centre position icon to verify its position.

If you find that the tip is away from the centre position, it may have a significant impact on application (like tip hitting the wall of the vial), it can be re-align the tip back to the centre position by adjusting the Column (X-axis) Offset and Row (Y-axis) Offset accordingly.

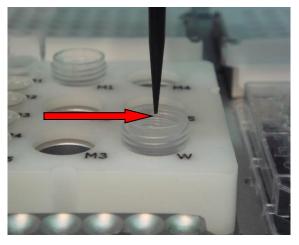


Figure 9-24 39 Well Reagent cooler Block-Testing W Position

In the above photo illustration (*Figure 9-24 39 Well Reagent cooler Block-Testing W Position*), the tip is slightly offset to the left away from the centre position. By adding a small positive value increment say +0.1 to the existing column offset value, followed by clicking the centre position tab(*Figure 9-25 Test position*), the robotic arm will move towards the centre in the X-axis direction. Once finalized, the Column offset value can be adopted for the holes M4 and M5 which are located in the same column.



| Asyn | nmetrical Plates [Plate Types: 100 - 199 Description | | Bow | Height Difference | Column Offs | _ | | d Level Sens Plate Type | - | Bow | Denth | |
|------|---|------------|-------|--------------------|-----------------|---|---|----------------------------|---|-----|---------|---|
| | 39-well Reagent/Cooler Block [R1] | 5 | 1 | -3.5 | 49 | | ▶ | 100 | 1 | | 21.6154 | |
| | 39-well Reagent/Cooler Block [R2] | 5 | 2 | -3.5 | 49 | | | 100 | 1 | 1 | 18.2114 | 1 |
| | 39-well Reagent/Cooler Block [R3] | 5 | 3 | -3.5 | 49 | | | 100 | 1 | 1 | 15.8286 | 1 |
| • | 39-well Reagent/Cooler Block [R4] | 5 | | -3.5 | 49 | | | 100 | 1 | 1 | 14.2968 | 1 |
| | 39-well Reagent/Cooler Block [R5] | 5 | 5 | -3.5 | 49 🗖 | | | 100 | 1 | 1 | 12.0842 | - |
| 1 | | | | | • | | • | | | | | |
| | ght Difference, Column Offset, Row Off | Frank LL S | Compe | anestion Rase Offe | et. Denth in (m | | | 7.0% | | | | ~ |

Figure 9-25 Test position

In general, the same methodology is adopted to verify and fine-tune all the other plate types and accessories in terms of height offset, column offset and row offset.

9.4. Reagent Drop Pin Position Teaching

This section will give the details to teach/check reagent drop pin position for 96 well plate.

Put the 96 position teaching plate on any position from 11-15 on the deck.

Open Aurora station from Tools>Open Settings>Advanced, and select the test position (the location where you put the plate) e.g. position 12 in figure.

Open accessories tab from Aurora Station settings (*Figure 9-26 Reagent Drop pin position testing-test position selection*), check the pin group, highlight the XYZ coordinates (double click) & click RD Test.

The arm will go to position 15 & align the reagent drop pin on the surface of the A1 well of the 96 well plate. To check if the pin is in the center of the well, try dispensing some solution e.g. 100ul manually using PWM pump in C mode (*Figure 9-27 Reagent Drop pin position testing-Accessories*) & watch the pin while its dispensing, if the pin is not dispensing in the center of the well, otherwise change the X (more negative value of X offset moves the pin/arm to left side of the well relative to the standard position of the A1 well of the plate—increase/decrease it to align in the center of the well) & Y (more negative value of Y offsets moves the pin/arm/ backward) change it to align the pin in the center of the well.

Likewise, you can perform other pins position testing/verification (Figure 9-28 PWM pump-Dispense 100ul volume-Pin # 1).



| General Advanced Accessories Plate Types Hardw. | | 8 : B |
|--|--|-------------------------------------|
| Tip Engagement [Robotic Arm] | Shaker | Syringe Pump |
| Start Speed (step/s) 50 | Start Speed (step/s) 100 | Pump Connected to Arm |
| End Speed (step/s) 500 | Acceleration (step/s ²) 10 | Pump Device 0 |
| Acceleration (step/s ²) | | Device Address (hex) 31 |
| | Communication | |
| Cooler/Heater Block | Step Loss Error Count 10 | Positions [Exclude X, Y, Z-Offsets] |
| Cooler: Address 1 💌 Channel 1 💌 | Time Out Error Count 10 | Position ▶ 13 |
| Position 10 - Source/Target Plate 💌 | 1st Time Out (s) 60 | 16 |
| Heater: Address 1 🗸 Channel 2 🗸 | 2nd Time Out (s) 240 | Chute Orientation |
| Position 12 - Heater Shaker/96-deep Well Plate 🔻 | Command Delay (ms) 100 | |
| , | Arm Address (hex) 31 | |
| Temperature Control Delay (ms) 10000 | Device Address (hex) 38 | PI Auto Recovery |
| - Source Temperature A | Cooler Time Out (s) 90 | Remove from Initialization |
| | | Double PI Auto Recovery |
| | Auto Recovery | Syringe Pump |
| Position 7 - Cooler Plate 2 | X-Offset (step) 2400 | 🔲 100 uL Small Syringe Pump |
| Source 2: Address 1 Channel 2 | Tip Disengagement | ✓ 250 uL Small Syringe Pump |
| Position 8 - Reagent/Cooler Block | Y-Offset (step) 800 | Small Syringe Pump Only |
| | | |
| Test Position [Plate Type] | Plate Type [Teaching Positions] | Position Test Mode |
| Position 12 - Heater Shaker/96-deep Well Plat. | Plate Type 1 - 96-well Plate 💌 | Single Channel Test |
| | | |

Figure 9-26 Reagent Drop pin position testing-test position selection

| 🐨 Aurora Station v1.20.100 | Aurora Station Settings | |
|--|---|--|
| File Tools Options Help | General Advanced Accessories Plate Types Hardware | |
| Gripper Command Log Robotic Arm Syringe Pump Cooler/Heater Robotic Arm | 3 4 18 1 1 1 4 2 21 1 1 1 1 5 2 21 1 1 1 1 | Column 5 Column 6 Column 7 Column 8 Column 9 ▲ 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 ▼ ▼ |
| 1 17 18 1 1 | Pipeting Tip Types Tip Type Description Tip Box Type Engagement Offset Disengagement 1 20 uL Tps (8-channel) 6 12 1 20 uL Tps (8-channel) 6 12 1 20 uL Tps (8-channel) 88 6 12 2 1000 uL Tps (8-channel) 7 6 12 2 1000 uL Tps (8-channel) 85 6 12 2 1000 uL Tps (8-channel) 85 6 12 I 100 uL Tps (8-channel) 85 6 12 | ent Offset Engagement Depth Tip Length Offset M ▲ 12 31.74 0 11 31.74 0 13.95.82 1 13 95.82 1 8.5 95.82 0 ↓ et (') in (mm) |
| 2700 - x → 10310 Y → Arm Control Step 10 ↓ ↓ ↓ ↓ ↓ | Pin Group Description Offset PXI Offset PXI Offset PXI Offset PXI Fin Science Science <thscience< th=""> <thscience< th=""> Sci</thscience<></thscience<> | 900 |
| COM Ports: 10, 9, 10, 3, 7, 8, 11, 35, 37, Temp. | | 🖌 OK 🛛 🔀 Cancel 🛛 🔂 Apply |

Figure 9-27 Reagent Drop pin position testing-Accessories



| 😭 PWM Pump v4.1 | .0.7 - 5-chan | nel | D - | - | | | |
|-----------------|---------------|---|--------------|---|--|-------|---------|
| File Tools Opti | one Help | | | | | | |
| | 1 단 🕸 | N 1 | | | | | |
| F Initialize | • | 🕽 Time: | FF | Purge Po | sition: 1 | | A Move |
| Valves | | | | | | | |
| Valves Liquid | Handling W | 'ash | | | | | |
| Volumes (uL): | 1 2 3 | Volume Delay (100 63,804 0 0 0 0 0 0 0 0 0 0 0 0 0 0 | | eat Cycles: Aspiration Aspirate Dispense Pressure | 1 Dispensing 5 7 7 7 7 7 7 7 7 7 7 | | |
| | | | | | | | |
| | | | | | | * * | Clear |
| Sent/Received | | | | | | | |
| | | | | * | | | Clear |
| | | | | ^ | | | |
| | | | | - | | | |
| | | | | | | | |
| | | | | ^ | | | |
|] | | | | ~ | | | |
| | | | | ~ | | | |
| | | | | - | | Ŧ | |
| COM Ports: 8, 7 | Valves: 5 | Status: Idle | Control Mode | Pressure: | 4/2 | 28/17 | 2:15 PM |





| PWM Pump v4.1 | 10.7 - 5-char | nel | E | - | | - 🗆 🗙 |
|-----------------|-----------------|--|--------------|---|------------|------------|
| File Tools Opti | ons Help | | | | | |
| | 전 🔅 | × 1 | | | | |
| 🤧 Initialize | (| Time: | ۴ | Purge Po | sition: 1 | A Move |
| -Valves | | | | | | |
| Valves Liquid | Handling W | /ash | | | | |
| Volumes (uL): | Valve 1 2 3 4 5 | Volume Delay 0 0 100 0 0 0 0 0 0 0 0 0 0 0 0 0 | | eat Cycles: Aspiration (Aspirate Dispense Pressure | Dispensing | ŧ |
| Log | | | | | | |
| | | | | | ^ | Near 📎 |
| Sent/Received— | | | | | | |
| | | | | A | * | ≽ Clear |
| | | | | - | - | 🚮 Graph |
| | | | | | * | |
| | | | | - | | |
| | | | | <u> </u> | | |
| | | | | - | | |
| | | | | | | |
| | | | | Â | | |
| 1 | | | | T | * | |
| COM Ports: 8, 7 | Valves: 5 | Status: Idle | Control Mode | Pressure: | 4/28/ | 17 2:16 PM |

Figure 9-29 PWM pump-Dispense 100ul volume-Pin # 2

After all the pin positions are tested and you have verified that these are correct, set the reagent drop Z offset before creating sequences in VERSAware.

Open OPTIONS from Tools>Reagent Drop and change the Z off set setting (more negative value move the arm up & positive value move the arm down). You can also change the priming volume for reagent drop (*Figure 9-30 Reagent Drop-Z-offset*)



| [Sequence] NAP/Advanced Reagent | Addition created on 2015-11-30 12:20:24 | |
|--|---|-----------|
| Air Gap Settings Syringe Pump Tip Boxes Plate Types Reagent Drop Priming | Reagent Drop Other General VarRef Arm Movements Pump Speeds | Arm Speed |
| neagent of op Filming | Volume (μL) 1(| Ī |
| Reagent Drop Z-Offset | | |
| | Dispensing Z-Offset (mm) | 3 |
| ReagentDrop Time Delay | ReagentDrop Time Delay (ms) | ō |
| | ·····g································ | |
| | | |
| | | |
| | | |
| | | |
| | | |
| | | |
| | | |
| | | |
| | | |
| | | |
| | | |
| | | |
| | | |
| | | |
| Restore 🎒 Default | 💼 Export 🛛 🏨 Import 🔹 😭 Apply 🛛 🗸 OK | 🗙 Cancel |

Figure 9-30 Reagent Drop-Z-offset



9.5. Reagent Drop Calibration (PWM PUMP)

Note: Calibration of the PWM pump is recommended in case a different reagent is being used which may affect the pressure setting or use multiple table calibration mode

PWM Pump interface is used for calibration. To open the interface window, follow the steps below:

| 🕵 Shell Status | |
|----------------|--|
| Task ID | |
| AS01 [1]: 3092 | |
| DH01 [1]: 584 | |
| VW01 | |
| | |
| | |

Shell Status

- Open shell status window (which runs alongside VERSAware), double click onto DH01 (1):584 and PWM Pump interface will open. Do not attempt to close shell status window whenever VERSAware is running.
- 2) Alternatively, under VERSAware tools, click onto the Aurora PWM Pump option to reopen the interface. To close, click again.



| PWM Pump v4.1 | 10.7 - 5-channel | | - | - | | | |
|-------------------------|--|---------------------------------------|--------------|--|---|-----|-------------|
| File Tools Optio | ons Help | | | | | | |
| | 1 관 🔅 ९ | | | | | | |
| 🗲 Initialize | 0 | Time: | € P | 'urge Posit | ion: 1 | | Move |
| Valves Valves Liquid | Handling Wash | n] | | | | | |
| Volumes (uL.): | Valve Vo 1 0 2 100 3 0 4 0 5 0 | lume Delay (0 0 0 0 0 | | eat Cycles: 1 Aspiration (* Aspirate) Dispense) Pressure) | Dispensing 5 5 7 7 F Apply | Ū | |
| Log | | | | | - | | Clear |
| Sent/Received | | | | | | | |
| | | | | * | - | | Clear Graph |
| | | | | ^ | - | | <u> </u> |
| | | | | * * | | | |
| | | | | * | | | |
| | | | | ÷ | - | - | |
| COM Ports: 8, 7 | Valves: 5 St | atus: Idle | Control Mode | Pressure: | 4/28 | /17 | 2:18 PM |

Figure 9-31 PWM Pump Calibration Mode

To change pressure in PWM Pump, click onto the "C" button **G** to switch to pump control mode (*Figure 9-31 PWM Pump Calibration Mode*).

When pump is operational, pressure can be observed by clicking the chart tab (bottom right of interface).

A graphical pressure curve in real-time appears which shows the user the current pressure maintained.

If changes are needed, open PWM settings from settings icon as shown below(*Figure 9-32 PWM Pump-Settings*). Change the pressure setting (if the pressure setting is lower than before, please release pressure manually by pulling the pressure tubing from priming bottle) and click OK, apply and close this window.



| PWM Pump v4.10.7 - 5-channel | PWM Pump Settings | × |
|----------------------------------|---|--------------|
| File Tools Options Help | Application | |
| | Title: 5-channel Device ID | DH01 |
| | VERSA Type: 4 - VERSA 1100A 🗾 Log Lines | 500 |
| 🌠 Initialize | Display Communication 🔽 Reset PWM Pump Error Records | 1,000 |
| | 🔽 Display Log 🔽 Resend Command 🔽 Compact I | Database |
| Valves | PWM Pump Liquid Handling | |
| Valves Liquid Handling Wash | 1st COM Port [Nanopipettor]: B Max Aspiration Volume (uL) | 350 |
| Volumes (uL): Valve Volume | 2nd COM Port [ReagentDrop]: 0 Max Dispensing Volume (uL) | 20,000 |
| | 3rd COM Port [Pressure/Vacuum]: 7 Wash Position | : 11 |
| | Number of Valves: 5 Purge Position | 16 |
| | Number of Lanes: 1 Buffer Position | 11 |
| | Number of Channels: 12 Robotic Arm | |
| 1 | 1 st Lane No: 1 Robotic Arm ID | AS01 |
| | 2nd Lane No: 21 Robotic Arm No | : 1 |
| Log | Min Delay (us): 0 Aspiration Z-Offset (step) | 1050 |
| | Max Delay (us): 65,535 Dispensing Z-Offset (step) | -200 |
| | Demo Interval (ms): 500 Initialization Delay (ms) | 500 |
| I | Spike Pulse (us): 250 Movement Delay (ms) | : 1 |
| Sent/Received | Pulse Interval (ms): 0 Purge Z-Offset (mm) | -5 |
| | Running Delay (ms): 0 Safe Z-Offset (mm) | 80 |
| | Response Interval (ms): 2,000 Liquid Handling Delay (ms) | 500 |
| | Pressure (psi): 12 | |
| | Vacuum (psi): 3 Read USB Se | rial Numbers |
| | Pulse Interval (ms) [Purge]: 0 Pin Groups | |
| | Valve Pin Group | 📷 Default |
| | Default Mode Serial Numbers 1 12 | 🤣 ОК |
| | Sector Assay Mode 1st: FTVP2TG1A 3 14 | X Cancel |
| | C Control Mode 3rd: FTVP2TG1B 4 15 5 16 | |
| COM Ports: 8, 7 Valves: 5 Status | | Apply Apply |

Figure 9-32 PWM Pump-Settings

| To set the new pressure setting, go to main interface and click the initialize button | |
|--|---|
| then click the "pressure" button Fressure to change settings as shown below (Figure 9-33 | ; |
| PWM Pump- New Pressure settings). | |



Operation Manual-VERSA 1100

| PWM Pump v4.10.7 - 5-channel | | | |
|---|------------------|---|----------------------|
| File Tools Options Help | | | |
| | | | |
| Time: | F | ^D urge Position | n: 1 Move |
| Valves Valves Liquid Handling Wash | | | |
| Volumes (uL): Valve Volume Dela 0 1 0 0 2 100 0 ▲ 0 0 ▲ 0 0 ● 3 0 0 ● 3 0 0 ● 5 0 0 | | eat Cycles: 1 Aspiration © D Aspirate Dispense Pressure | ispensing |
| | | | |
| | | | Clear |
| Sent/Received | | | |
| | | * | 🔶 Clear |
| | | - | 👻 📶 Graph |
| | | * | * |
| | | - | |
| | | <u> </u> | |
| | | - | |
| | | | |
| | | | |
| | | * | Ŧ |
| COM Ports: 8, 7 Valves: 5 Status: Idle | Control Mode | Pressure: | 4/28/17 2:18 PM |
| Figure 9-33 PWA | M Pump- New Pr | essure settings | |
| Open valves mode using the " | valves" button | Valves | |
| Initialize the pump using the i | nitialize button | 😽 Initialize | |
| Click the syringe button calibration in micro-seconds (| | ches the pump | o into pulse mode of |
| Open calibration data table by pin # 1. You can choose to sta | | | |
| | | | |



e.g. Add pulse value 50000, repeat cycles 10 as shown in *Figure 9-35 Add pulse & repeat cycle*, switch to pin # 2 (add 0 value for all other 4 pins) apply, dispense (new reagent or with new pressure setting) in a pre-tared weighing boat to check weight on a balance or in a tube to check the volume with a pipettor. Add this new weight/volume value in the calibration table & switch records to add the new volume/weight as shown in *Figure 9-36 Add new volume/weight value*. This way, check all the pulse values & repeat cycles which are there in the table like up to 30000 & keep adding the new weight values in the table. This is just repeating the table pulse time & cycles with new reagent or pressure setting as with pressure & different reagent weights/volumes change.

- In case, user want to add new data point e.g. 50000 pulse & 9 cycles. Check the weight by adding new # of cycles & add the new data point as shown in *Figure 9-37* Adding new data point in the calibration table
- Similarly, calibrate other pins & keep adding weight values in the calibration table for pin # 2, 3, 4 and 5.

| PWM Pump v4.10.7 - 5-channel | |
|--|---------------|
| File Tools Options Help | |
| | |
| Time: Fridalize Position: 1 | A Move |
| Valves Valves Liquid Handling Wash | |
| Volumes (uL): Valve Volume Delay (us) Repeat Cycles: 1 0 2 0 | |
| Log | |
| 2:27:36 PM Pump_Initialize 8 7 | Clear |
| Sent/Received | |
| | 🔺 ≽ Clear |
| | - Graph |
| | A |
| - | |
| | |
| - | |
| | |
| Į į | - |
| COM Ports: 8, 7 Valves: 5 Status: Idle Control Mode 4/ | 28/17 2:27 PM |

Figure 9-34 PWM Pump in Pulse mode of calibration



Operation Manual-VERSA 1100

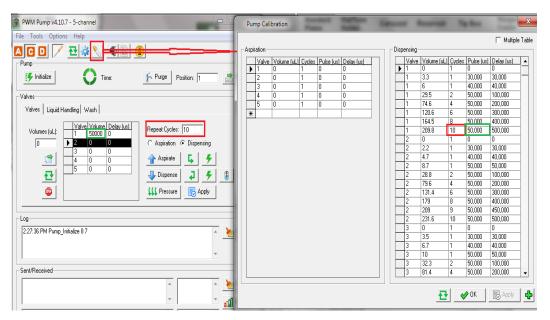


Figure 9-35 Add pulse & repeat cycle

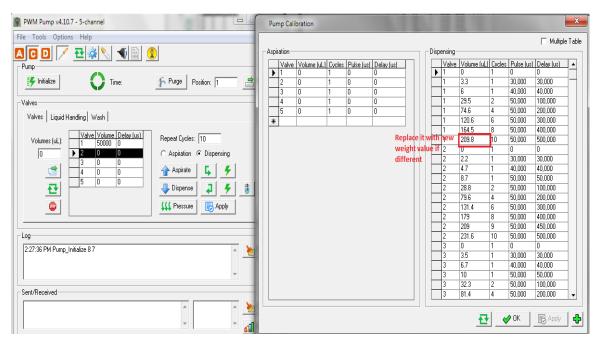


Figure 9-36 Add new volume/weight value



Operation Manual-VERSA 1100

| PWM Pump v4.10.7 - 5-channel | Pump Calibration |
|---|---|
| File Tools Options Help | CAsoiration |
| Image: Constraint of the second se | Aspiration Dispensing Valve Volume (uk) Cycles Pulse (us) Delay (us) 3 81.4 4 50.000 200.000 2 0 1 0 0 3 131.2 6 50.000 200.000 3 0.1 0 0 3 181.4 4 50.000 200.000 4 0 1 0 0 3 181.2 6 50.000 900.000 3 131.2 6 50.000 900.000 3 233 10 50.000 900.000 4 3.8 1 30.000 4 0 1 0 0 4 3.8 1 30.000 100.000 4 32.1 2 50.000 100.000 4 4 33.8 6 50.000 100.000 4 4 133.8 6 50.000 200.000 4 4 38.5 10 50.000 50.000 |
| - Sent/Received | Adding New data point 15, 252 1 10, 50,000 500,000 |
| Î Î | 🔂 🥓 OK 🗾 🔂 Apply |

Figure 9-37 Adding new data point in the calibration table

| PWM Pump v4.10.7 - 5-channel | Pump Calibration | Sandard Spillules | Serent 1 | Real To | × |
|--|------------------|---|--|--|--|
| File Tools Options Help Image: Second state st | | e (us) Delay (us) 0 0 0 0 0 0 | Dispensing Valve Volume (r 1 0 1 3.3 1 6 1 295 1 74.6 1 1206 1 1206 1 1206 1 164.5 2 0 2 2.2 2 4.7 2 8.7 2 8.7 2 8.7 2 8.7 2 131.4 2 179 2 209 2 231.6 3 0 3 3.55 3 6.7 3 10 3 3.55 3 6.7 3 10 | UL Cycles Putse [us] 1 0 1 30,000 2 50,000 4 50,000 4 50,000 8 50,000 9 50,000 10 30,000 11 30,000 12 50,000 13 50,000 14 50,000 15 50,000 16 50,000 1 50,000 2 50,000 4 50,000 1 50,000 1 50,000 1 0 1 0 1 0 1 0 1 0 1 0 1 30,000 1 1 1 1 1 1 1 1 1 1 1 1 1 <th>Multiple Table Delaw (us) ▲ 0 30,000 40,000 ▲ 200,000 30,000 400,000 ▲ 30,000 ↓ 0 30,000 400,000 ▲ 0 30,000 400,000 ▲ 200,000 ▲ 30,000 ↓ 40,000 ↓ 200,000 ↓ 30,000 ↓ 100,000 ↓ 100,000 ↓ 100,000 ↓ 100,000 ↓ 100,000 ↓ 100,000 ↓ 100,000 ↓ 100,000 ↓ 100,000 ↓</th> | Multiple Table Delaw (us) ▲ 0 30,000 40,000 ▲ 200,000 30,000 400,000 ▲ 30,000 ↓ 0 30,000 400,000 ▲ 0 30,000 400,000 ▲ 200,000 ▲ 30,000 ↓ 40,000 ↓ 200,000 ↓ 30,000 ↓ 100,000 ↓ 100,000 ↓ 100,000 ↓ 100,000 ↓ 100,000 ↓ 100,000 ↓ 100,000 ↓ 100,000 ↓ 100,000 ↓ |
| · · · · · · · · · · · · · · · · · · · | | | 1 | | EQ where T |

Figure 9-38 New data point in the calibration table for channel #1



| Valve Volume [uL] Cycles Pulse [us] Delay [us] ▶ 1 0 0 0 2 0 1 0 0 | Dispensing | Multiple Table | |
|--|---|----------------|--------------------|
| 3 0 1 0 0 4 0 1 0 0 5 0 1 0 0 ★ | 2 79.6 4 50.000 2 2 131.4 6 50.000 3 2 173 8 50.000 4 2 203 9 50.000 4 2 203.6 10 50.000 5 3 0 1 0 0 3 3.5 1 30.000 3 3 6.7 1 40.000 4 3 10 1 50.000 3 3 13.2 2 50.000 1 3 131.2 6 50.000 3 3 182 8 50.000 4 3 233 10 50.000 3 4 0 1 0 0 4 3.8 1 30.000 3 4 9.9 1 50.000 3 4 9.3 2 50.000 1 | 100,000 | Graph (Dispensing) |

Figure 9-39 Checking data in a graph

• After the calibration is finished, you can check different volumes for accuracy.

Switch to volume mode by clicking the syringe icon again and it will appear

unclicked \checkmark . Then you can add 100µL volume for valve 1 (Pin 1) & repeat 1 cycle. You can then switch to valve 2 as shown in figure 42 & then dispense in a pre-tared weighing boat & check the volume on a balance or with pipettor. Similarly, other volumes within the range of the calibration table/data can be checked.(*Figure 9-40 Testing volumes*)



| PWM Pump v4.10.7 | - 5-channel | | |
|----------------------|--|--|----------------------|
| File Tools Options | Help | | |
| | ₴ 💸 🔪 📲 🖺 | | |
| 🧲 Initialize | Time: | Frage Position: 1 | Move |
| Valves | | | |
| Valves Liquid Han | dling Wash | | |
| Volumes (uL): | Xelve Yelves Delay for 1 100 0 2 0 0 3 0 0 4 0 0 5 0 0 | Repeat Cycles: 1 Aspiration © Disper Aspirate 5 Dispense 2 Support Pressure 6 Aspirate 6 Comparison (Comparison (Compari | 7 7 |
| Log | | | |
| 2:27:36 PM Pump_Init | ialize 8 7 | | Clear |
| Sent/Received | | | |
| | | * | 🔺 ≽ Clear |
| | | - | |
| | | | Graph |
| | | <u>^</u> | ~ |
| | | ~ | |
| | | * | |
| | | - | |
| | | <u>^</u> | |
| | | - | - |
| COM Ports: 8, 7 Va | alves: 5 Status: Idle | Control Mode | 4/28/17 2:42 PM |

Figure 9-40 Testing volumes

User can also calibrate reagent drop pins for different reagents/solvents (ethanol, DMSO etc.) by using multiple table option, whenever, there is switch to different reagent—use that particular calibration table as shown in *Figure 9-41 Multiple table option* below.

| PWM Pump v4.10.7 - 5-channel | Pump Calibration | 3 |
|--|---|-----|
| File Tools Options Help Image: Constraint of the second se | Aspiration Aspiration Valve [Volume (uL] [Cycles Pulse (us) Delay (us) Valve [Valve (Us) Cycles Pulse (us) Delay (us) | ile |
| Valves | ▶ 1 0 1 0 0 2 0 1 0 0 3 0 1 0 0 4 0 1 0 0 5 0 1 0 0 | |
| Valves Liquid Handling Wash Volumes (uL): 1 100 0 0 2 0 0 C 3 0 0 C Aspiration | ** 1 120.6 6 50.000 300.000 1 164.5 8 50.000 400.000 1 168.7 9 50.000 450.000 1 180.7 9 50.000 450.000 1 201.8 10 50.000 50.000 | |
| Image: Constraint of the second se | 2 0 1 0 0 0 0 2 2 2 1 30,000 30,000 2 4.7 1 40,000 40,000 2 8.7 1 50,000 50,000 2 2.8.8 2 50,000 100,000 2 7.95 4 50,000 200,000 | |
| Log [227:36 PM Pump_Initialze 8 7 | 2 131.4 6 50.000 300.000 2 179 8 50.000 400.000 2 209 9 50.000 450.000 2 231.6 10 50.000 500.000 | |
| Sent/Received | 3 0 1 0 0 3 3.5 1 30,000 30,000 3 6.7 1 40,000 40,000 3 10 1 50,000 ▼ | |
| | Scales B gai=Water 10Psi-ethanol | |
| <u>۸</u> | | Þ |

Figure 9-41 Multiple table option



9.6. Single Channel Barrel Position Teaching

This system has the option of single channel operation as well. The first barrel from outside of the deck functions as a single channel head. The position for this barrel is aligned like the reagent drop pins.

Select the test position, open settings>accessories and then double click Tip barrel #8. This will highlight the XYZ co-ordinates, and then click 'Tip Test'.

The first barrel from outside will go to that position. If the barrel is not in the center of the well, adjust X & Y settings. This testing can be done by picking 20ul tip too using single channel test mode (*Figure 9-42 Single Channel Barrel Position teaching*).

| 3 4 18 1 | 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 |
|--|--|
| 3 4 18 1 | 1 1 1 1 1 1 1 1 1 1 • • • • • • • • • • • • • |
| 4 2 21 | 1 1 1 1 1 1 1 1 • • • • • • • • • • • • • |
| 5 2 21 | 1 1 1 1 Pepth Tip Length Offset [X] |
| 6 3 22 1 | 1 1 ▶ |
| Image: Project Control (Control (Contro) (Control (Contro) (Control (| epth Tip Length Offset (X) |
| Tip Type Tip Box Type Engagement Offset Disengagement Offset Engagement Depth Tip Length 1 20 uL Tips (1-channel) 6 12 12 31.74 (1 1 20 uL Tips (8-channel) 06 12 11 31.74 (1 1 20 uL Tips (8-channel) 88 6 12 10.8 31.74 (1 | epth Tip Length Offset (X) |
| Tip Type Description Tip Box Type Engagement Offset Disengagement Offset Engagement Depth Tip Length 1 20 uL Tips (1 channel) 6 6 12 12 31.74 0 1 20 uL Tips (8-channel) 20 6 12 11 31.74 0 1 20 uL Tips (4-channel) 88 6 12 10.8 31.74 0 | 2pth Tip Length Offset (X) |
| 2 1000 uL Tips (8-channel) 21 6 12 13 95.82 | |
| ingagement Offset, Disengagement Offset, Engagement Depth, Tip Length, Offset (X), Offset (Y) in (mm) n Groups | |
| Pin Group Description Offset (X) Offset (Y) Offset [Z] Shaker Scale Shaker Speed | |
| 4 Tip Barrel #5 0 -35.9001 -0.2107 7 Aspirator 210 6 -170 2 450 | ed |
| 7 Aspirator 210 6 -170 2 450 | ed |
| | red |
| ▶ 8 Tip Barrel #8 0.5 -62.5 0 4 900 | red |
| | ed |
| 8 Trip Barrel #8 0.5 -62.5 0 4 900 11 Tip Barrel #1 0 0 0 8 1300 | |

Figure 9-42 Single Channel Barrel Position teaching

9.7. Syringe Pump Tab

Syringe Pump Tab is used to calibrate the pump/piston and to check the volume accuracy manually. (*Figure 9-43 Syringe Pump Control*)

Press the Initialize button and the plunger /piston of the selected pump should move upward to its initialized position. Typical Syringe Pump Type includes 8-channel x 250μ l or 1000μ l.

Select the step option to perform aspiration of 10,000 steps and press the Send button. The piston should move downward. There are two options to check volume or perform calibration. Pump control is completely manual and other one is little bit automated.



NOTE: For units with air displacement option—both single channel and 8 channel have same calibration data as all 8 pistons move together with one plunger. Therefore, same data is used in both scales. Water displacement units have different calibration data as the single channel syringes (25μ l & 1000μ l) are separate from the 8 channel syringes.

| Aurora Station v1.20.100 | and the R Common | |
|---|--|---------------|
| File Tools Options Help | | |
| 🧔 📉 🥙 📐 🏹 🖉 🚳 🐋 | | |
| Gripper Command Log | | |
| | Temperature A Temperature C Temperature D Shakers Tip Chang | er |
| Pump Calibration | Syringe Pump | |
| Syringe Pump Type 250 uL | Time: 1 sec | |
| Scale 25 | | |
| Equation: Step (X) = Scale * Volume (uL) | Pump Log | |
| | 2:51:11 PM Large pump initialization 2:51:19 PM Large pump aspiration 100 uL [10,902] | |
| Multiple Scale 🔂 Apply | 2.51.15 PM Large pump aspiration 100 dL [10,502] | |
| Air Gap Aspiration (step) 800 | | |
| Sample Aspiration (step) 3900 | | |
| Time Delay (sec) 4 | | |
| Send | | |
| Pump Control | | |
| Function Aspiration | | |
| Volume (uL) 100 📀 | | |
| Step C | | |
| 🗲 Initialize 🛛 🔀 Send | ≽ Clear | |
| | | |
| | | |
| | | |
| | | |
| COM Ports: 10, 9, 10, 3, 7, 8, 11, 35, 37, Temperature (I | | 28/17 2:51 PM |

Figure 9-43 Syringe Pump Control

NOTE: If there is no response from the syringe pump, refer to the Syringe Pump Settings section of this manual to adjust the COM port.



9.8. Calibration of Syringe Pumps (8-channel x 1000µL)

Syringe Pump Scale Calibration

This chapter will discuss the procedure of syringe pump calibration which applies to both syringe pumps: 1000μ L (single channel) and $8x1000\mu$ L (8 channel) pumps. The "Multiple Scale" option should be selected, and the single scale option selected. (*Figure 9-44 Syringe Pump Calibration*)

Open Aurora Station (Tools \rightarrow Aurora Station). Initialize the robotic arm by pressing the button between X and Y-axes ('Robotic Arm' tab) and move the arm towards you.

Manually engage a tip onto the first outer barrel. (Use a 25μ L tip for calibrations up to 20μ L volume, a 50μ L tip for calibrations in the $20-50\mu$ L range, a 200μ L tip for calibrations in the $50-200\mu$ L range and a 1000μ L tip for calibrations in the $200-1000\mu$ L range.

| 🗑 Aurora Station v1.20.100 | Tay to take | |
|---|---|--------------------|
| File Tools Options Help | Volume Calibration | |
| A N H H | Syringe Pump | |
| Level Sensing Command Log | Pump Type 250 uL 🔽 🔽 Multiple Table | |
| Robotic Arm Syringe Pump Cool | Syringe Pump Volume (uL) Steps | er Vacuum Manifold |
| Pump Calibration | | |
| Syringe Pump Type 8×250 | 0 1.6 200 | Reset |
| | 4.3 500 | |
| Scale 20 | 0 6.6 700 | |
| Equation: Step (X) = Scale * V | 0 8.1 1,000 | |
| \underline{L} <u>duation</u> . Step (A) = State (A) | 0 071 0000 | A |
| 🔽 Multiple Scale | 0 27.1 3,000 100] 0 44.4 5,000 0] 0 72.7 8,000 200] | |
| | 0 72.7 8,000 2001 | |
| Air Gap Aspiration (step) 1000 | 0 90.8 10,000 | |
| | 0 111.2 12,000 | |
| Sample Aspiration (step) 200 | 0 139.4 15,000 | |
| Time Delay (sec) 4 | 0 167.7 18,000 | |
| | 0 197.1 21,000 | |
| | 0 223.6 24,000 | |
| | 0 248.6 27,000 | |
| - Pump Control | 0 304.2 33,000 | |
| | 0 332.7 36,000 | |
| Function Dispensi | 0 353.8 39,000 | |
| Volume (uL) | | |
| | Scale | |
| Step 1200 | Scale 2 Ethanol | T |
| | Scale1-Water | |
| 🗲 Initialize 🛛 📔 | <u> *</u> <u> </u> |) Clear |
| | | |
| | | |
| | | |
| | 者 🔁 🖌 🐼 🔂 Apply | |
| | | F I |
| COM Ports: 10, 9, 10, 3, 7, 8, 11, 17, 4, 3 | Temperature (C): | 5/3/17 12:49 PM |

Figure 9-44 Syringe Pump Calibration



| 🔄 Aurora Station v1.20.100 | |
|--|-----------------|
| File Tools Options Help | |
| 🍻 🖄 📂 🔁 🗾 🚅 🐝 🛋 🛍 🚯 | |
| Gripper Command Log | |
| Robotic Arm Syringe Pump Cooler/Heater Block Temperature A Temperature C Temperature D Shakers Tip C | nanger |
| Pump Calibration Svringe Pump | |
| Syringe Pump Type 250 uL Syringe Pump Selection | |
| Scale 25 | |
| Equation: Step (X) = Scale * Volume (uL) | Pump |
| Image: Multiple Scale Image: Apply Image: Multiple Scale Image: Apply Image: Multiple Scale Image: Apply | activity |
| Air Gap Aspiration (step) 800 | record |
| Sample Aspiration (step) 3900 | |
| Time Delay (sec) 4 | |
| Send Send | |
| Pump Control | |
| Function Aspiration | |
| Volume (uL) 100 @ | |
| Step C | |
| 💕 Initialize 🛛 🖂 Send | |
| | |
| | |
| | |
| | |
| COM Ports: 10, 9, 10, 3, 7, 8, 11, 35, 37, Temperature (C): | 4/28/17 2:52 PM |

Figure 9-45 Syringe Pump

Switch to 'Syringe Pump' tab (*Figure 9-45 Syringe Pump*) from the Aurora Station main menu. Select the desired syringe pump and click 'Initialize' button.

One-time initialization is required for each syringe pump for the entire calibration procedure.

Manually place a tip onto the barrel. Check the calibration table for pre-calibrated data. Calibration can be done in steps (0) or volume mode (0).

Calibration Using Steps

There are two ways to perform calibration procedure.

Auto Mode: In this mode, the air-gap is adjusted in steps, the volume is adjusted in steps and the time delay after air-gap/before dispensing the volume is accounted for automatically.



Follow the below steps:

- 1 According to the calibration pump scale, add the desired air-gap (e.g. for 8x250μL pump, add 1000steps (10μL volume) in the air-gap field, and 200 steps (1.6μL) in the sample aspiration field and a four second time delay).
- 2 By clicking send, the instrument will draw in an air gap (1000 steps/10µL), wait for four seconds, aspirate 200 steps worth of volume (at this time put your vial with liquid under the tip), wait for four seconds again, dispense 1200 steps/ volume (1000 steps for the air-gap and 200 steps for the aspiration volume) into a pre-tared weigh boat. Weigh this weigh boat and confirm the volume is correct.

If the volume is not correct, replace the old value (1.6µL) to the new weight value in the calibration table (*Figure 9-46 Syringe Pump Calibration—Auto mode*).

Using the same process check whole range of steps (500, 700,3000) and keep changing the volume value in the calibration table if different from the previous value.

Pump Control Mode: In this mode, both the air-gap and the volume is sent separately, and then the volume is dispensed.

Follow the steps as below:

- 1 Under "pump control", select 'steps'. This will make steps the active field for data entry. Select "aspiration" as the function and enter 1000 steps (10μL) which will serve as the air gap, then click the send button. You will see 1000 steps in the command log. (*Figure 9-47 Syringe Pump Calibration-Manual mode*)
- **2** Enter 200 steps in the "Pump Control" section (1.6μL volume), and before clicking send insert a sample source under the pipette tip (*Figure 9-48 Syringe Pump Calibration-Aspirate volume*). You will see the solution aspirated into the tip.
- 3 Next tare a weigh boat on a scale. In the software, click "dispensing" and enter the 1200 steps (1000 air-gap +200 aspiration volume steps = 1200steps) and click send and collect the volume in the pre- tared weigh boat (*Figure 9-49 Syringe Pump*).Weigh the collected sample and enter the weight (if different than the previous value) in the volume section of the calibration data table.
- 4 Repeat this procedure for whole range of this pump (100, 200...) and keep adding the weight/volume in the calibration table if different from pre-calibrated volumes.
- 5 After calibration, check the calibration data, and click the green arrow to show the graph (*Figure 9-50 Syringe Pump Calibration-Graph & Scale*). Also check the scale for maximum volume by clicking the icon below the calibration table which will open the 'Maximum Volume' window. This window shows the maximum volume of the pump that can be aspirated/ dispensed (*Figure 9-50 Syringe Pump Calibration-Graph & Scale*). Add these maximum volume values in OPTIONS for all the three pumps (Figure 9-51 OPTIONS-Add Maximum volume).



| | Aurora Station v1.20.100 | | PCP 4 |
|--|--|---|---|
| Level Sensing Command Log Robotic Arm Syringe Pump Cooler/Heater Block Source Temperature A Shakers Tip Changer Gr Pump Calibration Syringe Pump Type 8X 250 ul • Scale 20 Councion: Step (X) = Scale * Volume (ul.) Multiple Scale Multiple Scale Volume (ul.) Time Delay (sec) Multiple Scale Volume (ul.) Step [200 Time Delay (sec) Volume (ul.) Step [200 Step [200 | File Tools Options Help | | Volume Calibration |
| Volume (uL) 0 353.8 39,000 Step 1200 © Scale Scale 2 Mitialize Send Scale 1: Water * | File Tools Options Help File Tools Options Help Image: Sensing Command Log Robotic Arm Syringe Pump Cooler/Heater Block Pump Calibration Syringe Pump Type 8x 250 uL Scale 20 Equation: Step (X) = Scale * Volume (uL) Image: Multiple Scale Multiple Scale Air Gap Aspiration (step) Sample Aspiration (step) Time Delay (sec) Pump Control | Source Temperature A Shakers Tip Changer Gr Syringe Pump Time: 1 sec Pump Log 12:35:09 PM 8-channel pump initialization 12:35:18 PM 8-channel pump aspiration [1,000] 12:35:24 PM 8-channel pump aspiration [200] | Syinge Pump Volume Calibration Pump Type 250 uL ✓ Multiple Table Syinge Pump ✓ ✓ Multiple Table Syinge Pump ✓ ✓ 0 0 0 0 1.6 200 0 4.3 500 0 8.1 1,000 0 17.8 2,000 0 27.1 3,000 0 111.2 12,000 0 193.4 15,000 0 197.7 18,000 0 197.1 21,000 0 223.6 24,000 0 223.6 27,000 0 275.5 30,000 0 30.42 33,000 |
| | Step 1200 @ | | Scale 2 Ethanol Scale1-Water |

Figure 9-46 Syringe Pump Calibration—Auto mode

| 🔚 Aurora Station v1.20.100 | |
|---|--|
| File Tools Options Help | |
| 🧟 🔌 🤧 🚬 🄁 🍠 🌌 🗲 | |
| Level Sensing Command Log | |
| | Source Temperature A Shakers Tip Changer Gripper Vacuum Manifold |
| Pump Calibration | Syringe Pump |
| Syringe Pump Type 8×250 uL 💌 | Time: 1 sec |
| Scale 20 | |
| Equation: Step (X) = Scale * Volume (uL) | Pump Log |
| | 12:40:12 PM 8-channel pump initialization 12:40:14 PM 8-channel pump aspiration [1,000] |
| Multiple Scale Reply | Air gap |
| Air Gap Aspiration (step) 1000 | |
| Sample Aspiration (step) 200 | |
| Time Delay (sec) 4 | |
| | |
| Send 🖂 | |
| Pump Control | |
| Function Aspiration | |
| | |
| Volume (uL) | Manual Calibration |
| Step 1000 @ | · · · · · · · · · · · · · · · · · · · |
| 🜠 Initialize 🛛 🖂 Send | 🍋 Clear |
| <u> </u> | |
| | |
| | |
| | Ч |
| | |
| COM Ports: 10, 9, 10, 3, 7, 8, 11, 17, 4, 3 Temperature | (C): • • • 5/3/17 12:40 PM |

Figure 9-47 Syringe Pump Calibration-Manual mode



Operation Manual-VERSA 1100

| Aurora Station v1.20.100 | | | 23 | |
|---|-------------------------|-------------------------------|-----------------|------|
| File Tools Options Help Solution Help Image: Solution State Image: Solution State | Volume (| Calibration | | x |
| Level Sensing Command Log Robotic Arm Springe Pump Cooler/Heater Block Source Temperature A Shakers Tip Changer | Syringe Pur Pump Typ | | 💌 🔽 Multiple Ta | able |
| Pump Calibration Syringe Pump | | ige Pump Volume (i | | |
| Syringe Pump Type 8×250 uL 🚽 🏹 Time: 1 sec | ▶ 0 | 0 | 0 | |
| | 0 | 1.6 | 200 | |
| Scale 20 Pump Log | | 6.6 | 700 | |
| Equation: Step (X) = Scale * Volume (ul.) | | 8.1 | 1,000 | |
| 12:40:12 PM 8-channel pump initialization | | 17.8 | 2,000 | |
| Multiple Scale Apply 12:40:14 PM 8-channel pump aspiration (1.000) 12:41:34 PM 8-channel pump aspiration (200) | 0 | 27.1 | 3,000 | |
| 12.41.34 FM ochariner pump aspiration [200] | 0 | 44.4 | 5,000 | |
| Air Gap Aspiration (step) 1000 | 0 | 72.7 | 8,000 | |
| | 0 | 90.8 | 10,000 | |
| Sample Aspiration (step) 200 | 0 | 111.2 | 12,000 | |
| Time Delay (sec) 4 | 0 | 139.4 | 15,000 | |
| | 0 | 167.7 | 18,000 | |
| Send Send | 0 | 197.1 | 21,000 | |
| | 0 | 223.6 | 24,000 | |
| | 0 | 248.6 | 27,000 | |
| Pump Control | 0 | 275.5 | 30,000 | |
| Function Aspiration | 0 | 304.2 | 33,000 | |
| | 0 | 332.7 | 36,000 | |
| Volume (uL) | 0 | 353.8 | 39,000 | |
| Step 200 (* Step 200 (* Step 200 (*) | | e e 2 Ethanol e1- Water | | |
| | | ск 5/3/17 12 | 2:41 PM | |

Figure 9-48 Syringe Pump Calibration-Aspirate volume

| Aurora Station v1.20.100 File Tools Options Help Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: Station V1.20.100 Image: | Volume Ca Syringe Pump Pump Type 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 | | ✓ Y Multiple ✓ X Multiple | Table |
|---|---|---|---|-------|
| Pump Control Function Dispensing Volume (uL) Step 1200 Function Dispensing Volume (uL) Step 1200 | 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 | 197.1 223.6 248.6 275.5 304.2 332.7 353.8 2 Ethanol • Water | 21.000 24.000 27.000 30.000 35.000 35.000 39.000 | |

Figure 9-49 Syringe Pump



Operation Manual-VERSA 1100

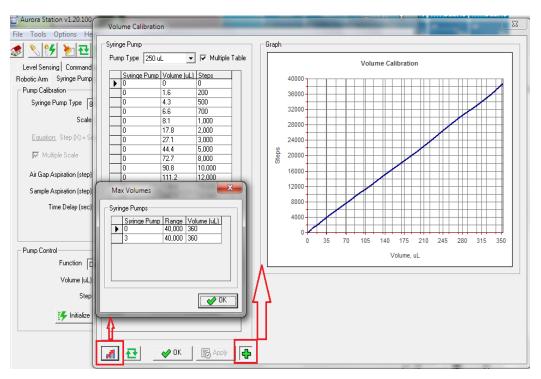


Figure 9-50 Syringe Pump Calibration-Graph & Scale



| Options | | | \times |
|---|-------------------------|--|----------|
| Syringe Pump Tip Boxes Plate Types | Reagent Drop 0 | ther | |
| Prime syringe pump before running each sequence | | | |
| | 1000 uL 4× | 1000 uL | - |
| Tip Volume | | | |
| Max. Volume (uL) | 900 | 900 | |
| Switch Volume (uL) | 900 | 900 | |
| Extra Volume | | | |
| Air Gap Volume (uL) | 30 | 30 | |
| Extra Aspiration Volume (uL) | 0 | 0 | |
| Extra Dispensing Volume (uL) | 0 | 0 | |
| Delay | | | |
| Delay After Aspiration (s) | 0 | 0 | |
| Delay After Dispensing (s) | 0 | 0 | |
| Priming | | | - |
| Pump Aspirate Speed | | Set Pump Aspirate Spee | :d |
| Start Speed (step/s) 1000 uL Pump 10 | End Speed (step/ | | |
| 1.0 | 600 | 5 | |
| 4 ?1000 uL Pump 10 | 600 | 5 | |
| | | | |
| Pump Dispense Speed | | Set Pump Dispense Spee | ed |
| Start Speed (step/s) | End Speed (step/ 800 | /s) Acceleration (step/s ²) 10 | |
| 4 ?1000 uL Pump 20 | | | |
| | 1000 | 10 | |
| | | | |
| Pump Air Aspirate Speed | | Set Pump Air Aspirate Sp | eed |
| Start Speed (step/s) 1000 uL Pump 10 | End Speed (step 600 | /s) Acceleration (step/s ²) 5 | |
| 1 | | | |
| 4 ?1000 uL Pump 10 | 600 | 5 | |
| | | | |
| | | | |
| Restore Default Save Default | | Apply 🗸 🗸 Car | ncel |

Figure 9-51 OPTIONS-Add Maximum volume

7 If you would like to add a new data point, note the weight of the volume and the number of steps from the 'Pump Log' as shown in *Figure 9-52 Calibration Table New Data Point Entry*. Then add the weight/volume and steps at the end of the calibration table, and click "Apply".



| Aurora Station v1.20.100 | Volume Calibration |
|--|---|
| File Tools Options Help Image: Second s | Syringe Pump Pump Type 8×250 uL 🔽 🔽 Multiple Table |
| Image: Sender Series of Command Log Robotic Arm Syringe Pump Cooler/Heater Block Source Terr Pump Calibration Syringe Pump Type Scale 20 Equation: Step (X) = Scale * Volume (uL) Image: Multiple Scale Air Gap Aspiration (step) Sample Aspiration (step) Sample Aspiration (step) Pump Control Function Dispensing Volume (uL) Volume (uL) Step 1200 Step 1200 Imitialize Send | Pump Type 8 × 250 uL ✓ Multiple Table 3 4.3 500 3 4.3 500 3 5.8 700 3 8.7 1.000 3 17.8 2.000 3 27.1 3.000 3 72.7 8.000 3 111.1 12.000 3 167.5 18.000 3 197.7 21.000 3 223.6 24.000 3 248.6 27.000 3 304.2 33.000 3 32.75 30.000 3 332.7 36.000 3 332.7 36.000 3 332.7 36.000 3 353.8 39.000 * Scale 2 Ethanol Scale1- Water * |
| | |
| COM Ports: 10, 9, 10, 3, 7, 8, 11, 17, 4, 3 Temperature (C): | • • 1:48 PM |

Figure 9-52 Calibration Table New Data Point Entry

Multiple Scale Tables

If you would like to maintain different calibration tables for different reagents (if you are using reagents with greatly differing densities), this can be done by enabling the Multiple Table option (*Figure 9-53 Multiple Table- Scale-1*).

Calibration data will be displayed according to the scale/table opened. Figure 9-56 Syringe Pump –Aspirate 50μ L volume shows Scale 1 data & Figure 9-54 Multiple Table scale-2 shows data from another table. Depending upon the reagent being used, switch to the appropriate calibration table and then create sequences, VERSA will use the calibration data/steps from the selected table.



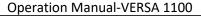
Operation Manual-VERSA 1100

| Image: Command Log Image: Command Log Robotic Arm Syringe Pump Cooler/Heater Block Source Temperature Pump Calibration Scale 20 Syringe Pump Scale 20 Equation: Scale 20 Equation: Scale 20 Image: Command Log Time: 1 0 1.6 200 Equation: Scale 20 0 2.7.1 3.000 Image: Command (step) 1000 Sample Aspiration (step) 1000 2.7.7 8.000 Sample Aspiration (step) 200 Time: 1 1.2.40:12 PM 8-0 0 134:4 5.000 0 17.8 2.000 Time Delay (sec) 4 Sample 1.2.40:256 PM 8-0 1.3.4:4 5.000 0 134:4 5.000 0 134:4 5.000 0 134:4 5.000 0 134:4 5.000 0 134:4 5.000 0 134:4 5.000 0 134:4 5.000 0 134:4 5.000 0 134:4 5.000 0 134:4 5.000 0 134:4 5.000 0 135:3.8 3.000 0 332:7 36.000 0 332:7 36.000 0 <th> File Tools Options Help </th> <th>Volume Calibration</th> | File Tools Options Help | Volume Calibration |
|--|---|--|
| Bobotic Arm Syringe Pump Cooler/Heater Block Source Temperature Pump Calibration Syringe Pump 8 × 250 uL Image: Cooler/Heater Block Source Temperature Syringe Pump Type 8 × 250 uL Image: Cooler/Heater Block Source Temperature 0 0 Social 20 Image: Cooler/Heater Block Source Temperature 0 0 Social 20 Image: Cooler/Heater Block Source Temperature 0 0 0 Social 20 Image: Cooler/Heater Block Source Temperature 0 1.6 200 Ecoustion: Step (X) = Scale * Volume (uL) Image: Cooler/Heater Block Social * Volume (uL) 0 1.7.8 2.000 I2:40:12 PM 8-c I2:40:14 PM 8-c I2:41:34 PM 8-c 0 72.7 8.000 0 167.7 18.000 0 111.2 12.000 0 187.7 18.000 0 167.7 18.000 0 12.42:56 PM 8-c 0 12.42:36 24.000 0 12.42:36 24.000 0 32.7 38.000 0 32.8 33.000 0 32.7 38.000 0 3 | | |
| Pump Control 0 248.6 27,000 Pump Control 0 275.5 30,000 Volume (uL) 0 332.7 36,000 Volume (uL) C 358.8 39,000 Scale 2 libanol Scale 1 - Water Scale 2 libanol Scale 1 - Water ** | Robotic Arm Syringe Pump Cooler/Heater Block Source Temperal Pump Calibration Syringe Pump Type 8×250 uL Syringe Pump Scale 20 Time: Equation: Step (X) = Scale * Volume (uL) Pump Log Multiple Scale Apply Air Gap Aspiration (step) 1000 Sample Aspiration (step) 200 | ▶ 0 0 0 0 1.6 200 1 s 0 4.3 500 0 8.6 700 0 8.6 700 0 1.7.8 2.000 8-cl 0 27.1 3,000 8-cl 0 72.7 8,000 0 111.2 12,000 0 139.4 15,000 0 167.7 18,000 |
| Initialize Send | Pump Control Function Dispensing Volume (uL) | 0 248.6 27.000 0 275.5 30.000 0 304.2 33.000 0 332.7 36.000 0 353.8 39.000 Scale |
| | | Scale1-Water |

Figure 9-53 Multiple Table- Scale-1

| Aurora Station v1.20.100 | Volume Calibration |
|---|--|
| File Tools Options Help | Volume Calibration |
| Image: Second | $\begin{array}{c ccccccccccccccccccccccccccccccccccc$ |
| Equation: Step (X) = Scale * Volume (uL) Image: Multiple Scale Air Gap Aspiration (step) Sample Aspiration (step) Time Delay (sec) Image: Apply | 0 28.9 3,000 # 8-cl # 8-cl # 8-cl |
| Pump Control Function Dispensing Volume (uL) Step 1200 For Initialize Send | Scale Scale Scale Scale Scale Comparison Scale Comparison Scale Comparison Scale Comparison Compari |

Figure 9-54 Multiple Table scale-2





Testing Small volumes using Multiple Cycles:

This method of testing is recommended for small volumes (1, 2 & 5μ L) which cannot be weighed properly on the balance with one dispense/cycle only.

Follow the steps below:

1. Open Aurora Station, and open the Syringe pump tab. Select the pump that you wish to check the volume of.

2. Go to 'manual calibration' with volume selected as shown in figure.

3. Initialize the pump.

4. Manually engage one 50µL tip onto the desired barrel by hand.

5. Select an aspiration option

6. Add a 20µL air-gap in the volume column and hit send (there will be volume & steps displayed in the log table on the left. (*Figure 9-55 Syringe Pump –Aspirate 20µL Air-gap*)

| The Aurora Station v1.20.100 | |
|--|--------------|
| File Tools Options Help | |
| | |
| Level Sensing Command Log | |
| Robotic Arm Syringe Pump Cooler/Heater Block Source Temperature A Shakers Tip Changer Gripper Vacuum Mar | nifold |
| Pump Calibration Syringe Pump | |
| Syringe Pump Type 8X 250 uL 🗨 🌔 Time: 2 sec | |
| Scale 20 | |
| Equation: Step (X) = Scale * Volume (uL) | |
| Multiple Scale Apply 1:56:50 PM 8-channel pump aspiration 20 uL [2,237] | |
| Air Gap Aspiration (step) 1000 | |
| Sample Aspiration (step) 200 | |
| Time Delay (sec) 4 | |
| Send | |
| Pump Control | |
| Function Aspiration | |
| Volume (uL) 20 | |
| | |
| Step C | |
| 🌮 Initialize 🛛 🙀 Send | |
| | |
| | |
| | |
| | |
| COM Ports: 10, 9, 10, 3, 7, 8, 11, 17, 4, 3 Temperature (C): | 3/17 1:56 PM |

Figure 9-55 Syringe Pump – Aspirate 20µL Air-gap



7. Enter a 50 μ L volume in the pump control, and click send (Again place a tube of distilled water below the barrel to aspirate the 50 μ L volume). (*Figure 9-56 Syringe Pump –Aspirate 50\muL volume*)

8. Change to dispense mode

| 🚰 Aurora Station v1.20.100 |
|---|
| File Tools Options Help |
| |
| Level Sensing Command Log |
| Robotic Arm Syringe Pump Cooler/Heater Block Source Temperature A Shakers Tip Changer Gripper Vacuum Manifold |
| Pump Calibration Syringe Pump |
| Syringe Pump Type 8×250 uL 🔹 🌔 Time: 1 sec |
| Scale 20 |
| Equation: Step (X) = Scale * Volume (uL) |
| 1:56:46 PM 8-channel pump initialization |
| Multiple Scale Apply 11:57:55 PM 8-channel pump aspiration 50 uL [5,594] |
| Air Gap Aspiration (step) 1000 |
| Sample Aspiration (step) 200 |
| Time Delay (sec) |
| Send |
| |
| Pump Control |
| Function Aspiration |
| Volume (uL) 50 C |
| Aspirate 50ul water |
| |
| Finitialize Send |
| |
| |
| |
| |
| COM Ports: 10, 9, 10, 3, 7, 8, 11, 17, 4, 3 Temperature (C): |

Figure 9-56 Syringe Pump – Aspirate 50µL volume

9. Add 10μ L & click send & dispense back to the same tube. This dispense back volume is to compensate any backlash of the system (*Figure 9-57 Syringe Pump –Dispense back to vial 10µL*)



| 🔄 Aurora Station v1.20.100 | |
|---|-------------------------|
| File Tools Options Help | |
| 🌌 🔨 📂 🎦 🌌 🌌 📽 🎬 🕚 | |
| Level Sensing Command Log | |
| Robotic Arm Syringe Pump Cooler/Heater Block Source Temperature A Shakers Tip Changer (| Gripper Vacuum Manifold |
| Pump Calibration Syringe Pump | |
| Syringe Pump Type 8×250 uL 🖃 🚺 Time: 1 sec | Reset |
| Scale 20 | |
| Equation: Step (X) = Scale * Volume (uL) | |
| 1:56:46 PM 8-channel pump initialization | 2371 |
| Multiple scale E⊘ APPY 1:57:55 PM 8-channel pump aspiration 50 ul. [5] | 5941 |
| Air Gap Aspiration (step) 1000 | ,143] |
| Sample Aspiration (step) 200 | |
| Time Delay (sec) 4 | |
| Send | |
| Pump Control | |
| Function Dispensing | |
| Volume (uL) 10 C vial | |
| Step | - |
| 🌮 Initialize 🛛 🖂 Send | ≽ Clear |
| | |
| | |
| | |
| | μ |
| | |
| COM Ports: 10, 9, 10, 3, 7, 8, 11, 17, 4, 3 Temperature (C): | 5/3/17 1:59 PM |

Figure 9-57 Syringe Pump –Dispense back to vial 10µL

10. Enter 1µL volume in the pump control, then aspirate and dispense it into a pre-tared weigh boat (making sure the tip touches the boat while dispensing). Repeat this 1µL aspiration and dispensing cycle in the same boat five times & then weigh the boat—it should be around 5µL. (*Figure 9-58 Syringe Pump –Dispense 1ul (five times) to weighing boat*) Divide this weight by 5 & get the volume of 1µL. Repeat it 10 times to calculate the CV. Repeat steps 5-9 again to finish 10 replicates. If the accuracy is not good, calibrate the system for 1µL again.



| Aurora Station v1.20.100 | |
|---|--|
| File Tools Options Help | |
| 🍻 🔌 📂 🍉 🔁 🍠 🌌 🔹 🐋 | |
| Level Sensing Command Log | |
| Robotic Arm Syringe Pump Cooler/Heater Block | Source Temperature A Shakers Tip Changer Gripper Vacuum Manifold |
| Pump Calibration | Syringe Pump |
| Syringe Pump Type 8×250 uL 💌 | Time: 0 sec |
| Scale 20 | |
| Equation: Step (X) = Scale * Volume (uL) | Pump Log |
| Multiple Scale Apply | 1:56:46 PM 8-channel pump initialization 1:56:50 PM 8-channel pump aspiration 20 uL [2,237] |
| | 1:57:55 PM 8-channel pump aspiration 50 uL [5,594] 1:59:02 PM 8-channel pump dispensing 10 uL [1.143] |
| Air Gap Aspiration (step) 1000 | 2:00:38 PM 8-channel pump dispensing 1 uL [125] 2:00:38 PM 8-channel pump dispensing 1 uL [125] |
| Sample Aspiration (step) 200 | 2:00:39 PM 8-channel pump dispensing 1 uL [125] |
| Time Delay (sec) 4 | 2:00:40 PM 8-channel pump dispensing 1 uL [125] 2:00:41 PM 8-channel pump dispensing 1 uL [125] |
| Send | |
| Pump Control | |
| Function Dispensing 💌 | |
| Volume (uL) 1 | Dispense 1ul five times to weighing |
| Step O | boat |
| | |
| 💅 Initialize 🛛 🖂 Send | Near Clear |
| | |
| | |
| | |
| | |
| COM Ports: 10, 9, 10, 3, 7, 8, 11, 17, 4, 3 Temperature | C): • • 5/3/17 2:00 PM |

Figure 9-58 Syringe Pump –Dispense 1ul (five times) to weighing boat

9.9. Reagent Cooler Block Tab

This tab sets and monitors the temperature of the reagent/cooler block in the range of 2 - 90°C with 0.25°C increments.

The tab allows the user to check or change COM ports or present temperature. The recommended temperature for the reagent/cooler block is 4 °C which is also the default value.

Unlock the COM port as displayed in the figure below (*Figure 9-59 Cooler Block Control*) to observe readings of actual and pre-set temperatures. If there is no response, proceed to change the COM port. Test the new COM port by clicking the "open" tab.

To change present temperature, go to the temperature field and input the temperature required and click the "apply" tab to save the new settings.



After implementing the change, allow up to 30 minutes for the change to take effect before loading reagents and enzymes onto the block. The temperature log provides a record of any changes made. Click the "clear" button to erase the log records.

If the temperature reading from an external thermometer does not match the display temperature, parameter B can be adjusted to match the true temperature. Wait and check after it stabilizes at the required temperature (*Figure 9-59 Cooler Block Control*).

NOTE: If there is no response from the cooler block, refer to the Temperature Control section of this manual to adjust the COM port. Use only installed COM ports for cooler block configuration (refer to software installation chapter of this manual for more details).

Figure 9-59 Cooler Block Control





9.10. Source Temperature Tab

This tab allows the user to change/ set the COM ports, as well as the temperature for other cooling/ heating adaptors that have been fitted onto the deck.

The temperature can be changed or set here for up to two different temperature adaptors (e.g. plate coolers/ heaters, shaker with heater etc.). Once the new set temperature takes effect, it can be monitored under the "temperature monitor" part of the window (bottom of screen) for each adaptor (*Figure 9-60 Source Temperature Settings*).

| The Aurora Station v1.20.100 |
|--|
| File Tools Options Help |
| |
| Gripper Command Log |
| Robotic Arm Syringe Pump Cooler/Heater Block Temperature A Temperature C Temperature D Shakers Tip Changer |
| COM Port |
| Image: Close 3:21:24 PM Address 1 < 21.3 12 |
| - Temperature Control |
| CDM Port 11 Gunlock Temperature |
| Parameter A1 1 Serial Number |
| Parameter A1 1 Serial Number Parameter B1 0 FTUC5AP9C adjustment |
| Parameter A2 1 parameters |
| B Parameter B2 0 |
| Equation: Actual Temperature (°C) = A * Set Temperature (°C) + B 3:21:24 PM Address 1> -1 -1 [Ch 1 & 2 read error] |
| Temperature 1 (°C) 21.3 |
| Temperature 2 (°C) 12 |
| Reply Send |
| Temperature Monitor |
| Temperature 1 (°C): |
| Temperature 2 (°C): Temperature Input |
| |
| |
| CDM Ports: 10, 9, 10, 3, 7, 8, 11, 35, 37, Temperature (C): |

Figure 9-60 Source Temperature Settings

9.11. Shaker Tab

This tab allows the operator to set shaker COM ports (already specified) and test the speed of the shaker.

Shaker speeds can be set between 200-2500 rpm. To change the shaker control settings, click "apply" to implement the settings. You can test the new settings by clicking on the "send" tab (*Figure 9-61 Shaker Settings*).



In the application tabs, the user can use any speed between 100 - 2500 rpm depending upon the protocol requirements and the plate being used on the shaker.

| 🚰 Aurora Station v1.20.100 | |
|---|---|
| File Tools Options Help | |
| 🔕 🔌 🛃 🚬 🔁 🛃 🥒 🏙 🛛 | |
| Gripper Command Log | |
| | ature A Temperature C Temperature D Shakers Tip Changer |
| Shaker #1 | Shaker #2 |
| | |
| COM Port 8 | COM Port 0 |
| | |
| Speed (rpm) 200 | Speed (rpm) 800 |
| Time (sec) 30 Shake | Time (sec) 60 Shake |
| Serial Number FTTA2B7NA 🔤 Stop | Serial Number FTTA2B7NB 🔤 Stop |
| 🔽 One Direction | ✓ One Direction |
| Shaker #3 | Shaker #4 |
| 0 | O |
| COM Port 0 | COM Port 0 |
| Address 0 | Address 0 |
| Speed (rpm) 900 | Speed (rpm) 1100 |
| Time (sec) 3 Shake | Time (sec) 12 Shake |
| Serial Number FTTA2B7NC 🔤 Stop | Serial Number FTTA2B7ND Stop |
| 🔽 One Direction | ✓ One Direction |
| Shakers A Shakers B | |
| | |
| | P |
| COM Ports: 10, 9, 10, 3, 7, 8, 11, 35, 37, Temperature (C): | • • • • 5/1/17 4:00 PM |

Figure 9-61 Shaker Settings

9.12. Gripper & Aspirator Tab

Gripper: This tab shows all the settings for gripper. To set the COM port for the gripper the user can test/set the gripper position using the gripper engagement offset, XYZ offsets, speed, and positions

Gripper Speed Settings: These are default settings (Figure 9-62 Gripper Settings)

Gripper XYZ Settings: These are also default settings, but can be adjusted depending on the plate being moved. The gripper X-Offset value, if increased, will change the gripper position on the right side of the plate and if decreased will change the gripper position on the left side.

Gripper Y-Offset value if increased will move the gripper outwards and vice versa.



Gripper Z-Offset is the value which allows the gripper to grab the plate at a specific Z distance (*Figure 9-63 Gripper Holding Deep Well Plate*).

Gripper Offset Settings: Engagement Offset is used to set the gripper Z setting to open the gripper when moving the plate from one position another. Other settings like max range, pad clearance etc. are also set here. Plate count is the number of plates to be stacked at one position.

| | 🔄 Aurora Station v1.20.100 | | |
|-------------|---|--|--|
| | File Tools Options Help | | |
| | Image: Settings Image: Settings Image: Settings Image: Settings COM Port Image: Settings Image: Settings Image: Settings Image: Comparison of the set of | | |
| | | | |
| | | | |
| | | | |
| | Speed Settings | | |
| | Engagement Speed | | |
| | Start Speed (step/s) 50 | | |
| | End Speed (step/s) 1500 Gripper Speed Settings | | |
| | Acceleration (step/s ²) 10 | | |
| | | | |
| | Gripper Aspirator | | |
| | Gripper X-Offset (mm) 208 Engagement Offset (mm) 50 Source Z-Offset (mm) 0 | | |
| Gripper XYZ | | | |
| Settings | | | |
| Settings | Gripper Pads Clearance (mm) 24 | | |
| | | | |
| | Gripper Plate Type 11 - 96-deep Round Well Plate 🗸 Source Plate Count 1 | | |
| | Source Position 6 - Cooler Plate 1 | | |
| | Target Position 11 - Magnetic Stand | | |
| | Apply J Initialize Close Step 1000 1 X 0 | | |
| | COM Ports: 10, 9, 10, 3, 7, 8, 11, 35, 37, Temperature (C): | | |

Figure 9-62 Gripper Settings





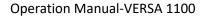
Figure 9-63 Gripper Holding Deep Well Plate

9.13. Vacuum Tab

This tab allows user to test vacuum manually. After the COM port is set, the vacuum can be tested for valves 1 & 2 (*Figure 9-64 Vacuum Settings*). This tab is also used for RD Level Sensing.

| 🖅 Aurora Station v1.20.100 | |
|--|---|
| File Tools Options Help | |
| 🧟 🔨 💔 📐 社 🛃 🌌 🎕 🗨 🛍 | |
| Command Log | |
| Robotic Arm Syringe Pump Cooler/Heater Block Sou Vacuum Manifold Settings | rce Temperature A Shakers Tip Changer Gripper Vacuum Manifold |
| COM Port 4 Serial Number | Position Valve Valve ID 1 1 9 |
| Time Out (ms) 2000 FTTA2B7NB | 5 2 10 6 1 9 |
| Step Delay (ms) 500 | * |
| AC Control ID 13 | - Waste Level Sensing |
| Level Sensing ID 15 | Enable Level Sensing |
| 🔓 Unlock 🕞 Apply | Vacuum Manifold Log |
| COM Port | |
| Close | |
| Vacuum Manifold Control | |
| Reset | |
| Control Valve 1 | |
| Control Valve 2 | |
| AC Control | |
| Level Sensing | |
| AC Control Valve 🔲 Safety Hood | Clear |
| COM Ports: 10, 9, 10, 3, 7, 8, 11, 17, 4 Temperature (C): | • • • 5/1/17 4:09 PM |

Figure 9-64 Vacuum Settings





9.14. Command Log Tab

This screen displays the summary of all the executed steps created since the VERSAware was last opened. Click on the "clear" tab to erase logged message once they have been identified and rectified *Figure 9-65 Command Log Settings*).

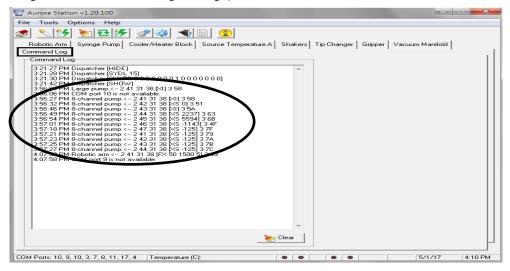


Figure 9-65 Command Log Settings

NOTE: Consult the manufacturer on rectification of errors if unsure or if errors persist.

9.15. Liquid level Sensing (Optional-Single Channel - LLS Hardware Required)

This feature of liquid level sensing on the unit provides user the ease of aspirating the liquid after sensing the level in the tube/plate and then aspirating the liquid from that level with accuracy.

In the figure below (*Figure 9-66 Liquid Level Sensing Settings*), LLS comport can be set, LLS can be tested manually to make test it before running any assays.



| 🕵 Aurora Station v1.20.66 | – 🗆 X |
|--|--------------------|
| File Tools Options Help | |
| | |
| Robotic Arm Syringe Pump Cooler Block Shaker Tip Changer Gripper Vacuum Manifold Level Sensing | Command Log |
| Level Sensing Control | Level Sensing Log |
| COM Ports 11 12 13 7 | <u>^</u> |
| Maximum Retries 0 Geometric Volume Calculation | |
| Retry Pullback (mm) 20 | |
| 👚 Unlock 🛛 😰 Apply 🛛 🖅 Initialize 🛛 🚫 Stop | × |
| | ^ |
| Level Sensing Monitor | |
| | |
| | ~ |
| | |
| 1 C Microsoft | |
| Office | |
| | |
| | |
| LILLY Components | |
| | |
| | |
| | / Clear |
| | |
| | |
| COM Ports: 4 Ў¤ 3 Ў¤ 4 Ў¤ 5 Ў¤ 8 Ў¤ Temperature (ЎrC): | 2018-04-26 4:46 PM |

Figure 9-66 Liquid Level Sensing Settings

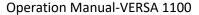
Liquid Level Sensing (LLS) Calibration

This chapter deals with both manual checking and calibration of the liquid level sensor equipped. You are advised to manually check the sensor's operation before or after calibration. It is good practice to manually check the sensor's operation periodically to ensure it is in good working condition.

Manual checking LLS operational capability

Steps:

- 1. Move the arm to an empty position anywhere on the deck
- 2. Open Aurora Station and click on the level sensing tab.
- 3. Click "initialize".
- 4. A dialog will pop up saying, "initializing in progress."
- 5. The log will show the signal levels at various rates



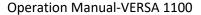


- 6. Place your finger slightly below the syringe/tip barrel (no tip engaged)
- 7. Note the jump of the signal from 100 to approximately 200 (Figure 9-67 Base Signal).
- 8. Next, insert a black conductive $20\mu L$ tip into the barrel.
- 9. Insert the tip into a 5 to 7mL vial with distilled water.
- 10. Note the signal level changing from 100 to 200 (*Figure 9-68 Signal Level Change Barrel with Tip Immersed in Liquid*).
- 11. If the above are observed when performing steps 1 to 10, then the liquid sensor is working as it should. Proceed to calibrate or check COM ports if you observe no change in the signal level.

The below figures provide examples of what to expect when level sensing is operational around the barrel and in a liquid.

| V Aurora Station v1.18.5 File Tools Options Help | |
|--|--|
| Image: Control Color Block Source Temperature Level Sensing Command Log Level Sensing Control COM Port Retry Pullback (mm) Image: Color Block Source Temperature COM Port 9 Retry Pullback (mm) Image: Color Block Source Temperature Level Sensing Command Log Maximum Retries 2 Tolerance (mm) Image: Color Block Image: Color Block Source Temperature Image: Color Block Image: Color Block Source Temperature Level Sensing Command Log Image: Color Block 9 Retry Pullback (mm) Image: Color Block Image: Color Block Image: Color Block 9 Retry Pullback (mm) Image: Color Block Image: Color Block Image: Color Block 10 Color Block 10 Image: Color Block Image: Color Block Image: Color Block 10 Color Block 10 Image: Color Block Image: Color Block Image: Color Block 10 10 10 Image: Color Block 10 Image: Color Block 10 10 10 10 10 Image: Color Block 10 10< | Level Sensing Log 1:26:58 PM 105 1:26:58 PM 105 |
| Level Sensing Monitor | 1.26.58 PM 105 1.26.58 PM 105 1.26.58 PM 105 1.26.58 PM 105 1.26.58 PM 105 1.26.58 PM 105 1.26.57 PM 105 |
| COM Ports: 7 · 5 · 6 · 8 · 9 Temperature (*C): 6.2 · 10.2 · 10.2 • 105 | 6 12/18/09 1:26 PM |

Figure 9-67 Base Signal



| Retry Pullback (mm) Store Temperature Level Sensing Command Log Level Sensing Control COM Port Participation Store Temperature Level Sensing Command Log COM Port Participation Store Temperature Level Sensing Command Log Maximum Retries Participation Store Store Unlock Papely Store Store | Level Sensing Log 1:28:54 PM 185 1:28:54 PM 185 1:28:54 PM 185 1:28:54 PM 185 1:28:54 PM 185 |
|---|--|
| COM Port 9 Retry Pullback (mm) 6 Maximum Retries 2 Tolerance (mm) 0.4 Comparison Unlock Image: Apply Image: Apply Stop | 1:28:54 PM 185 1:28:54 PM 185 1:28:54 PM 185 1:28:54 PM 185 |
| | 1:28:54 PM 185 |
| Level Sensing Monitor | 1:28:53 PM 185 1:28:53 PM 185 1:28:52 PM 185 |

Figure 9-68 Signal Level Change – Barrel with Tip Immersed in Liquid

LLS calibration check for a current plate type

Steps:

LUUMINATING SOLUTION

1. Open Aurora Station and select a new blank or empty row for use in the coordinates table. Under the position field, type in a position number and a comment (this can be any number or name that don't coincide with the default teach positions). Leave all other fields empty and highlight the new row entry (*Figure 9-69 New Row Entry for Coordinates*).

| toto.6m Sump | Paren Cook | Black | | Temperatu | al sha | - To 0 | harger 0 | incom 1 | Level Service | g Comma | ratLog |
|--------------|--------------------|----------------|----------|-------------------|---------|-------------|----------------------|---------|-------------------|----------|--------|
| | | | | | | er eller e | | | | | |
| 10 | 6. 16 38 | | | | | | | | 13 | 500 L | |
| 3 | | | | | | | | | | 1 | |
| | | | | | | | | | | | |
| | 16 1 | | | | | | | | | _ | |
| | FILE | Contractory of | - | | | | - | | | - | |
| | - H | | | 2 | | | I HEF | | 100.000 | EN | |
| | 1100 | HIGH | 41H | 1111111 | | 111110111 | | | - HILLING | | |
| | | (INCOME) | | distant. | | | | SEE 1 | | | |
| | | 666 | | 111.4 | | 1 | | 2001 | 10 | 22 | |
| | 18 | (Internet and | | an analta | | Collins of | - | | Concernant of the | | |
| | | 44.2 | | 1000 | - H B | 13 | | | 15 | | |
| | | H Refer | 88 I. | | ・月間 | ille in the | | | | | |
| | - | 4.0 | Sillin | 20 | 1.1.1.1 | 21 | | | | | |
| | | and the second | <u> </u> | - Contract | | | | _ | _ | - | |
| 2900 - | | | | | | | | | | + 152 | |
| | extb 1 | fie Y 10 | 10 | aoz10 | Ge | ×vzl o | Fort 1 Ter | I Teatl | Same IT T | | |
| Are Carted | | | | the second second | | | Connent | 1 | | | |
| Sap (with | and install in the | | 15 | 10435 | 2550 | 51011 | 20 J.L. TID | | 0 | | |
| 10 | • * * | | 16 | 273 | 75 | 47414 | Prining Pr | | | | |
| | + | | 17 | 287 | 1310 | 49000 | Waste Po The Duty | | | | |
| V FAD Z UN | + = - | | 18 | 94 | 2003 | 93394 | Teres LL | | | | |
| | | | | | | - | - | | | - | |

Figure 9-69 New Row Entry for Coordinates



2. Again from Aurora Station, select advanced settings, select single channel

Mode to test LLS as shown below in Figure (*Figure 9-70 Setting the Tip Box Position, Plate Position & single channel mode for Calibration*).

NOTE: You'd have to ensure that the test position for both the tip box and plate type are set by clicking onto the "advanced" tab in Aurora Station Settings. To change or set, click on the arrow to open options and select the position of choice. Remember that if you select e.g. position 14 for $20/50/200 \ \mu$ L tip box that you have a tip box placed in position 14 on the deck available. You'd also want to drag the appropriate tip box icon over onto the working deck interface in VERSAware to position 14. After which, you'd want to "reload" tip boxes. The same goes for the plate type you'd want to test. If test position for a plate is selected as 1, load appropriate plate type for the test should be in that position and icon dragged over to that position on the working deck interface in VERSAware.

| ieneral Advanced Accessories Plate Types Hardware Tip Engagement (Robotic Am) | ⊧ ⊨Shaker | Syringe Pump |
|---|---|--|
| Start Speed (step/s) 50 End Speed (step/s) 500 | Start Speed (step/s) 100 Acceleration (step/s ²) 10 | Pump Connected to Atm Pump Device 0 |
| Acceleration (step/s ²) | eccentrative 1 [10 | Device Address (hex) [31 |
| Reagent/Cooler Block Cooler Address 1 Channel 1 Position 8 - Reagent/Cooler Block Cooler Control Delay (ms) 10000 | Communication Step Loss Error Count 10 Time Out Error Count 10 1st Time Out (s) 60 2nd Time Out (s) 240 | Positions [Exclude X, Y, Z-Offset] |
| Source Temperature Source 1 Address 1 Channel 2 Position 7 - Source/Target Plate Source 2 Address 2 Channel 2 | Command Delay (ms) [100 Arm Address (hex) [31 Device Address (hex) [38 | Pi Auto Recovery Pi Auto Recovery Double Pi Auto Recovery |
| Position 9 - Source/Target Plate | X-Offset (step) 2400 | Syringe Pump |
| Chute Orientation | Tip Disengagement Y-Ottset (step) [900 | 250 pL Small Syringe Pump Small Syringe Pump Only |
| Test Position [Plate Type] | Plate Type [Teaching Positions] | Position Test Mode |
| Position 14 · 1000 µL. Tip Box/Plate | See Type 1 - SS-well Plate | Single Channel Test |

Figure 9-70 Setting the Tip Box Position, Plate Position & single channel mode for Calibration



3. Click on the plate type icon in Aurora Station. Focus on the topmost table to test LLS parameters. To achieve this, click on the particular plate type field for test (*Figure 9-71 Testing LLS Parameters under Aurora Station Settings Plate Types Tab*).

| - | Dista Tuna | Description | | Cohampa | De | in I Ca | Lene D | istance a | | Dista T | - | Denti | | Mahim | | |
|-----|---|------------------------|----------------|-------------|----------|--|---------|----------------|----------------|--------------|-------|-------|----------|----------|----------|----|
| - | | | | 10 | 5 | 36 | utenu | starice - | | 44 | ape . | | | | <u>c</u> | - |
| | 44 | | Holder | 8 | 4 | 14 | 4978 | | | 44 | - | 0 | | 1860 | - | |
| • | 45 | | | 12 | 8 | 9 | | | | 45 | - | 21.65 | 15 | 0 | - | |
| | 46 | 50 µL Tip Box (AmpliS | lide) | 12 | 8 | 9 | | | | 45 | | 18.24 | 84 | 10 | | - |
| | 47 | 95-well Non-skitted Pl | CR Plate 3 | 12 | 8 | 8.9 | 5 | | | 45 | | 17.01 | 54 | 20 | | |
| 1.5 | 48 | 96-well Non-skirted Pl | CR Plate 4 | 12 | 8 | 8.9 | 5 | | | 45 | | 15.53 | 58 | 30 | | |
| 1 | | | | 141230 | | 1. | | • | | 45 | | 15.04 | 26 | 40 | | * |
| • | | | er Block (T1 | | Row 1 | Heigh | * Diffe | ence + | | | 1 | olumn | Row 1 | | | - |
| | web/web/Phas | | 1001 | | | | | | 1100 | a section | | | | | | |
| - | Elata Tuna | Description | | [Column | Daw | Maint | + Dilla | and all | - | Elate Tur | ale | - | Dave | Danth | ă î | |
| | 44 4 x 8 Eppendorf Tube Holder 8 4 14.4378 44 4 x 8 Eppendorf Tube Holder 8 4 14.4378 45 Sciwel Statted FURF Parks 2 12 9 9 46 50 uL, Tip Box (Amplified) 12 8 9 47 95 well Non-skatted PCR Plate 3 12 8 8.95 • 48 96 well Non-skatted PCR Plate 4 12 8 8.95 • • 48 96 well Non-skatted PCR Plate 4 12 8 8.95 • • 45 17.0154 20 49 96 well Non-skatted PCR Plate 4 12 8 8.95 • • • 45 15.0426 0 • • 100 35 well Respert/Cooler Block (T1) 1 1 0 100 1 118.9746 100 1 118.9746 100 1 118.9746 100 1 118.9746 100 1 118.9746 100 1 118.9746 100 1 118.9746 100 1 118.9746 100 1 | | | | | | | | | | | | | | | |
| | 100 | 35-wel Reagent/Cool | ler Block [12] | 1 | | 0 | | | 1 | 100 | 1 | | 1 | 18.495 | 5 | |
| | 100 | | | | 3 | 0 | | | | 100 | 1 | | 1 | | | |
| | | | | | | - | | - 22 | | 1.44.9 | 1 | | | | 3 | |
| | 100 | 35-well Reagent/Cool | ier Block [T5] |] [1 | 5 | 0 | | and the second | | 100 | 1 | | 1 | 12.33 | | • |
| 4 | | | | 10 | | | | • | 4 | | | | | <u> </u> | | E. |
| Hes | th Dilletons | e. Column Offset, Role | Offset, LLS | Coopentatio | on Ba | ice Citi | iet.De | oth in Jam | I. Voka | (in in bit.) | | | | 0 | 1 | |
| | d Distan IDI | da Tupar 200 - 2001 | | 10 | | | | | | | | | | | | |
| | 200000 | | Discutor | Coale Dista | and I | Carles | Durate. | Lucia D | W.com | - LOW | est. | 00.00 | eal a | di stata | at La | 1 |
| | | | | | | | | | and the second | | | | | | | |
| - | | Carousel B | 88.57 | 0 | 1 | 1 | | -9.0256 | | 48.151 | 4 | 12.46 | 7 0 | 12 | - 6 | |
| - | | | | - | 1 | 1 | | | - | | | | | | | |
| 100 | 203 | Rotor G-100 A | 118.37 | 0 | 1 | 1 | 100 | 17.021 | | 48 | - | 50 | 0 | 3 | | |
| 1. | | | Consistent (| | | | 10000 | Protector | | 14.02 | | | | | • E | 1 |
| - | | | | | | | | | | | | | | | | |

Figure 9-71 Testing LLS Parameters under Aurora Station Settings Plate Types Tab

4. Return to the "plate types" tab again to start the LLS calibration. Then select the plate type field that you want to test by highlighting that field with your mouse. Usually the detection range field for that plate type would have been set by default, but if a new plate is entered or reset for the detection range, this value would have to be changed. To illustrate this, we first explain how to test default positions:

Step 1: Click on plate type number to test. (*Figure 9-72 Testing Default Positions under Aurora Station Settings Plate Types Tab*)

| Symn | netrical Plate | s [Plate Types: 1 - 99]> Liquid Level Sensing | | | |
|------|----------------|---|---------|------|------------|
| | Plate Type | Description | Columns | Rows | Column [🔺 |
| | 41 | 96-well Plate Filter | 12 | 8 | 9 |
| | 42 | 96-well Plate Receiver | 12 | 8 | 9 |
| | 43 | IBEX HR-HTC | 10 | 5 | 36 |
| | 44 | 4 x 8 Eppendorf Tube Holder | 8 | 4 | 14.7734 |
| ► | 45 | 96-well Non-skirted PCR Plate Adaptor | 12 | 8 | 9 🚽 |
| ¥ | | | | | |

Figure 9-72 Testing Default Positions under Aurora Station Settings Plate Types Tab



Step 2: In the rightmost table, scroll up to the corresponding plate type no. and note the depth and volume. You'd want to test from the lowest volume all the way to the highest volume. But essentially sampling/ calibrating anywhere from 12 to 16 volumes would be sufficient. (*Figure 9-73 Testing LLS Volume and Depth*)

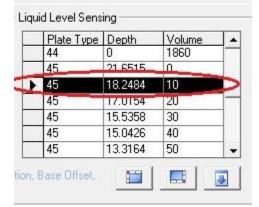


Figure 9-73 Testing LLS Volume and Depth

Step 3:Then with a manual pipette, dispense the same volume into the first well of the
plate to test. If 10μL is selected, then there should be 10μL of liquid in that well.
(Figure 9-74 LLS Calibration Check with selected Plate Type)



Figure 9-74 LLS Calibration Check with selected Plate Type

Step 4: Next click "First icon" and the robotic arm will move to pick up a tip from the specified tip position (first tip) as specified under the "advanced" tab. If you click on the second icon, the arm will pick up a tip from last well (96) of the tip box. Once a tip is automatically

engaged by the barrel, you can click "Downward arrow icon to test LLS" as shown in Figure.(Figure 9-75 Testing Depth and Volume Parameters under Aurora Station Settings Plate Types Tab)



| Plate Type 44 | 0 | 1860 | |
|------------------|---------|------|-----|
| 10 | | 1000 | |
| 45 | 21.0515 | 0 | |
| 45 | 18.2484 | 10 | |
| 45 | 17.0154 | 20 | |
| 45 | 15.5358 | 30 | |
| 45 | 15.0426 | 40 | |
| 45 | 13.3164 | 50 | 120 |

Figure 9-75 Testing Depth and Volume Parameters under Aurora Station Settings Plate Types Tab

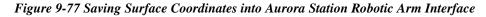
You will notice that the tip moves to a position just above the first well. By default and at all times, the tip will always move to the surface position. (*Figure 9-76 Surface Position Coordinates Achieved*)



Figure 9-76 Surface Position Coordinates Achieved

Step 5: Next you may return to Aurora Station robotic arm interface and ensure that the surface coordinates are already present in the GoX, GoY, and GoZ fields before clicking the "save" tab to save this surface position into the new line created. Highlight the field coordinates, then click the "save" button .(*Figure* 9-77 Saving Surface Coordinates into Aurora Station Robotic Arm Interface)

| 2800 - | | | | | \sim | • 5 |
|---------------|------------|---------------|----------|----------|---------------------------|-----------|
| GoX 8108 | GoY 2450 [| Go Z 5011 | D Go > | YZ Of | fset Tip Test ave 🗆 Tip (| Calibrati |
| Control | Positio | on Step (X) | Step (Y) | Step [Z] | Comment | |
| | 15 | 10495 | 2550 | 51011 | 20 µL Tip Box/Plate | |
| K + X | ▲ 16 | 273 | 75 | 47414 | Priming Position | |
| 4 4 | 17 | 287 | 1310 | 46000 | Waste Position | |
| | 19 | 87 | 2509 | 45984 | The Chute | |
| Jo Z Up 🗶 🔸 🔟 | | 8108 | 2450 | 50111 | Rename "Temp LLS Check" | |



Step 6: After saving the surface position coordinates, start working from this position for LLS calibration of individual volumes. In the arm control portion of the interface (as above), enter "10" as a value for the step and check off "no Z up".



At this point, there should be 10μ L of liquid in the well and the barrel with tip should be just above the surface of the well.

Note the signal at this position. It should be around 142 more or less. You can note the liquid level sensing signal value on the bottom right corner of the interface next to the date and time (*Figure 9-78 Level Sensing Signal check under Aurora Station Robotic Arm Interface*).

| | * | | | | a-au | • | |
|-------------------------------|----------------------|------------|--|-----|----------|---------|---------|
| | | | | | \frown | | |
| COM Ports: 6 · 4 · 5 · 7 · 10 | Temperature (°C): 25 | i.5 · 30.2 | | 142 | 5 | 9/17/09 | 3:35 PM |
| | | | | | | | |

Figure 9-78 Level Sensing Signal check under Aurora Station Robotic Arm Interface

Step 7: After making a record of this value, attempt to move the tip down with the step arrow controls. Move down and until the surface of the tip barely touches the surface of the 10µL liquid. You'll notice the signal increasing as the tip moves down.

Usually, the detection range that is set in the 'plate types' tab accounts for this and you can confirm the difference in signal detection from the plate surface to the surface of the liquid (10μ L) to be similar or close to what is set in the detection range field already set in the plate types tab for that particular plate type. (*Figure 9-79 Check signal difference under Aurora Station Plate Types Tab Detection Range Field*)

If for e.g. the signal is 154 and the surface signal is 142, then the difference is 12 +/- 1 for the detection range (limit). To check the depth offset at the surface of 10uL, first single click on the new field in Aurora Station after the visual inspection of tip touching the 10µL surface is achieved. The new coordinates would automatically be present in the GoX, GoY, and GoZ fields. You'd then click on the "offset" tab to view the offset field value (in mm). This value should correspond or be similar to the depth value for volume 10 in the rightmost table of the "Plate Types" tab. If it isn't, change of edit that value by copying and pasting the new offset into the depth field in the "Plate Types" tab rightmost table.(*Figure 9-81 Check Depth Offset (Calculator) at 10 µL with Depth Value under Aurora Station Plate Types TabFigure 9-79 Check signal difference under Aurora Station Plate Types Tab Detection Range Field)*



| | vices | | | | |
|----------------|------------|-----------------|-------|---|-----------|
| > Liquid Level | Sensing | | | | |
| Column Offset | Row Offset | Detection Range | Arr 🔺 | | Plate Typ |
| -0.7981 | -0.2826 | 7 | 100 | | 44 |
| -0.7981 | -0.2826 | 7 | 100 | | 44 |
| -108.3966 | 98.5249 | | | | 44 |
| -2.1357 | -2.877 | 30 | 100 | | 45 |
| 0.4839 | -0.348 | 12 | 30 | ► | 45 |
| | | | - | | 45 |
| | | | • | | 45 |

Figure 9-79 Check signal difference under Aurora Station Plate Types Tab Detection Range Field

| No. | Offset Calcula | tor 💌 |
|-----|-------------------|-------------|
| | Column Distance | |
| | ×1 (step) | 2579 |
| | X2 (step) | 2579 |
| | Total Columns | 2 |
| | Distance (mm) | 0 |
| | Offset (mm) | 0 |
| | Row Distance — | |
| | Y1 (step) | 5470 |
| | Y2 (step) | 5470 |
| | Total Rows | 2 |
| | Distance (mm) | 0 |
| | Offset (mm) | 0 |
| | Height Difference | e |
| | Z1 (step) | 2509 |
| | Z2 (step) | 3249 |
| | Difference (mm) | -18.2484 |
| | Offset (mm) | 18.2484 |
| | | ↓ OK |

Figure 9-80 Check Depth Offset (Calculator) at 10 µL with Depth Value under Aurora Station Plate Types Tab

| _ | Plate Type 44 | Depth 0 | Volume 1860 | - |
|---|------------------|------------|----------------|---|
| × | 45 | 21.6515 | 0 | |
| | 45 | 18.2484 | 10 | |
| | 45 | 17.0154 | 20 | |
| | 45 | 15.5358 | 30 | |
| | 45 | 15.0426 | 40 | |
| | 45 | 13.3164 | 50 | |

Figure 9-81 Check Depth Offset (Calculator) at 10 µL with Depth Value under Aurora Station Plate Types Tab

Step 8:Next check minimum level sensing at "0" depth approx. 1mm from the very
bottom of the well. Move the tip down further with the step arrow controls



until the tip surface barely touches the bottom of the well. At this point, the signal value should be similar to the surface signal value for 10μ L (as a guide).

Step 9: Once that is achieved, highlight the whole field teach position in Aurora Station after the visual inspection of tip touching approx. 1mm from the bottom of the well is achieved. The new coordinates would then automatically be present in the GoX, GoY, and GoZ fields. Then click on the offset tab to view the offset field value (in mm). This value should correspond or be similar to the depth value for volume "0" in the rightmost table of the plate types tab. If it isn't, edit that value by copying and pasting the new offset (fr.offset tab calculator) into the depth field in the "Plate Types" tab rightmost table.

| 😻 Offset Calcula | tor 💌 |
|-------------------|---------|
| Column Distance | , |
| ×1 (step) | 2579 |
| ×2 (step) | 2579 |
| Total Columns | 2 |
| Distance (mm) | 0 |
| Offset (mm) | 0 |
| - Row Distance - | |
| Y1 (step) | 5470 |
| Y2 (step) | 5470 |
| Total Rows | 2 |
| Distance (mm) | 0 |
| Offset (mm) | 0 |
| Height Difference | e |
| Z1 (step) | 2509 |
| Z2 (step) | 3279 |
| Difference (mm) | 18.9862 |
| Offset (mm | 18.9882 |
| L | 🗸 ОК |

Figure 9-82 Check Depth Offset (Calculator) at 0uL with Depth Value under Aurora Station Plate Types Tab

| | Plate Type | Depth | Volume | |
|---|------------|---------|--------|---|
| | 44 | Ω | 1860 | |
| ¥ | 45 | 21.6515 | 0 | |
| | 45 | 18.2484 | 10 | |
| | 45 | 17.0154 | 20 | - |
| | 45 | 15.5358 | 30 | |
| | 45 | 15.0426 | 40 | |
| | 45 | 13.3164 | 50 | |

Figure 9-83 Check Depth Offset (Calculator) at 0uL with Depth Value under Aurora Station Plate Types Tab

- Step 10: Perform the same steps to check for 20μL. Remember to manually pipette an additional 10μL to the same well of the plate first before moving the tip down again for the surface level depth check for 20μL.
- Step 11: You would subsequently check for 30µL using the above steps above and so on and so forth. If the checks seem within range of the depths listed in the "Plate



Types" tab rightmost table, discontinue the calibration procedures for the rest of the volumes. A rule of thumb would be to perform checks for the volumes used most frequently for any specific plate type for your work or research. Remember to have the right amount of liquid in the well when testing for that volume.

LLS calibration setup for new volumes - current or new plate type

NOTE: If a new plate type is required that cannot be found in the list of plate types in Aurora Station plate types settings tab, please consult an Aurora representative to aid in entering that plate type for you. But calibration has to be achieved once that is performed by the user. Please follow the below steps for calibration:

Steps:

1. Open Aurora Station and select a new blank or empty row for use in the coordinates table. Under the position field, type in a position number and a comment (this can be any number or name that don't coincide with the default teach positions). Leave all other fields empty and highlight the new row (*Figure 9-84 New Row Entry for Coordinates Table*)

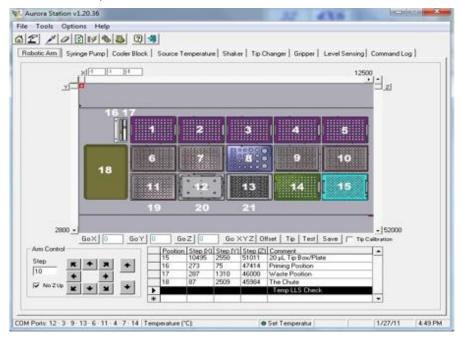


Figure 9-84 New Row Entry for Coordinates Table

2. Next click on the settings icon in Aurora Station. Focus on the topmost table to test LLS parameters. To achieve this, click on the new plate type field created for test (*Figure 9-85 Creating New Plate Type Field under Aurora Station Settings Plate Types Tab*).



| ** | whice/Plate | o (Plate Types: 1-39) | | | | | | Los | id Level Ser | (ing | | |
|----|-------------|----------------------------|------------|----------|----------|---------------|-------------|-------|------------------------------|---------|----------|-----|
| | Flore Type | Description | | Column | D Rows | | Monce + | | Flote Type | | Viawe | - |
| 14 | 62 | 6 deep Column Preserve | | 6 | 1 | 10.0612 | | | 1 | 10.0504 | | |
| 1. | 63 | 35 web Flat Joston Plat | | 12 | 10 | 2 | | | 1 | 10.3572 | | |
| 1 | 64 | 24 well Flat-bothore Plat | | 6 | 4 | 19 2606 | | 1.0 | 1 | 9.6174 | 40 | |
| 1 | 65 | 6-well Flat-bottom Plate | | 3 | 2 | 39,5209 | | | 1 | 8.631 | 60 | |
| | 66 | 45 And Ral-botton Plat | * | 0 | 6 | 13.08 | | 1 | 1 | 7.6445 | 100 | |
| • | | New Plate Type | | | | | - | | 1 | 5.9164 | 14D | |
| 4 | | | | | | | • | 12 | 1 | 4.0254 | 100 | |
| | | Arennati | | | | | | | | - 310 | <u></u> | |
| | | au Phote Types: 100 - 1 | 201 | | | | | | Level Series | 75.11 | | |
| | | Description | | Cohurses | | Hampha Dillia | - access | 11 | Plate Taxed | Johnn R | on Dwith | - |
| • | 100 | 35 well Floagavi/Coole | | | 1.0 | | | • | | 1 | 19:97:00 | |
| 22 | 100 | 35 well Floagank/Coole | | | 2 0 | | | | 100 1 | 1. | 10.495 | |
| | 100 | 35 wellflosge#/Coole | | | 2 0 | | | | 100 | 1 | 16.2796 | 3 |
| 1 | 100 | 35 well Reagent/Coole | | | 4 0 |) | | | 100 | 1 | 13:563 | |
| | 100 | 15 well Reagent/Coole | Elock [T5] | C 11 | 6 0 |) | | | 100 | (| 12.33 | |
| ٠ | | | | | | | | | 1 miles | | | |
| - | PR CENSION | s. Column Dirtse, Human | Phot LL 1 | Campinan | in, Barr | Other Co | artis part. | *** | - Antala | | 0 | |
| | | en Types: 200 - 229j | | | | | | | | | | |
| | | Description. | | | rex G | | | Anath | Bfort DG | | | £ • |
| • | 200 | Caroutel A. | | 0 | 1 | 172 | 0.1.693 | | 47.7585 | 12,2821 | 1.2 | |
| 1 | 201 | Colousell | | 0 | 1 | 32 | 9.0296 | | 40.1514 | 12,417 | 0 | |
| 1 | 202 | Plokol 6-72.4 | | 0 | 1 | 72 | 17,333 | | 43,4516 | 49.9522 | 0.8 | - |
| | 209 | Potor 6-100 A | 118.37 | 0 | 10 | 100 | 112.021 | _ | 49 | -50 | 0.9 | |
| | | Distances, Weight Differen | | | | | | | -01 | GEL | (b) 1 | e l |

Figure 9-85 Creating New Plate Type Field under Aurora Station Settings Plate Types Tab

NOTE: Columns and rows, offsets and arm parameters shown in the picture above have been left empty but after consultation with your Aurora Representative, it should be entered into the fields. Focus for the LLS calibration for the new plate type should be placed on the detection range field instead. To achieve the detection range field, refer to the following steps below:

| | vices | | | | |
|----------------|------------|-----------------|------|---|------------|
| > Liquid Level | Sensing | | | | |
| Column Offset | Row Offset | Detection Range | Am 🔺 | | Plate Type |
| -0.7981 | -0.2826 | 7 | 100 | | 44 |
| -0.7981 | -0.2826 | 7 | 100 | | 44 |
| -108.3966 | 98.5249 | | | | 44 |
| -2.1357 | -2.877 | 30 | 100 | | 45 |
| 0.4839 | -0.348 | 12 | 30 | ► | 45 |
| | | | - | | 45 |
| | | | • | | 45 |

nt Difference, Column Offset, Row Offset, Depth in (mm), Volume in (μL)

Figure 9-86 Detection Range Field under Aurora Station Settings Plate Types Tab

3. First ensure that the test position for both the tip box and plate type are set by clicking onto the "advanced" tab in Aurora Station Settings. To change or set it, click on the arrow to open options and select the position of choice. Remember that if you select for position 1 (as an example) for $20/50/200 \mu$ L tip box that you must place a tip box in position 1 on the deck available. You will need to "reload" tip boxes. The same goes for the plate type you want to test. If the test position for your plate is selected as 5, the appropriate plate type for test should be in that position (*Figure 9-87 Setting the Tip Box Position and Plate Position for Calibration*).





| arasal Advanced Accessories Plate Types Hardw | | |
|---|---|------------------------------------|
| Tip Engagement (Flobotic Aux) | Shoker | Springe Pump |
| Stat Speed (step/s) 50 | Start Spaced (steps/s) 100 | T Pure Connected to Are |
| End Speed (step/s) 500 | Acceleration (step/s ²) [10 | PumpDavice 0 |
| Acceleration (step/o ²) | | Device Addecs (hex) |
| | Constantiation | |
| Parapert/Cooler Block | Step Loso Exor Count. 10 | Positions (Exclude X, Y, 2 0 Ever) |
| Cooler Address 1 • Charred 1 • | Time Out Early Count 10 | * Postion |
| Position 8-Reagent/CoolerBlock | Tilt Time Ouk (s) 60 | |
| Coder Control Delay (Ink) 10000 | 2nd Time Out (s) 240 | |
| | Commend Delay (Ins) 100 | |
| Source Temperature | Are Address (hea) | |
| Source 1 Addens 1 . Cherrel 2 . | Device Address (hes) 38 | Pt Auto Recovery |
| Postion 7 - Source/Target Plats + | | P Renove kontralisization |
| Source 2 Address 2 + Duarnel 2 + | | T Double PI Auto Recovery |
| | Auto Recovery | Saince Plano |
| Position 9-Source/Target Plate | X-D#set [step] 2400 | T 100 ul. Small Syringer Punet |
| Chule Dienitation | Tip Divergegeneral | C 250 ut. Small Sympe Pump |
| IF YARE C XAsis | V-Ottoet (dep) 800 | C Small Syringe Pump Drile |
| | | |
| Test Position (Plate Lape) | Plate Type [Teaching Routicos] | Position Test Mode |
| Politin 5-Sounce/Target Plate | Plate Tope Problem Plate | Single Drawed Test |

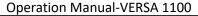
Figure 9-87 Setting the Tip Box Position and Plate Position for Calibration

5. Next, ensure that new fields are entered for calibration of LLS for the new plate type, inputing several volumes starting from 0 in increments of 10 μ L. Depth will be calculated afterwards. If a new plate type is entered e.g. 46, then enter 46 in the new fields under plate type and for each entry, enter a corresponding volume value in increments of 10 μ L.

| | Plate Type | Depth | Volume | |
|---|------------|-------|--------|---|
| | 45 | 0 | 340 | _ |
| | 47 | 0 | 0 | |
| | 47 | 0 | 10 | |
| | 47 | 0 | 20 | _ |
| | 47 | 0 | 30 | |
| | 47 | 0 | 40 | |
| • | 47 | q | 50 | |

Figure 9-88 Entering New Plate Type Numbers with Corresponding Volumes prior to LLS Calibration Test

- 5. Start calibrating with $0 \mu L$, then $10 \mu L$, then $20 \mu L$ and so on. Return to the 'plate types' tab (leftmost table) to start the LLS calibration. Highlight the plate type row that you want to test by clicking on that row. The detection range field for that plate type would have to be set if a new plate is entered. To illustrate this, we first explain how to test default surface position:
- Step 1: Click on the plate type number to test (note that the all offsets at this point would have been entered by your Aurora representative for a new plate type.





All you need to do is test the default surface position and set the detection range.

| _ | Plate Type | Description | Columns | Rows | Column Distance | |
|---|------------|---------------------------|---------|------|-----------------|---|
| | 62 | 6-deep Column Reservoir | 6 | 1 | 18.0512 | - |
| | 63 | 96-well Flat-bottom Plate | 12 | 8 | 9 | |
| | 64 | 24-well Flat-bottom Plate | 6 | 4 | 19.2606 | |
| | 65 | 6-well Flat-bottom Plate | 3 | 2 | 39.9209 | |
| | 66 | 48-well Flat-bottom Plate | 8 | 6 | 13.08 | - |
| • | 67 | New Plate Type | | | | |
| 4 | | | | | - F | Γ |

Figure 9-89 Highlight Row of New Plate Type

Step 2: In the rightmost table, scroll up to the corresponding plate type no. and note the depth and volume (in this case $10 \ \mu$ L). Then test for the unknown depth value along with the detection range. Also test from the lowest volume all the way to the highest volume (or top surface of the well).

| | Plate Type | Depth | Volume | 4 |
|---|------------|-------|--------|---|
| | 45 | 0 | 340 | - |
| | 47 | 0 | 0 | |
| | 47 | 0 | 10 | > |
| | 47 | 0 | 20 | _ |
| | 47 | 0 | 30 | - |
| | 47 | 0 | 40 | |
| • | 47 | Q | 50 | |

Figure 9-90 Start the Calibration by Highlighting the Row with 10uL Volume under Aurora Station Plate Types Tab

Step 3: With a manual pipette, dispense an equal amount of that volume into the first well of the plate to test. If 10 μ L is selected, then there should be 10 μ L of liquid in that well.





Figure 9-91 LLS Calibration Check with selected New Plate Type

Step 4: Next click "Tip" and the robotic arm will move to pick up a tip from the specified tip position. Once a tip is automatically engaged by the barrel, you can click "test".

| | Plate Type | Depth | Volume | |
|---|------------|---------|--------|---|
| | 44 | 2.7126 | 1680 | _ |
| | 44 | 0 | 1860 | |
| | 45 | 21.6515 | 0 | |
| • | 45 | 18.2484 | 10 | - |
| | 45 | 17.0154 | 20 | |
| | 45 | 15.5358 | 30 | |
| | 45 | 15.0426 | 40 | - |

Figure 9-92 Tip Engagement and Surface Test

Notice that after the barrel with tip moves to position itself just above the first well. By default and at all times, the tip would always move to the surface position.



Figure 9-93 Surface Position Achieved

Step 5: Next return to the Aurora Station robotic arm interface and ensure that the surface coordinates are already present in the GoX, GoY, and GoZ fields before clicking the "save" tab to save this surface position into the new row that was originally created. Then click the "save" button.



| 7970 <u>-</u> GoX 2579 Go1 | r 54 | 70 Go | Z 2509 | Go > | (YZ Of | fset Tip Test Save 🔽 Ignore | r Tip |
|----------------------------|-------------|--------------|---------------|----------|----------|-----------------------------|-------|
| Arm Control | | Position | Step (X) | Step (Y) | Step (Z) | Comment | |
| Step | | 10 | 1653 | 240 | 5131 | Waste Position | |
| | | 11 | 724 | 307 | 1590 | The Chute | |
| | | 12 | 3071 | 7645 | 3283 | Magnet Plate Mover | |
| ▼ NoZUp be the be | | 13 | 5475 | 7640 | 3308 | Shaker Plate Mover | |
| | • | 171 | 2579 | 5470 | 2509 | Rename to "Temp. LLS Check" | |
| | * | | | | | | - |

Figure 9-94 Saving Surface Coordinates into Aurora Station Robotic Arm Interface

Step 6: After saving the surface position coordinates, start working from this position for LLS calibration of individual volumes. In the arm control portion of the interface (as in figure above), enter "10" as a value for the step and check off "no Z up". At this point, there should be 10 μL of liquid in the well and the barrel with tip should be just above the surface of the well.

Note the signal at this position. Let's use 142 as an example to illustrate for now. You can note the liquid level sensing signal value on the bottom right corner of the interface next to the date and time.



Figure 9-95 Level Sensing Signal check under Aurora Station Robotic Arm Interface

Step 7: After making a record of this value, attempt to move the tip down using the step arrow controls. Move the tip down until the surface of the tip barely touches the surface of the 10 μL liquid. You will notice the signal increasing as its tip moves down. Note the signal value.

To illustrate this, we'll use 155 as the signal value when the tip touches the surface of the 10 μ L liquid. If for e.g. the signal is 155 and the surface signal is 142, then the difference is 12 +/- 1 for the detection range (limit). Click on the "plate types" tab and enter the detection range as 12 or 13 in the detection range field.

Click "apply" and then "ok" to save the new setting. Then to check the depth offset at the surface of 10uL, first single clicking on the newly entered field in Aurora Station after the visual inspection of the tip touching the10uL surface is achieved (*Figure 9-98 Check (Offset Calculator) and Enter New Depth Offset for 10uL Volume*). The new coordinates will automatically be present in the GoX, GoY, and GoZ fields. Then click on the "offset" tab to view the offset field value (in mm). This value should be entered in the depth field for volume 10 in the rightmost table of the "Plate Types" tab. To perform this, copy the new offset



(using the offset tab calculator) and paste them into the depth field in the "Plate Types" tab rightmost table.

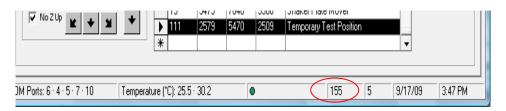


Figure 9-96 Signal at 10uL Surface Noted under Aurora Station Plate Types Tab

| te Types Dev > Liquid Level | vices | | | | |
|----------------------------------|------------|-----------------|-------|---|------------|
| > Liquio Lever | sensing | | | | |
| Column Offset | Row Offset | Detection Range | Arr 🔺 | | Plate Type |
| -0.7981 | -0.2826 | 7 | 100 | | 44 |
| -0.7981 | -0.2826 | 7 | 10C | | 44 |
| -108.3966 | 98.5249 | | | | 44 |
| -2.1357 | -2.877 | 30 | 10C | | 45 |
| 0.4839 | -0.348 | 12 | 30 | ► | 45 |
| | | | - | | 45 |
| | | | • | | 45 |
| | | | | | |

nt Difference, Column Offset, Row Offset, Depth in (mm), Volume in (μ L)

Figure 9-97 Enter Signal Difference under Aurora Station Plate Types Tab Detection Range Field

| 😻 Offset Calcula | tor 🚬 |
|------------------|----------|
| Column Distance | |
| ×1 (step) | 2579 |
| ×2 (step) | 2579 |
| Total Columns | 2 |
| Distance (mm) | 0 |
| Offset (mm) | 0 |
| - Row Distance - | |
| Y1 (step) | 5470 |
| Y2 (step) | 5470 |
| Total Rows | 2 |
| Distance (mm) | 0 |
| Offset (mm) | 0 |
| Height Differenc | e |
| Z1 (step) | 2509 |
| Z2 (step) | 3249 |
| Difference (nm) | -18.2484 |
| Offset (mm) | 18.2484 |
| | 🖌 ок |

Figure 9-98 Check (Offset Calculator) and Enter New Depth Offset for 10uL Volume

.

4



| | Plate Type | Depth | Volume |
|---|------------|---------|--------|
| | 47 | 0 | 0 |
| • | 47 | 18.2484 | 10 |
| - | 47 | 0 | 20 |
| - | 47 | 0 | 30 |
| - | 47 | 0 | 40 |
| - | 47 | 0 | 50 |
| | 47 | 0 | 60 |

tion, Base Offset,

Figure 9-99 Check (Offset Calculator) and Enter New Depth Offset for 10uL Volume

1

- Step 8: Next check the minimum level sensing at "0" depth for approx. 1mm from the very bottom of the well. Move the tip down further with the step arrow controls till the tip surface barely touches the bottom of the well. At this point, the signal value should be similar to the surface signal value for 10 μL (as a guide).
- Step 9: Once that is achieved, highlight the whole field teach position in Aurora Station after the visual inspection of tip touching approx. 1mm from the bottom of the well is achieved. The new coordinates would then automatically be present in the GoX, GoY, and GoZ fields. Next, click on the offset tab to view the offset field value (in mm). This value should be entered in the depth field for volume 0 in the rightmost table of the "Plate Types" tab. To perform this, copy the new offset (fr. offset tab calculator) and paste into the depth field in the "Plate Types" tab rightmost table.



Figure 9-100 Check (Offset Calculator) and Enter New Depth Offset for 0uL Volume

| | Plate Type | Depth | Volume | - |
|---|------------|---------|--------|---|
| | 45 | 0 | 340 | - |
| | 47 C | 18.9882 | 10 | |
| | 47 | 18.2484 | 20 | |
| | 47 | 0 | 30 | - |
| | 47 | 0 | 40 | |
| | 47 | 0 | 50 | |
| • | 47 | 0 | 60 | |

Figure 9-101 Check (Offset Calculator) and Enter New Depth Offset for 0uL Volume

- Step 10:Perform the same steps above to check and input depth value for 20uL.Remember to manually pipette an additional 10uL to the same well of the platefirst before moving the tip down again for the surface level depth check for20uL.
- Step 11: Subsequently check and input the depth value for 30uL using the above steps. Continue adding in 10uL increments and perform all the necessary steps for offsets at each until the top of the well is reached. A good rule of thumb would be to perform checks for the volumes used most frequently regarding a specific plate type for your work or research. Remember to have the right amount of liquid in the well when testing for that volume.

Below is the table showing dead volumes for various plate types/vials/tubes/reservoirs etc.



| Plate ID | Plate Description | Dead Volume (μL) |
|----------|--|---------------------|
| 1 | 96-well Plate | 34 |
| 2 | 384-well Plate | 26 |
| 4 | 12-column Reservoir | 910 |
| 8 | 35-vial Holder | 141 |
| 10 | 35-tube Holder | 57 |
| 11 | 96-deep Round Well Plate (H: 43.57 mm) | 44 |
| 12 | 96-well Skirted PCR Plate 1 | 14 |
| 13 | 384-well PCR Plate | 3 |
| 14 | 12-deep Column Reservoir | 995 |
| 17 | 4-deep Column Reservoir | 1,665 |
| 19 | 48-tube Holder | 57 |
| 27 | 48-tube 1.5 mL Holder (Eppendorf) | 22 |
| 34 | 48-vial Holder | 141 |
| 37 | 192-PCR Tube Block | 13 |
| 44 | 4 x 8 Eppendorf 1.5 mL Tube Holder | 22 |
| 45 | 96-well Skirted PCR Plate 2 | 12 |
| 47 | 96-well Non-skirted PCR Plate 3 | 13 |
| 48 | 96-well Non-skirted PCR Plate 4 | 12 |
| 52 | 96-deep Square Well Plate (H: 43.91 mm) | 43 |
| 53 | Roche Magnapure-32 | 27 |
| 54 | 96-tube Holder (Micronic) | 26 |
| 55 | 48-screwtop 1.25 mL Tube Holder (Sigma) | 44 |
| 56 | 96-deep Round Well Plate (H: 31.36 mm) | 43 |
| 57 | 96-deep V-bottom Round Well Plate (H: 35.91 mm) | 21 |
| 58 | 96-deep Round Well Eppendorf Plate (H: 43.95 mm) | 34 |
| 59 | 96-well Skirted PCR Plate 5 | 13 |
| 60 | 96-well Skirted PCR Plate 6 | 14 |
| 61 | 96-well Non-skirted PCR Plate 7 | 14 |



| Plate ID | Plate Description | Dead Volume (μL) |
|----------|---|---------------------|
| 62 | 6-deep Column Reservoir | 1,101 |
| 63 | 96-well Flat-bottom Plate | 73 |
| Plate ID | Description | Dead Volume (μL) |
| | | |
| 101 | 39-well Reagent/Cooler Block [T1 - T16] | 10 |
| 101 | 39-well Reagent/Cooler Block [S1 - S12] | 19 |
| 101 | 39-well Reagent/Cooler Block [R1 - R5] | 22 |
| 101 | 39-well Reagent/Cooler Block [M1 - M5, W] | 150 |

Figure 9-102 Dead volume for various plate types

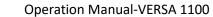
9.16. Aurora Station Settings

Click the Aurora Station Settings icon is to configure settings of the system. The figure (*Figure 9-103 Aurora Station General Settings Tab*) below displays the window for the Aurora Station Settings. Browse through the tabs for additional settings, and click "Apply" to implement the setting.

General Settings

The general settings tab can be used to assign deck positions like priming, waste and the tip chute.

NOTE: These settings are pre-configured and should optimize the performance of your instrument. Contact Aurora Biomed should you need to make some changes. Ensure that you click "Apply" to implement any changes in the settings.



| Application | - Robotic Arm |
|---|-------------------------------|
| Title Aurora Station | Bight Arm |
| Aurora Station Type 5 - VERSA 1100A | Error Handling |
| | Step Loss Auto Recovery |
| Positions | Resume After Time Out |
| Priming Position 17 - Waste Position | ▼ Database |
| Waste Position 17 - Waste Position | Compact Database |
| | Error Records 1000 |
| Tip Chute 18 - Tip Chute | ▼ , |
| Test Position Delay (ms) 🛛 🔽 Display A | spirator Aurora Dispatcher |
| 🔽 Display RD Priming Position 🛛 🔽 Display B | lead Mixer Device ID AS01 |
| Log | Display Options |
| 🔽 Display Command Log | 🔽 Display Syringe Pump |
| 🔽 Save Command Log | ✓ Display Cooler/Heater Block |
| 🔽 Include Dispatcher Log | Display Source Temperature A |
| 🔽 Display Temperature Log | 🔽 Display Shakers |
| 🔽 Display Level Sensing Log | 🔲 Display Plate Mover |
| 🔲 Display Raw Data Log | Display Tip Changer |
| 🔲 Save Raw Data Log | ✓ Display Gripper |
| Log Lines 1000 | Display Vacuum Manifold |
| | Display Liquid Level Sensing |
| Display Options | Display Magnet Elevator |
| Display Source Temperature B | Display Ultrasonic Sensor |

Figure 9-103 Aurora Station General Settings Tab

Advanced Settings

rora

LUMINATING SOLUTION

In this tab (*Figure 9-104 Aurora Station Advanced Settings Tab*), changes regarding Tip Engagement (speed), Cooling Block, Shaker (speed), Communication, Auto Recovery, Tip Disengagement, Air Gap adjustment etc. can be performed. However, it is strongly recommended not to change the pre-setting parameters. In most cases, end users only need to use the "Test Position" button to perform testing and offset adjustment for other plate types from plate type tab. Here user will set test position on the deck where any new other plate type is placed to check its position from plate types. Remember to click "Apply" to implement any changes made.



| | Shaker | Syringe Pump |
|--|-------------------------------------|--|
| Start Speed (step/s) 50 | Start Speed (step/s) 100 | Pump Connected to Arm |
| End Speed (step/s) 500 | Acceleration (step/s ²) | Pump Device 0 |
| Acceleration (step/s ²) | , | Device Address (hex) 31 |
| | Communication | |
| oler/Heater Block | Step Loss Error Count 10 | Positions [Exclude X, Y, Z-Offsets] |
| Cooler: Address 1 Channel 1 | Time Out Error Count 10 | Position ▶ 13 |
| Position 10 - Source/Target Plate 💌 | 1st Time Out (s) 60 | 16 |
| Heater: Address 1 - Channel 2 - | 2nd Time Out (s) 240 | Chute Orientation |
| Position 12 - Heater Shaker/96-deep Well Plate 🔻 | Command Delay (ms) 100 | |
| | Arm Address (hex) 31 | |
| emperature control Delay (ms) [10000 | Device Address (hex) 38 | PI Auto Recovery |
| urce Temperature A | Cooler Time Out (s) 90 | Remove from Initialization Double PI Auto Recovery |
| ource 1: Address 1 🗸 Channel 1 🚽 | Auto Recovery | |
| Position 7 - Cooler Plate 2 | X-Offset (step) 2400 | Syringe Pump |
| | ((((()))) [2400 | 🔲 100 uL Small Syringe Pump |
| | Tip Disengagement | 250 uL Small Syringe Pump |
| Position 8 - Reagent/Cooler Block | Y-Offset (step) 800 | 🔲 Small Syringe Pump Only |
| st Position [Plate Type] | Plate Type [Teaching Positions] | Position Test Mode |
| Position 11 - Magnetic Stand | Plate Type 1 - 96-well Plate 💌 | 🔲 Single Channel Test |

Figure 9-104 Aurora Station Advanced Settings Tab

NOTE: Increased robotic arm speed and acceleration may result in step loss or arm failure.

Accessory Settings

The Tip Box positions, record the used tips and remaining tips is in the "Tip Box Positions" box as shown below. In 'Pipetting Tip Types' table, tip parameters are recorded such as engagement offset, depth (how deep barrel goes into the tip to engage it, tip length, and the X/Y offsets for different tip types.

Pin Groups and Shaker configurations are tabulated as shown in below(*Figure 9-105 Aurora Station Accessories Settings Tab*). Depending on the configuration of the system and the modules in the workstation, some of these options may not apply. These settings come pre-configured for your specific applications. Check with Aurora Biomed for application specific development.



| ip B | ox Position | | | | | | | | | | | | | _ |
|-------|---------------|-----------------------|----------|------------|---------|----------------|---------|-----------|----------------------------------|------------|-----------|------------|------------|---|
| | Tip Box P | osition Tip Type | Tip Box | Type Co | olumn 1 | | olumn | 3 Column | | | | 7 Column 8 | Column 9 | • |
| ▶ | 1 | - | 21 | 1 | | 1 1 | | 1 | 1 | 1 | 1 | 1 | 1 | - |
| | 2 | | 21 18 | 1 | | 1 1 | | 1 | 1 | 1 | 1 | 1 | 1 | |
| | 3 | | 18 21 | 1 | | 1 1 1 1 | | 1 | 1 | 1 | 1 | 1 | 1 | |
| | 4 | | 21 | 1 | | 1 1 | | 1 | 1 | 1 | 1 | 1 | 1 | |
| | 6 | | 21 | 1 | | 1 1 | | 1 | 1 | 1 | 1 | 1 | | - |
| 4 | 0 | 3 | 22 | | | I I | | | | <u> I</u> | <u> </u> | | | • |
| • | | | | | | | | | | | | | | |
| | | | | | | | | | | | | | | - |
| Pipet | ting Tip Typ | Des | | | | | | | | | | | | - |
| | Tip Type | Description | | Tip Box | Type E | Engagement C |)ffset | Disengage | ement Offset | Engageme | ent Depth | Tip Length | Offset (X) | • |
| | 1 | 20 uL Tips (1-ch | annel) | 6 | 6 | | | 12 | | 12 | • | 31.74 | 0 | |
| | | 20 uL Tips (8-ch | | 20 | 6 | | | 12 | | 11 | | 31.74 | 0 | |
| | | 20 uL Tips (4-ch | | 88 | E | 6 | | 12 | | 10.8 | | 31.74 | 0 | |
| | | 1000 uL Tips (1-0 | | | 6 | | | 12 | | 13 | | 95.82 | 1 | |
| | | 1000 uL Tips (8-0 | | | 6 | | | 12 | | 13 | | 95.82 | 1 | |
| | 2 | 1000 uL Tips (4-0 | channel) | 85 | 6 | 6 | | 12 | | 8.5 | | 95.82 | 0. | • |
| • | | | | | | | | | | | | | • | |
| _ | iroups | ffset, Disengagen | | | | | igth, (| | lffset (Y) in (r ker Scale/Sp | | | | | |
| | | Description | |)ffset (X) | Offset | (Y) Offset [Z] | • | | Shaker Sc | ale Shake | r Speed | | | |
| | 4 | Tip Barrel #5 | 0 | | -35,900 | | | | 1 | 0 | | | | |
| | 7 | Aspirator | - | 10 | 6 | -170 | | | 2 | 450 | | | | |
| | 8 | Tip Barrel #8 | - | l.5 | -62.5 | 0 | | | 4 | 900 | | | | |
| | 11 | Tip Barrel #1 | 0 | | 0 | 0 | | | 8 | 1300 | | | | |
| | 12 | Pin #1 | | 16 | -62 | -10 | | | | | | | | |
| | 13 | Pin #2 | | 16 | -67 | -10 | - | | | | | | | |
| | et (X). Offse | et (Y), Offset (Z) in | n (mm) | TTT | ip Test | 📔 😭 RD Te | est | Sh | aker Speed i | n (rpm) | | | | |

Figure 9-105 Aurora Station Accessories Settings Tab

Plate Types Settings

All Plate Type configurations are tabulated in the 'Plate Types Settings' Tab as shown above. Depending on the configuration of the system and the modules in the workstation, some of these options may not apply.

When entering a new plate, enter all relevant information in the symmetrical plates section. Base the offset of the new plate on the 96 deep-well plate. Accurately enter the offset difference (as compared with the 96-well plate) allows the workstation to adjust accordingly regardless of the differing depth of the plates on the deck.

Start with measuring the height difference between your new plate against a standard 96-well plate and enter the difference in mm into the field. Next calculate for X and Y offsets by placing the new plate onto the deck; and using Device Manager AS to move the arm. Figure out the offset distance with the step arrow control or offset calculator of the syringe barrel to the top surface of the new plate.



| nmetrical P | lates [Plate Types: 1 - 99, 400 | - 499] | | | | | — Liq | uid Level Se | nsing —— | | |
|--|--|----------------------------|----------------------------|---------|--------------------------|--------------|------------------|--------------|---------------|-------------|----------|
| Plate T | pe Description | | Columns | Row: | s Column | Distance 🔺 | | Plate Typ | e Depth | Volume | |
| 1 | 96-well Plate | | 12 | 8 | 9 | _ | | 1 | 10.8504 | | |
| 2 | 384-well Plate A | | 24 | 16 | 4.5 | | | 1 | 10.3572 | 20 | |
| 3 | 1536-well Plate (Corning) [| no LLS] | 48 | 32 | 2.25 | | | 1 | 9.6174 | 40 | |
| 4 | 12-column Reservoir | | 12 | 1 | 9 | | | 1 | 8.631 | 60 | |
| 5 | 4-glass Slide Tray (X: 4.60 | 98, Y: 4.46 | 5,4 | 1 | 31.5784 | | | 1 | 7.6446 | 100 | |
| 6 | 20 uL Tip Box (1-channel) | | 12 | 8 | 9.05 | | | 1 | 5.9184 | 140 | |
| • | | | | | | | | 1 | 4.6854 | 180 | - |
| Jump Dista | nce, Row Distance, Height Di | | Column Offic | at Da | Officer | | Sort | by Plate Typ | e . | en l'anna l | |
| acking Off | ince, How Distance, Height Di set, LLS Compensation, Base (| rrerence, u Tifset: Der | Joiumn Orrs ath in (mm) | Volum | w orrset, he in ful 1 | A V ' | | (mm) 0 | | | <u> </u> |
| donting on | 500, 220 00mpontodion, 2000 (| 511000, 5 0, | | 1 Ordin | io in (oc) - | | 000 | (1111) 10 | | | |
| mmetrical l | Plates (Plate Types: 100 - 199) | | | | | | - Liguio | d Level Sens | ing | | |
| Dista T. | vpel Description | | I Calvered | D | Height Diff | erence 🔺 | · | Plate Type | - Column P | ow Dopth | |
| 100 | 35-well Reagent/Cooler Bl | ock [T1] | | | neigni Din D | | • | 100 | 1 1 | 21.6154 | |
| 100 | 35-well Reagent/Cooler BI | | 1 | 2 | - N | | ŕ | 100 | 1 1 | 18.2114 | |
| 100 | 35-well Reagent/Cooler Bl | | | | | | | 100 | 1 1 | 15.8286 | |
| 100 | 35-well Reagent/Cooler BI | | | - | - 0 | | | 100 | 1 1 | 14,2968 | |
| 100 | 35-well Reagent/Cooler BI | | 1 | 5 | 0 | • | | 100 | 1 1 | 12.0842 | - |
| | | | | | | | 1 | | I | | |
| | | | | | | | | · | | | |
| eight Differ | ence, Column Offset, Row Offs | et, LLS Co | ompensatio | n, Bas | e Offset, D | epth in (mm) |) | Z-Offset (m | m) 0 | • | <u> </u> |
| | | | | | | | | | | | |
| | [Plate Types: 200 - 299] | | | | | | _ | | | | |
| und Plates | | | Circle Distan | nce C | | ls Height D | <u>iffere</u> nd | |) Offset (Y) | Adjustment | |
| Plate T | 32-well Carousel A [no L] 8 | | | 1 | 32 | -9.1489 | | 47.7595 | -13.3931 | 0 | |
| Plate Ty 200 | | 3.57 0 | | 1 | 32 | -9.0256 | | 48.1514 | -12.467 | 0 | |
| Plate T 200 201 | 32-well Carousel B [no L 8 | | | 1 | 72 | 17.111 | | 49.8016 | -48.8 | 0 | |
| Plate T 200 201 202 | 32-well Carousel B [no L 8 Rotor G-72 A [no LLS] 1 | 19.42 0 | | | 1100 | 17.021 | | 48 | -50 | 0.3 | - |
| Plate T 200 201 | 32-well Carousel B [no L 8 | 19.42 0 | | 1 | 100 | 17.021 | | | | | |
| Plate T 200 201 202 203 | 32-well Carousel B [no L 8 Rotor G-72 A [no LLS] 1 | 19.42 0 | | 1 | 100 | 17.021 | | | | | • |
| Plate T 200 201 202 202 203 | 32-well Carousel B [no L 8 Rotor G-72 A [no LLS] 1 | 19.42 0 18.37 0 | | | 1.11 | | | 6 | | | |

Figure 9-106 Aurora Station Plate Types Settings Tab

NOTE: The settings in your software come pre-configured for your specific applications. Check with Aurora Biomed for application specific development

Hardware Settings

In this window (*Figure 9-107 Aurora Station Hardware Settings Tab*), the devices attached to the workstation along with the associated COM ports are configured. Speed and acceleration steps of the robotic arm and pump can also be configured. Maximum moving range of the Robotic Arm has already been set and configured. All adaptors used for different PCR plates, magnetic blocks etc. are configured here under Plate/Tip Box Adaptors. Click "Apply" to implement any changes made in this window.



| Devi | ce Description | COM Port | Serial Number | Bange (X) | Bange (Y |) Bange (Z) | Start Speed (X) | End Speed (X) | |
|---|--|---|---------------|----------------------------|---|-----------------------|--|---------------|--|
| 0 | Syringe Pump (250 uL) | 10 | FTU3N93DD | 40000 | | | 10 | 1000 | |
| 1 | Robotic Arm | 9 | FTU3N93DC | 12100 | 2700 | 7800 | 50 | 1500 | |
| 3 | Syringe pump (8 × 250 uL) | 10 | FTU3N93DD | 40000 | | | 10 | 1000 | |
| 4 | Gripper Arm | 3 | FTTA2B7NA | 46000 | | | 100 | 1500 | |
| 5 | Magnet Elevator | 7 | FTU3N93DD | 30000 | | | 50 | 1500 | |
| 6 | N2 Dryer Valve | 8 | FTTA2B7NA | | | | | | |
| • | | | | | | | | • | |
| 2 3 4 5 6 7 | 96-well PCR Plate Adaptor B 96-well PCR Plate Adaptor (f 96-well Magnetic Stand 24-spike Magnetic Stand Ambion Magnetic Stand-96 12-column Reservoir Adapto | Fixed) | | 11 12 45 47 48 | 0 0 0 0 | 0 0 0 0 0 | -15.2399 -9.9735 -14 -9.764 -14.5865 | 10 9 11 | |
| 8×1 8×5 15-pc mware 0 New | 00A Settings 1000 uL Syringe Pump 500 uL Syringe Pump osition Deck Layout Iptions Motor Board Firmware Valve Switch Command | Resend Corr Resend Cour Error C * Middle Row Y-Offset (ste | int 0 | Syrir | ge Pump (F Pump St 0 50 2 50 3 50 | Priming/Air G | R = Detection Ra iap] | | |

Figure 9-107 Aurora Station Hardware Settings Tab

10.VERSA 1100 Main Interface

- 1. Menu drop-downs
- 2. Short cuts
- 3. Deck configuration
- 4. Assay/Sequence folder window 9. Tip T
- 6. Sequence Steps window
- 7. Single channel or 8-channel mode change icon
- 8. Lab ware Library
 - 9. Tip Transfer for single channel boxes
- 5. Application Tabs



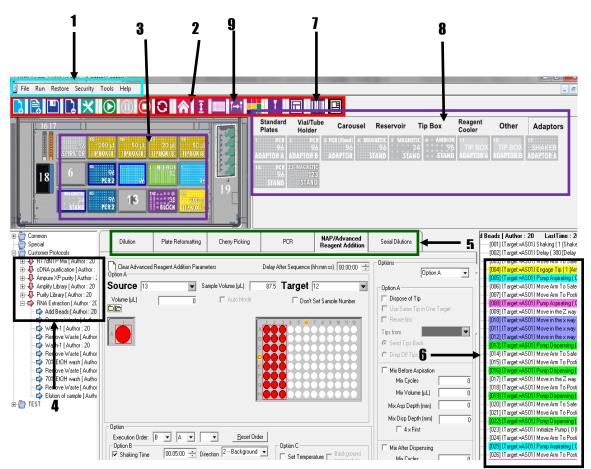


Figure 10-1 VERSAWare Main Interface

Menu Drop-downs – consists of the File, Run, Tools and Help functions.

Icon Shortcuts – provides direct functions like adding, deleting and saving assay/sequence; starting, pausing and stopping assay/sequence runs; and reloading tips

Deck configuration – configuring the deck for use with 96, 384 well plates and reservoir

Saved Assay/Sequence – Lists all the assay/sequence created which can be accessed and used anytime when required

Application Tabs – consists of the applications Dilution, Plate Reformatting, Pooling Application, Cherry Picking, PCR and Advanced Reagent Addition

Sequence Steps – provides the series of commands when running an assay sequence file

Tips Channels Number – Selects Single-Channel or 8-Channel Head for use in the application Tabs.

Lab-ware Library – Lists of Plate types, Tip Boxes, Adaptors and Vail/tube Holders.

Tip Transfer – Helps user to transfer tips with robotic arm from 8-channel tip box to single channel tip box.



10.1. VERSAware Drag-Drop Plate Library

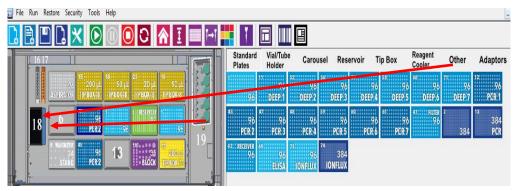


Figure 10-2 VERSAware Deck Configuration and Plate Library

Aurora has accounted for a wide array of plate types found in the market. These have been configured for use on the VERSA platform to allow users to aspirate from and dispense into. Offsets have also been pre-set during the manufacturing and testing process, thus they are ready to use without any further user intervention needed.

To use a particular plate, move the mouse cursor to that plate's icon located in the plate library on the right side of the main interface screen, click and drag it to the working deck on the left side of the plate library. Release the left mouse button to drop the icon onto any numbered position (1 to 15) on the deck.

Special plates for e.g. the 96 PCR 1, 96 PCR 2, 96 PCR 3 and 96 PCR 4 need to be placed on top of adaptors to be utilized. To view images of these plates before use, right click the plate in the plate library and a pop-up image of the plate will be displayed (*Figure 10-3 VERSAware Plate Library – 96 PCR 2*).

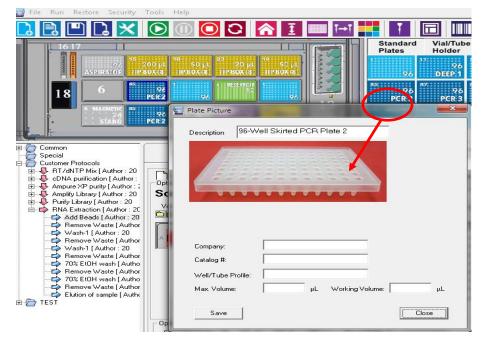


Figure 10-3 VERSAware Plate Library – 96 PCR 2



The above figure depicts the preview picture of 96 PCR 2 plate. We advise using 96 PCR 2, 3 and 4 with adaptors A or B. Please note that the 96 PCR 1 plate can be used directly placed onto the deck without using adaptor. For the use of a plate with an adaptor follow the instructions below:

First select adaptor plate A or B to be used.

Drag and drop one of them (eg. Adaptor B) onto the deck configuration.

Next, select the plate to be uses (e.g. 96 PCR 3) and drag-drop this icon onto adaptor which you previously dropped onto the deck.

When that happens, the 96 PCR 3 will be present for use on the deck and you'd see a colored shadow around the plate. This indicates a plate and adaptor combo as shown in the figure below (*Figure 10-5 VERSAware-Create New Folder*).

VERSAware software has folders, Two folder named as "Common" and "Special" are prespecified in the software (*Figure 10-4 VERSAWare folders*).

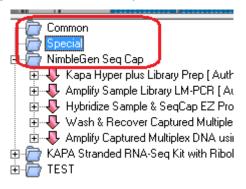


Figure 10-4 VERSAWare folders

VERSAware-pre-specified Folders-common and Special

User can create new folders by right clicking as shown below (*Figure 10-5 VERSAware-Create New Folder*). There are other options too like add message at the end of the sequence (this option must be clicked on from OPTIONS-Other tab), delete, copy, cut/paste any assay or sequence. Sample number can also be in an assay. Assays/sequences can be renamed, imported and saved.



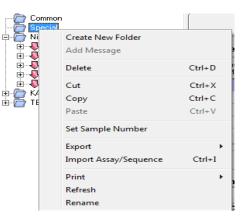


Figure 10-5 VERSAware-Create New Folder

Assays are created under the folder from this icon LO of the tool bar as shown below:

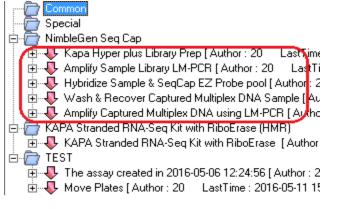


Figure 10-6 VERSAware-Create New Assay



Sequences are created from this + icon of the tool bar and saved under Assays to create all the liquid handling steps as shown below:



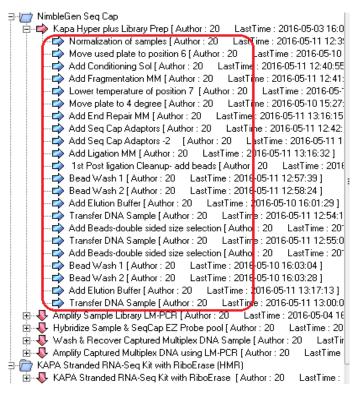


Figure 10-7 VERSAware- Create Sequences/write protocols

There are a total of 17 user icons available for "one-click" operation(s) which will be further explained below:



Figure 10-8 VERSAware Icon Tool Bar

<Click> on the New Assay icon to add a new assay. Enter new assay's name and click "ok". The user can add any number of sequences

After creating a sequence under any of the application tabs, click on the add Sequence icon

to add it as a new sequence. Sequences created can be saved to any existing assay by selecting/ highlighting the assay on the main interface screen.

User can also make changes to any existing sequence and save over it by clicking on the save

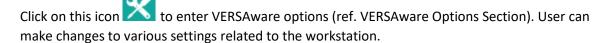
icon ICI. Click to open any sequence you want to change, make the changes and update the sequence using the save sequence icon. It is important to update the new changes by clicking on this icon, otherwise the changes will not take effect. This icon is also used to update or apply



new changes made to any sequence – be it a Z-offset setting change or any changes made in the options tab.



Click on this icon to delete a selected assay or sequence. Selected assay/ sequence is deleted by first highlighting it and then clicking on this icon.



Click on this icon



to start/ run any selected assay/ sequence.

Click on this icon to pause an assay/ sequence. User can pause at any stage of the sequence and unclick to continue the run. Sequence will continue from the where it left off/ paused on. Used when certain changes need to be made or to refill tip boxes.



to stop an assay/ sequence from running. Sequence will start again from Click on this icon the very beginning if user chooses to run this sequence again.



to run an assay/ sequence continuously. Assay/ sequence will run

continuously until the



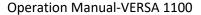
icon is "clicked".

Click on this icon



to send the robotic arm back to the home position

Click on this icon to reload tip boxes. Used to reload tips when prompted with an audible buzz after robotic arm has picked up its last tip from any box.





| | 15 000 µL | 200 µL P BOX (8) | ⁸ 50 µL ГІР ВО ((8) | 20 20 TIP B()X (| | 22 200 μL TIP BOX (1) |
|----------------------------|---------------------------|--|---------------------------------------|--|--|-----------------------------|
| 23 50 μL TIP BOX (1) | DUAL TIP BOX | | | | | |
| | ASPIRATOR 6 | 15 200 µl 11P 80X (8 85 96 PE R:2 | ¹⁸ 50 µL ПРВОХ(8) 1 | 20 20 119 BOX (4) RESERVO 1 | 8. IIP BOX (8) | |
| | 5 MAGNETIC 24 STAND | 45 96 PCR 2 | 113 | ter BLOC | 22 55 19 10 10 10 10 10 10 10 10 10 10 10 10 10 | 19 [|
| Start Row: 1 | Start Colu | umn: 1 | | | 🖌 ок | 🗙 Cancel |

Figure 10-9 VERSAware Reload Tip Boxes Icon Dialog Box

NOTE: Tip boxes have to be dragged and dropped from the library onto the deck to make them available for use.

Click on this icon ito transfer tips from an 8-channel tip box to a single channel tip box operation. The arm proceeds to transfer tips from the 8-channel tip box of specified position (# 2 in the figure below) to the targeted single-channel tip box position (Position 15 in the Figure below) for single channel use (source and target must be specified – 20, 50, 200, 1000 μ L Tip (1) and Tip (8). 1 for single channel and 8 for eight channel. Drag source tip box from position 2 to the "Source Tip Box" and Target single channel tip box to "Target Tip Box" as shown by the arrows in the figure below:



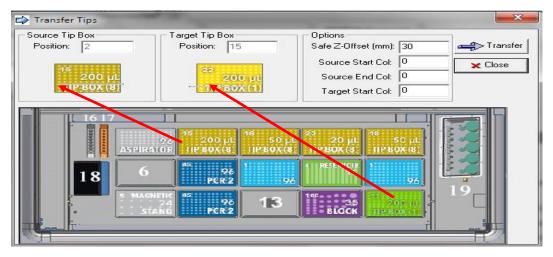
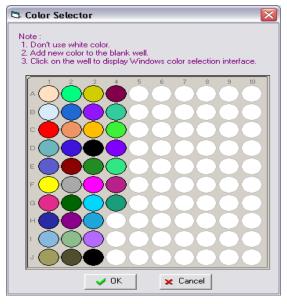


Figure 10-10 VERSAware Tip Transfer for single channel box Dialog Box

Click on this icon for the color selector for replicates and Ampligrid application, this icon allows the user to choose or custom choose more colors for use with each well of the slide. A dialog box will open which has several instructions and options for selection. This is to be used when additional colors are needed to code more wells. By default the color selector allows for 30+ colors to be used and displayed.

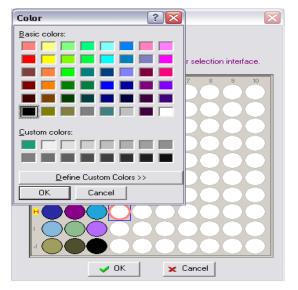
NOTE: User defined color selector only applies to the Ampligrid application tab. For replicates using PCR and Normalization tab, only 32 colors are allowed by default (color selector does not apply here).



A dialog box will appear that will prompt the user to first select an empty (white) well with the mouse. <Click> to use the palette (ref. below).

Figure 10-11 VERSAware Color Selector Dialog Box





Select from 48 basic colors or define your own by clicking onto the "define custom colors" tab. Create user defined color(s) by adjusting the color range and hue. Click on "add to custom colors" tab, and next click "ok" to insert a new colored well. This will be displayed on the color selector dialog box as shown above. To apply click ok.

Figure 10-12 VERSAware Color Selector Palette

Click on the single–channel icon to switch to the 8-channel or single channel mode of the robotic head

Click on the Licon to refresh the VERSAware main interface screen.

10.2. VERSAware 1100 Drop-down Menu

| | File | Run | Restore | Security | Tools |
|---|------|--------|------------|----------|-------|
| Г | | Add A | ssay | | |
| | | Add S | equence | | |
| | | Updat | e Sequenc | e | |
| | | Delete | Assay/Se | quence | |
| | | Refres | h | | |
| | | Export | | | + |
| | | Impor | t Assay/Se | quence | |
| | | Print | | | ×. |
| | | Exit | | | |

Figure 10-13 VERSAware File Drop-down Menu

File Drop-down Menu

Alternatively, the "file" drop down menu could be used to add an assay, a sequence, to update changes to a sequence or delete an assay or sequence. Users can also export or import assays and sequences to/ from different file formats. Click on export to save a file or picture (screen shot) to a text (.txt) or picture (.bmp) file respectively. Users can also choose to print the present screen



| 🕎 File | Run | Restore | Security | Tools | Help |
|----------------|-----|-------------|------------|-------|---------|
| | | Start Assay | //Sequence | e (| Ctrl+F5 |
| LÓ L | | Start Imm | ediately | | F5 |
| | | Pause | | | F9 |
| and the second | | Stop | | | F12 |

Figure 10-14 VERSAware Run Drop-down Menu

Run Drop-down Menu

Alternatively, the "run" drop down menu could be used to start an assay or sequence, to immediately start a newly created sequence on-screen, and pause or stop any assay/

| File Run | Restore Security Tools Help Le Co Co |
|--|---|
| Common Space Commo | Backup Management |
| | 🖓 Restore 🔀 Delete 🗙 Close |

Figure 10-15 VERSAware Restore Drop-down Menu

Restore Drop-down Menu

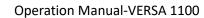
This icon can be used to restore the deleted sequences which

| | unty Tools Help |
|--------------------------------|--|
| Security | |
| G <u>e</u> neral User s | s |
| User Name Admin | User Admin |
| | Password |
| | Administrator General |
| | |
| | |
| | |
| | |
| | Save Add Close |

Figure 10-16 VERSAware Security Drop-down Menu

Security Drop-down Menu

Alternatively, the "Security" drop down menu could be used to set the user ID and password for security





| VERSAware 1100A v3.5.81 - [Con | trol Center] |
|---|-----------------------------|
| File Run Restore Security | Tools Help |
| <mark>]] </mark> | Options Configuration |
| [1617] | Barcode Configuration |
| ASPIRATOR II | Aurora Station PWM Pump |

Figure 10-17 VERSAware Tools Drop-down Menu

| Configuration | | | 23 |
|-------------------|-------------|----------------|-------|
| Instrument Type | | | |
| Instrument: | 3 VERSA 110 | 0 | - |
| Positions | | | |
| Reagent/Co | oler Block: | 8 Position 8 | - |
| | Shaker: | 12 Position 12 | - |
| Magne | tic Stand: | 11 Position 11 | - |
| Plate Mover | | | |
| Device: | 2 Gripper | | • |
| Reagent Drop Pins | | | |
| Pins: | 2 5 | | • |
| | ОК | Cancel | Apply |

Figure 10-18 VERSAware Tools Drop-down Menu-Configuration

| 🕎 File Run Restore Security Tools | Help | |
|-----------------------------------|-----------------------|------------------|
| | Contents > | Trouble shooting |
| | About VERSAware 1100A | |

Figure 10-19 VERSAware Help Drop-down Menu

Tools Drop-down Menu

This menu consists of various options that can be used to edit various system settings and open other submenu or interfaces like Device Manager AS, Clicking configuration will bring up another window.

Configuration Window

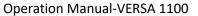
Instrument type: Set to VERSA1100 NAP by default.

Positions: Used to set or change the reagent block, shaker and magnetic stand position on the deck. At present the default is position 8, 12 and 11 respectively.

Other devices like the plate gripper has already been set and is the default position for that device.

Help Drop-down Menu

This menu provides VERSA1100 trouble shooting details and software version type for VERSA Appl.1100





10.3. VERSAware 1100 Options



The VERSAware options can be accessed by clicking on the ______ icon or by alternatively clicking on the drop down menu tools>options.

Here, users can edit or change various system/ instrument/ plate type settings according to their requirements. If clicking on the options for any sequence. The new changes will only apply for that sequence and not for the whole system or instrument throughout.

NOTE: Changes made here in the "options" apply only to individual sequences if a particular sequence is highlighted prior to "clicking" on the options icon. It is pertinent that you apply and update the changes by clicking on the "apply" button and then proceed to "click" on the "update" icon for changes to take effect.

Syringe Pump Settings

Depending upon the volume range of the user, some units are configured with 1000ul or 500ul 8 channel syringes. Users can also set air gap volumes, mixing air gap volumes, extra aspiration/dispensing volumes for all plate types for pumps (*Figure 10-20 VERSAware Syringe Pump Settings*). This extra aspiration/dispensing back volume settings help to cover the backlash of the pumps and make first and last well volumes correct. These should be set so that at the end there is little bit (1-3ul) volume left in the tip which can be dispensed at the source or at the waste position. Delays after aspiration/dispensing can also be added in the sequence. This is useful in case the solutions are viscous. Syringe aspiration/dispensing speeds for solutions and for an air gap can be set for all the syringe types depending upon the application.



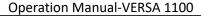
| | 250µL | 8×250μL | |
|---|-------|---------|--|
| Tip Volume | | | |
| Max. Volume (μL) | 300 | 300 | |
| Switch Volume (μL) | 300 | 300 | |
| Extra Volume | | | |
| Extra Aspiration Volume (µL) | 15 | 15 | |
| Extra Dispensing Volume (µL) | 10 | 10 | |
| Backlash Volume (μL) | 0 | 0 | |
| Delay | | | |
| Delay After Aspiration (s) | 0 | 0 | |
| Delay After Dispensing (s) | 0 | 0 | |
| Priming | 0 | | |
| Priming Cycles Back Aspiration Volume (µL) | 0 | 0 | |
| | | | |
| | | | |

Figure 10-20 VERSAware Syringe Pump Settings

NOTE: The values set here are by default and are specific for each user's application. No further changes are necessary unless specified by the manufacturer.

Tip Boxes Settings

The instrument comes pre-programmed with safe Z-setting Offsets for safe arm movement above the tip boxes to avoid hitting it. The values here are set as default data. No change is necessary. Maximum volume which can be aspirated/dispensed for each tip type can also be set here. There is provision to add different types of tips in single channel tip box as shown below. First six columns are loaded with 200ul tips and 7-12 columns are loaded with 50ul tips. Depending on the volume used in the sequence, tips will be taken from the single channel tip box (*Figure 10-21 Tip Boxes Settings*).





| Gap Sett ge Pump | ings Tip Boxes Plate Types Reagent Drop | o Other General Va | Ref Arm Movements Pump | Speeds Arm |
|----------------------------|--|--------------------|------------------------|------------|
| | Tip Box Type | Safe Z-Offset (mm) | Max. Volume (µL) | |
| | 25 μL Tip Box | 20 | 20 | |
| | 1,000 µL Tip Box | 20 | 900 | |
| | 8-Channel 200 µL Tip Box | 20 | 200 | |
| | 8-Channel 50 µL Tip Box | 20 | 50 | |
| | 8-Channel 25 µL Tip Box | 20 | 20 | |
| | 8-Channel 1,000 µL Tip Box | 20 | 900 | |
| | 200 µL Tip Box | 20 | 200 | |
| | 50 µL Tip Box | 20 | 45 | |
| | Dual Tip Box | 20 | 930 | |
| ual Tip | Box Settings | | | |
| Ī | Tip Box Type | Start Column | End Column | |
| 1 | 22 - 200 µl Tip Box | | 1 6 | 5 |
| 2 | 23 - 50 µl Tip Box | | 7 12 | 2 |
| | | | | |
| 3 | | | | |
| 3 4 | | | | |
| | | | | - |
| 4 | | | | |
| 4 5 6 7 | | | | |
| 4 5 6 7 8 | | | | |
| 4 5 6 7 8 9 | | | | |
| 4 5 6 7 8 | | | | |

Figure 10-21 Tip Boxes Settings

Note: If using filter tips—set the Maximum volume in OPTIONS—Tip Box as—20µL-10µL, 50µL — 45µL, 200µL -180µL and 1000µL--900µL

Plate Types Settings

The plate type options allow users to change Z-Offsets for any particular plate type. This screen also displays the plate types available for this system that have been pre-specified by the user. Any changes made here would affect the related sequence and not the system as a whole.

All positions are taught on the surface of a 96 well plate. If the aspiration/dispensing off set is set as ZERO then the reagent will be dispensed on the surface of any plate type used. To dispense and aspirate from the bottom of the plate increase this aspiration/dispensing off sets. These are set in mm. All plate types are set by default to the bottom of the plate (click Max Depth icon). However the user can change it according to the reagent level in the wells.



As an example, if a tip dispenses liquid too far from the bottom of the well of a 96-well plate, increase the dispensing Z-Offset by increments of 1 or 2 mm first, apply and then update the sequence; and run again to see if tip goes further into the well to dispense.

The same applies for aspiration. For increased accuracy, measure the height from the tip's end to the bottom of the well measured in mm. Make provisions for the required Z-Offset increase in mm.

Likewise, Reagent Cooler Block (columns 1-7) Z-off settings are also found here. These can be changed for each sequence depending upon the volumes in these tubes. The Arm movement Z-offset (mm) helps to move the arm at a specified Z movement within that plate type.

For example, if movement Z-offset is set at 5mm instead of normal setting of 15mm, then arm will move at lower position with respect to the plate. It will save some time during multiple dispensing.

| Plate Type | Aspiration Z-Offset (mm) | Dispensing Z-Offset (mm) | Mo∨ement Z-Offset (mm) | √olume (μL) | Gripper Safe Z-Offset (mm) | |
|--|----------------------------------|--|--------------------------------------|----------------------------------|--|---|
| 96-Well Plate | 10.85 | 10.85 | 15 | 350 | 60 | |
| 96-Deep Round Well Plate 1 | 39.11 | 39.11 | 15 | 100 | 60 | |
| 96-Deep Square Well Plate 2 | 42.24 | 42.24 | 15 | 100 | 60 | |
| 96-Deep Round Well Plate 3 | 29.35 | 29.35 | 15 | 100 | 60 | |
| 96-Deep V-bottom Round Well Plate 4 | 32.06 | 32.06 | 15 | 100 | 60 | |
| 96-Deep Round Well Eppendorf Plate 5 | 40.49 | 40.49 | 15 | 100 | 60 | - |
| Reagent/Cooler Block [Depth] | | | | | Max. Depth | |
| For 3 Tube/Vial Aspiration Disper T1 - T16 (mm) 21.62 2 S1 - S8 (mm) 29.59 2 R1 - R8 (mm) 37.73 2 M1 - M3 (mm) 51.49 5 Safe Z-Offset for Movement (mm) 30 J Max. E | 21.62 29.59 37.73 51.49 | For 6 TubeA T1 - T16 S1 - S12 R1 - R5 M1 - R6 Safe Z-Offset Movement (| (mm) 2 (mm) 2 (mm) 3 (mm) 5 | 21.62 29.59 87.73 51.49 | Dispensing 21.62 29.59 37.73 51.49 Max. Depth | |
| For 6-column Reservoir (mm) Column 1 6.02 Column 2 Column 4 23.56 Column 5 | 11.26 37.41 | Column 3 | 16.23 | | Max. Depth | |
| For 8-column Reservoir (mm) Column 1 9.75 Column 5 33.03 Column 6 39 | Co | olumn 3 31.71 | Co | ilumn 4 📑 | 33.03 39 Max. Depth | |

Figure 10-22 VERSAWare Plate Types Settings

NOTE: The values set here are by default and are specific for each user's application. No further changes are necessary unless specified by the manufacturer or if you experience an insufficient dispense or aspiration height Z-Offset.



Reagent Drop Settings

Priming volume for the 5 channel reagent drop module can be changed along with its dispensing Z-offset. Increase or decrease if the dispensing height is too low or too high from the surface of the well. Also, add delay time between wells if required for large volumes (*Figure 10-23 VERSAware Reagent Drop Z-offset settings*).

| Options | - | | | The second | 1000 | - | | | |
|-------------|-----------------|-------------|--------------|------------|---------|----------|---------------------|-------------|----------|
| Air Gap Set | tings | | | | | | | | |
| | | Plate Types | Reagent Drop | 0 Other 0 | General | VarRef | Arm Movements | Pump Speeds | Arm Spe |
| Reage | nt Drop Priming | J | | | | | | | |
| | | | | | | | Volume (μL) | 1 | ō |
| | | | | | | | | | |
| Reage | nt Drop Z-Offse | et | | | | | | | |
| | | | | | | Disper | nsing Z-Offset (mm) | | 3 |
| | | | | | | | | | |
| Reage | entDrop Time De | elay | | | | | | | _ |
| | | | | | B | eagentDr | rop Time Delay (ms | | 0 |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| Restore | 🃸 Default | 1 | 📸 Export | 📕 💼 Imp | port | | 🖹 Apply 📘 | сок 📋 | 🗙 Cancel |

Figure 10-23 VERSAware Reagent Drop Z-offset settings

Other Settings

In other, these options allow the user to set different Z-offsets for mixing, air gap, arm movement from one position to another (*Figure 10-24 VERSAware Other Settings*). These settings if used properly reduce the total timing of an assay.

Also arm speed for dispensing and speeds for handling waste can be set here. In case, the instrument is equipped with Liquid Level Sensing (LLS), it can be activated from here for each sequence. After and before any sequence, arm initializing options are also here. The user can add message after any sequence



| equence] NAP/Advanced Reagent Addition created on 2015 | 5-11-30 12:20:24 |
|---|--|
| Air Gap Settings yringe Pump Tip Boxes Plate Types Reagent Drop Other | Consult VerBell Am Management Down Consult Am Con- |
| - Back Aspiration Volume | General Varker Arm Movements Pump Speeds Arm Spe |
| Back Aspiration Volume | Back Aspiration Volume (μL) 0 |
| | |
| - Plate Mover | -Offset for Movement: Source> Target (mm) 100 |
| - Air Gap Aspiration | |
| | Safe Z-Offset for Air Gap Aspiration (mm) 15 |
| Mixing | |
| 🔲 Using New Mixing | Mixing Safe Z-Offset (mm) 10 |
| 96-channel Aspirator Deck Position Start Speed (step/s) 50 End Speed (step/s) | Select Method 1 Dispensing At Source 1 Safe Z-Offset (mm) 120 500 Acceleration (step/s²) 10 |
| | |
| Liquid Level Sensing 👘 Mathematical Remain | ining Volume Tracking Z-Offset (mm) 3 |
| EMail Adress Setting | _ Syringe Pump |
| EMail: versa1@aurorabiomed.com | Syringe Pump Scale 3-Scale1 |
| Others | ✓ Initialize After Sequence |
| Initialize Z-axis After Tip Engagement | Safe Arm Movement |
| | |

Figure 10-24 VERSAware Other Settings

General Settings

The general settings tab (*Figure 10-25 General Settings*) allows user to hide or to show the application tabs so as not to clutter the VERSAware main interface screen. After the activation of any tab, it will appear on the main interface of the software and after deactivation, it will disappear from the interface. Depending upon the applications, the user can choose show those tabs on the interface.

| [Sequence] Air Gap Sel | | ed Reagent A | ddition created | l on 2015-11-30 | 12:20:24 | - | - | |
|---------------------------|---------------|--------------|-----------------|-----------------|----------|---------------|-------------|-----------|
| | | Plate Types | Reagent Drop | Other General | VarRef | Arm Movements | Pump Speeds | Arm Speed |
| 🗖 Add Sar | nple | | | | | | | |
| 🔽 Serial D | ilutions | | | | | | | |
| 🔲 Reagen | t Addition | | | | | | | |
| ☑ Dilution | | | | | | | | |
| 🔽 Plate Re | eformatting | | | | | | | |
| 🔲 AmpliSli | de | | | | | | | |
| 🔲 Pooling | Application | | | | | | | |
| Cherry F | Picking | | | | | | | |
| PCR | | | | | | | | |
| 💌 NAP/Ad | Ivanced Reage | nt Addition | | | | | | |
| 🔲 Normalia | zation | | | | | | | |
| 🗌 Advanc | ed NAP | | | | | | | |
| 🔲 Vacuum | Manifold | | | | | | | |
| 🔲 VarRef I | NAP | | | | | | | |
| 🔲 Plate Tr | ansport | | | | | | | |
| 🔲 Matrix N | ormalization | | | | | | | |
| 🔲 Liquid T | ransfer | | | | | | | |
| 🔲 HLA Tyj | ping | | | | | | | |
| | | | | | | | | |
| | | | | | | | | |
| | | | | | | | | |
| | | | | | | | | |
| | | | | | | | | |
| | | | | | | | | |
| | | | | | | | | |
| | | | | | | | | |

Figure 10-25 General Settings

Arm Movements

rora

Arm movements setting tab allows user to set X/Z way movement after aspiration and after dispensing. These can be set for all the tube types of the reagent cooler block as shown below (*Figure 10-25 General Settings*). These settings help to remove any liquid outside of the tip after aspiration. The arm will move up after aspiration to the specified Z distance like 24mm as shown below in the figure (*Figure 10-26 Arm Movements*) and then move 2mm to right side to touch the side of the well and again move 4mm to left side to touch the left side of the well, move 2mm to the center and move out to dispense the reagent in the target plate.

Likewise X/Y offsets can also be set before aspiration, after aspiration and before dispensing and after dispensing reagent in the wells. These X/Y off sets help to aspirate/dispense reagents at different X/Y positions in a well.



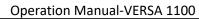


| r Gap Settin | ; Tip Boxes Plate Types Reagent Drop Other General VarRef Arm Movements Pump Speeds Arm | s Speed l |
|--------------|---|-----------|
| | in boxes nate types neagent brop other deneral vanier annotements rump speeds Ann ent from One Position to Another | - Deed |
| | Safe Z-Offset (mm) 120 | |
| Delay | | 5 |
| | Delay Time After Arm Movement (second) | |
| Arm Move | nts For Vial/Tube By X/Z Way | - |
| E X- | sets And Z-Offsets(AfterAspiration) | |
| | Regular Plate Reagent/Cooler Block | |
| | After Source Aspiration X-Offset (mm) 2 Edit / View The Settings | |
| | After Aspiration Z-Offset (mm) 24 | |
| -E× | fsets And Z-Offsets(After Dispensing) | |
| | Regular Plate Reagent/Cooler Block | |
| | After Target Dispensing X-Offset (mm) 2 Edit / View The Settings | |
| | After Dispensing Z-Offset (mm) 12 | |
| L | | |
| | nts For Vial/Tube By X/Y Way | |
| | t And Y-Offset (Before Aspiration) re Source Aspiration X-Offset (mm)2 Before Aspiration Y-Offset (mm)5 | |
| P P | re Source Aspiration X-Offset (mm) 2 Before Aspiration Y-Offset (mm) 5 | |
| - X-Of | t And Y-Offset (After Aspiration) | - I I |
| | er Source Aspiration X-Offset (mm) 13 After Aspiration Y-Offset (mm) 14 | |
| X-Of | t And Y-Offset (Before Dispensing) | |
| Be | e Target Dispensing X-Offset (mm) 1 Before Dispensing Y-Offset (mm) 3 | |
| | t And Y-Offset (After Dispensing) | |
| 1 | er Target Dispensing X-Offset (mm) 11 After Dispensing Y-Offset (mm) 12 | |
| Arm Move | Ints For Mixing By X/Z Way | |
| | ets And Z-Offsets(Mixing) | - |
| | Mixing Dispensing X-Offset (mm) 3 After Mixing Dispensing Z-Offset (mm) 4 | |
| | | - |

Figure 10-26 Arm Movements

| Arm Movements For Vial/Tube By X/Z Way X-m Movements For Vial/Tube By X/Z Way X-Diffsets And Z-Offsets(After Aspiration) Regular Plate After Source Aspiration X-Offset (mm) 6 After Aspiration Z-Offset (mm) 42 Edit / View The Settings Chart Aspiration Z-Offset (mm) 42 Reagent/Cooler Block Edit / View The Settings Arm Movement Offset Options After Aspiration For 3 Tube/Vial | *-Offsets And Z-Offsets(After Aspiration) Regular Plate After Source Aspiration X-Offset (mm) 6 After Aspiration Z-Offset (mm) 42 Edit / View The Settings m Movement Offset Options After Aspiration agent/Cooler Block | Movements For Vial/Tube By X/Z Way X-Olfsets And Z-Olfsets (After Aspiration) Regular Plate After Source Aspiration X-Offset (mm) 6 After Aspiration Z-Offset (mm) 42 Arm Movement Offset Options After Aspiration For 3 Tube/Vial For 3 Tube/Vial X-Offset T1 · T16 (mm) 1 S1 · S8 (mm) 2 R1 · R8 (mm) 3 24 |
|--|--|---|
| Regular Plate Reagent/Cooler Block After Source Aspiration X-Offset (mm) 6 After Aspiration Z-Offset (mm) 42 C Arm Movement Offset Options After Aspiration Reagent/Cooler Block Reagent/Cooler Block For 3 Tube/Vial T1 · T16 (mm) 1 | Regular Plate Reagent/Cooler Block After Source Aspiration X-Offset (mm) 6 After Aspiration Z-Offset (mm) 42 Im Movement Offset Options After Aspiration Imagent/Cooler Block agent/Cooler Block Arm Movements After Aspiration For 3 Tube/Vial Imagent/Cooler Block T1 · T16 (mm) 1 S1 · S8 (mm) 2 R1 · R8 (mm) 3 24 R1 · R5 (mm) | Regular Plate Reagent/Cooler Block After Source Aspiration X-Offset (mm) 6 After Aspiration Z-Offset (mm) 42 Arm Movement Offset Options After Aspiration Image: Cooler Block Reagent/Cooler Block Image: Cooler Block For 3 Tube/Vial X-Offset T1 · T16 (mm) 1 S1 · S8 (mm) 2 R1 · R8 (mm) 3 X1 · M3 (mm) 5 X1 · M3 (mm) 45 |
| After Source Aspiration X-Offset (mm) 6 After Aspiration Z-Offset (mm) 42 Edit / View The Settings Arm Movement Offset Options After Aspiration Reagent/Cooler Block For 3 Tube/Vial T1 · T16 (mm) 12 | After Source Aspiration X-Offset (mm) 6 After Aspiration Z-Offset (mm) 42 Im Movement Offset Options After Aspiration Imagent/Cooler Block Arm Movements After Aspiration -For 3 Tube/Vial | After Source Aspiration X-Offset (mm) 6 After Aspiration Z-Offset (mm) 42 Arm Movement Offset Options After Aspiration Reagent/Cooler Block Arm Movements After Aspiration For 3 Tube/Vial X-Offset T1 · T16 (mm) 1 S1 · S8 (mm) 2 R1 · R8 (mm) 3 After Rs (mm) 5 After Aspiration 0 M1 · M3 (mm) 5 After Aspiration 0 M1 · M6 (mm) 0 |
| After Aspiration Z-Offset (mm) 42 Edit / View The Settings 3. Arm Movement Offset Options After Aspiration Image: Content of the setting set of the setting set of the set of th | After Aspiration Z-Offset (mm) 42 Im Movement Offset Options After Aspiration agent/Cooler Block Arm Movements After Aspiration -For 3 Tube/Vial X-Offset Z-Offset T1 - T16 (mm) 1 12 S1 - S8 (mm) 2 16 R1 - R8 (mm) 3 24 | After Aspiration Z-Offset (mm) 42 Arm Movement Offset Options After Aspiration Reagent/Cooler Block Arm Movements After Aspiration For 3 Tube/Vial X-Offset T1 · T16 (mm) 1 S1 · S8 (mm) 2 R1 · R8 (mm) 3 After Aspiration S1 · S12 (mm) M1 · M3 (mm) 5 |
| Arm Movement Offset Options After Aspiration Reagent/Cooler Block Arm Movements After Aspiration For 3 Tube/Vial X-Offset | m Movement Offset Options After Aspiration agent/Cooler Block Arm Movements After Aspiration For 3 Tube/Vial Z-Offset T1 · T16 (mm) 1 S1 · S8 (mm) 2 R1 · R8 (mm) 3 24 | Arm Movement Offset Options After Aspiration Reagent/Cooler Block Arm Movements After Aspiration For 3 Tube/Vial |
| Reagent/Cooler Block Arm Movements After Aspiration For 3 Tube/Vial X-Offset Z-Offset T1 - T16 (mm) | For 3 Tube/Vial X-Offset Z-Offset T1 · T16 (mm) 1 12 S1 · S8 (mm) 2 16 R1 · R8 (mm) 3 24 | For 3 Tube/Vial X-Offset Z-Offset T1 · T16 (mm) 1 12 S1 · S8 (mm) 2 16 R1 · R8 (mm) 3 24 M1 · M3 (mm) 5 45 |
| Arm Novement Onset Options Arter Aspiration Reagent/Cooler Block Arm Movements After Aspiration For 3 Tube/Vial X-Offset | For 3 Tube/Vial X-Offset Z-Offset T1 · T16 (mm) 1 12 S1 · S8 (mm) 2 16 R1 · R8 (mm) 3 24 | For 3 Tube/Vial X:Offset Z:Offset For 3 Tube/Vial X:Offset For 6 Tube/Vial Z:Offset T1 · T16 (mm) 1 12 Si · S8 (mm) C C S1 · S8 (mm) 2 16 Si · S12 (mm) C C R1 · R8 (mm) 3 24 M1 · M3 (mm) C C |
| For 3 Tube/Vial X-Offset For 6 Tube/Vial X-Offset T1 · T16 (mm) 1 12 T1 · T16 (mm) 0 | For 3 Tube/Vial X-Offset To 6 Tube/Vial X-Offset T1 - T16 (mm) 1 12 T1 - T16 (mm) 0 0 S1 - S8 (mm) 2 16 S1 - S12 (mm) 0 0 R1 - R8 (mm) 3 24 R1 - R5 (mm) 0 0 | For 3 Tube/Vial X-Offset For 6 Tube/Vial X-Offset T1 · T16 (mm) 1 12 T1 · T16 (mm) 0 0 S1 · S8 (mm) 2 16 S1 · S12 (mm) 0 0 R1 · R8 (mm) 3 24 R1 · R5 (mm) 0 0 M1 · M3 (mm) 5 45 M1 · M6 (mm) 0 0 |
| T1 · T16 (mm) 1 12 T1 · T16 (mm) 0 0 | T1 - T16 (mm) 1 12 T1 - T16 (mm) 0 S1 - S8 (mm) 2 16 S1 - S12 (mm) 0 0 R1 - R8 (mm) 3 24 R1 - R5 (mm) 0 0 | T1 · T16 (mm) 1 12 T1 · T16 (mm) 0 0 S1 · S8 (mm) 2 16 S1 · S12 (mm) 0 0 R1 · R8 (mm) 3 24 R1 · R5 (mm) 0 0 M1 · M3 (mm) 5 45 M1 · M6 (mm) 0 0 |
| | S1 - S8 (mm) 2 16 S1 - S12 (mm) 0 0 R1 - R8 (mm) 3 24 R1 - R5 (mm) 0 0 | S1 - S8 (mm) 2 16 S1 - S12 (mm) 0 0 R1 - R8 (mm) 3 24 R1 - R5 (mm) 0 0 M1 - M3 (mm) 5 45 M1 - M6 (mm) 0 0 |
| S1 - S8 (mm) 2 16 S1 - S12 (mm) 0 0 | R1 - R5 (mm) 3 24 R1 - R5 (mm) 0 0 | R1 · R8 (mm) 3 24 R1 · R5 (mm) 0 0 M1 · M3 (mm) 5 45 M1 · M6 (mm) 0 0 |
| | | M1 · M3 (mm) 5 45 M1 · M6 (mm) 0 0 |
| B1 · B8 (mm) 3 24 B1 · B5 (mm) 0 0 | M1 - M3 (mm) 5 45 M1 - M6 (mm) 0 0 | |
| M1 · M3 (mm) 5 45 M1 · M6 (mm) 0 0 | | Operation |
| Operation | - Operation | |
| | | OK Clear Cancel |
| OK Clear Cancel | OK Clear Cancel | |

Figure 10-27 Arm Movements-Reagent cooler Block





Pump Speeds

Pump Speed settings tab allows the user to control pump speeds for aspiration and dispensing

(*Figure 10-28 Pump Speeds*). Even the pump speed to take in the air gap can be controlled by the user. Higher/lower speeds can be set to dispense waste at the waste position.

| [Sequence] NAP/Advanced Reagent Addition created on 2 | 015-11-30 12:20:24 | |
|--|-------------------------------|-------------------------------------|
| Air Gap Settings | | |
| Syringe Pump Tip Boxes Plate Types Reagent Drop Othe | r General VarRef Arm Mo | vements Pump Speeds Arm Speed |
| Pump Aspirate Speed | | |
| Start Speed (step/s) | End Speed (step/s) | Acceleration (step/s ²) |
| 250 μL 10 | 600 | 5 |
| 8×250 μL 10 | 600 | 5 |
| Pump Dispense Speed | | |
| Start Speed (step/s) | End Speed (step/s) | Acceleration (step/s ²) |
| 250 μL30 | 800 | 10 |
| 8×250 μL 20 | 1000 | 10 |
| Pump Air Gap Speed | | |
| Start Speed (step/s) | End Speed (step/s) | Acceleration (step/s ²) |
| 250 µL 10 | 600 | 5 |
| 8×250 μL 10 | 600 | 5 |
| | , | |
| Pump Speed for Waste Liquid Handling Method | | |
| Start Speed (step/s) | End Speed (step/s) | Acceleration (step/s ²) |
| Dispensing At Waste 10 | 800 | 10 |
| Dispensing At Source 50 | 300 | 5 |
| | | |
| | | |
| | | |
| | | |
| | | |
| | | |
| | | |
| | | |
| | | Ē |
| 👪 Restore 🏾 🏠 Default 🛛 💼 Export | Import 🛃 Apply | 🗸 OK 🛛 🗙 Cancel |

Figure 10-28 Pump Speeds

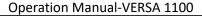


Arm Speeds

Arm Speed setting tab allows user to control arm speeds after aspiration and dispensing in Z way (*Figure 10-29 Arm Speeds*).

| 🔄 [Sequence] NAP/Advanced Re | eagent Addition c | reated on 2015-11 | -30 12:20:24 | | × |
|------------------------------|-------------------|--------------------|--------------|-------------------------------------|--------------------|
| Air Gap Settings | ĩ | x x | | 1 | |
| Syringe Pump Tip Boxes Plate | | Drop Other Gen | eral VarRef | Arm Movements Pump | Speeds Arm Speed |
| Start Speed (step/s) | | Speed (step/s) | 300 | Acceleration (step/s²) | 10 |
| Arm Speed after Dispensi | na 17-Avis) | | | | |
| Start Speed (step/s) | | Speed (step/s) | 300 | Acceleration (step/s ²) | 10 |
| | | | | | |
| | | | | | |
| | | | | | |
| | | | | | |
| | | | | | |
| | | | | | |
| | | | | | |
| | | | | | |
| | | | | | |
| | | | | | |
| | | | | | |
| | | | | | |
| | | | | | |
| | | | | | P |
| 🛃 Restore 🏾 🏠 Default | 💼 Exp | oort 🛛 🌆 Import | | 🖹 Apply 🔰 🧹 OK | X Cancel |

Figure 10-29 Arm Speeds





Air Gap Settings

Air Gap setting tab allows user to set different air gap settings for all the four types of tips available in lab-ware (*Figure 10-30 Air Gap Settings*). There are before aspiration and after dispensing too. Separate air gap settings are there for mixing options too so that user can avoid any bubble formation during mixing—air gap can be reduced for each tip type.

| [Sequen | cej NAP/Advanced | Reagent Addition | created o | on 20 | 12-11 | 30 12:20:24 | | | <u> </u> |
|------------|------------------|-------------------|-----------|-------|-------|---------------------------------------|------------------|-----------|----------|
| | | Plate Types Reage | ent Drop | Othe | er G | eneral VarRef Arr | m Movements Pump | Speeds Ar | m Spe |
| vir Gap Se | ettings | | | | | | | | |
| -Tip Air | Gap | | | | | | | | |
| ⊢Air | Gap Before Asp | oriation | | | – Air | Gap After Aspri | ation | | |
| | Tip Box Name | Air Gap Volume | Unit | тĿ | | Tip Box Name | Air Gap Volume | Unit | |
| | 20 µL Tip | 5 | μL | 11 | | 20 µL Tip | Air Gap volume | μL | |
| | 50 µL Tip | 10 | μL | | | 50 µL Tip | 0 | μL | |
| | 200 µL Tip | 20 | μL | | | 200 µL Tip | 0 | μL | |
| | 1000 µL Tip | 30 | μL | | | 1000 µL Tip | 0 | μL | |
| | | | | | | 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 | - | | |
| Mixing | g Air Gap | | | | | | | | |
| Mix | ting Air Gap Bef | ore Aspriation — | | | Mix | ting Air Gap Afte | er Aspriation — | | |
| | Tip Box Name | Air Gap Volume | Unit | 1 | | Tip Box Name | Air Gap Volume | Unit | |
| | 20 µL Tip | 5 | μL | | | 20 µL Tip | 0 | μL | |
| | 50 µL Tip | 10 | μL | | | 50 µL Tip | 0 | μL | |
| | 200 µL Tip | 20 | μL | | | 200 µL Tip | 0 | μL | |
| | 1000 µL Tip | 30 | μL | | | 1000 µL Tip | 0 | μL | |
| | | | | - | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |

Figure 10-30 Air Gap Settings



11.VERSA Application Tabs

This section will provide information on how to configure and operate VERSAware NAP/PCR, how to design, validate, store and run Serial Dilution, NAP/Reagent Addition, Dilution, Plate Reformatting, Cherry Picking, PCR application and Normalization sequence(s).

11.1. Startup

The VERSAware software provides a user-friendly graphic interface with an easy drag-and-drop technique to create, validate, save, combine and run application sequences defined by parameters such as Serial Dilution, Dilution, Plate Reformatting, Pooling Amplislide, Cherry Picking, PCR [Polymerase Chain Reaction] and Normalization application sequences.

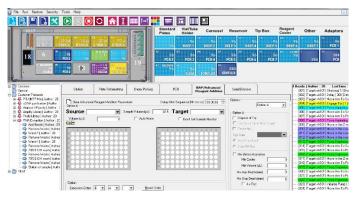


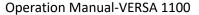
Figure 11-1 VERSAware Workspace Main Interface

VERSAware1100 allow users to configure the deck using different labware types, define, store, combine and run assays or sequences for various applications. Device Manager AS provides robotic arm control, teaching positions, syringe pump control and calibration; and temperature control. Aurora Station on the other hand stores all communication parameters, robotic arm and syringe pump speed, acceleration and travel limit settings along with tip engagement speed and acceleration and tip disengagement offset.

11.2. Basics

The 10 μ L or 20 μ L pipette tips are generally used with the small 25 μ L syringe pump, and 50, 200, 1,000 μ L pipette tips are typically used with the large 1,000 μ L syringe pump and 200 μ L tip for 8-channel x 250 μ L pump.

Please contact your Aurora sales representative for pricing and catalogues on consumables. Refer to the Teaching Positions or the VERSAware1100 Main Interface section of this manual for more information on tip box location(s).







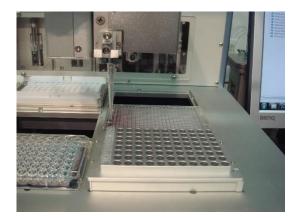


Figure 11-2 8-Channel - 200 µL Pipette Tip Box Figure 11-3 Single Channel - 200 µL Pipette Tip Box

The drag-and-drop technique is used to configure the deck with necessary vessels for any particular assay or sequence. All 15 positions can be used for deck configuration. Depending on the configuration of the deck and customer's requirements, the below mentioned guidelines are recommended deck layout configuration for VERSA1100.

Position 1 – 4X8 Tube Adaptor
Positions 2 to 3 – 8 channel -20/50/200µL tip boxes
Positions 4 to 5 – 8 channel -1000µL Conductive tip boxes
Positions 6 & 7 & 13 – Empty
Positions 8 to 10 - AmpliSlide
Position 11 – Deep well plate
Position 12 – Heater/Shaker
Position 14 & 15 – 4X8 Tube Adaptor
NOTE: Drag and drop the required plate or tip type from the library onto the deck interface for

use

11.3. Folder Assays and Sequences

Assays and sequences are stored in the database of VERSAware1100 software. Multiple sequences can be stored under each created assay and the storage capacity is unlimited. Any stored assay or a sequence can be selected to run at any time by clicking on it. To rename as assay or sequence, click on any assay or sequence title.



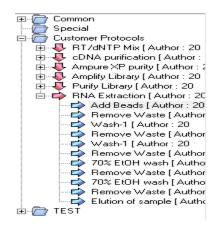


Figure 11-4 Example: Assay and Sequences

An option to cut/copy and paste sequences is also available (*Figure 11-5 VERSAWare- Cut, Copy and Paste Sequence*). Select the sequence you want to cut/copy and paste and right click to choose the option. The original sequence will be pasted after the selected sequence. There is also an export (to file) and import (from file) function for sequences; along with a print function for individual sequences or steps.

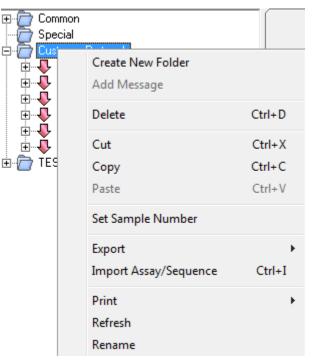
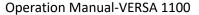


Figure 11-5 VERSAWare- Cut, Copy and Paste Sequence

Follow the steps below for creating and running sequences or assays:

First click on the appropriate application tab.

Then drag and drop required lab-ware or plate types on the main deck interface.





Ensure the actual plates and tips are in place on the physical deck for use.

Design your protocol – highlight wells and input options.

If mistakes are made, erase all parameters by clicking the clear sequence

setting icon.

Recreate and click the Add New Assay icon to create a new blank assay and change the assay name if required.

11.4. Add New Assay Icon

Add a sequence to this new assay by pressing the Add New Sequence button and change the sequence name if needed.

The sequence will be saved in the database if there are no errors.

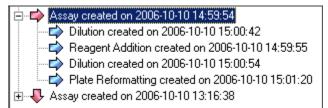
Add New Sequence Icon

Press the Start Assay/Sequence button to run this sequence.



Start Assay/Sequence Icon

If you want to run the entire assay that consists of multiple sequences, select the assay and all attached sequences will run one after another.



There is another option available to run an application without saving the sequence. To do this, click on the Reagent Addition tab and press the Start Assay/Sequence button on the VERSAware V1100 toolbar.

While running an assay, before each sequence, teach and initialize the robotic arm and prime both syringe pumps to prevent possible robotic arm step loss error (ref. Aurora Station section of the manual).

Click the Stop button to terminate the sequence. However, a single command being performed at that moment, whether it is a robotic arm movement or liquid handling operation, will continue running until it is finished.

Click the Pause button to pause or resume the sequence run.



Click the Stop button to stop the sequence run. You have the option of resuming from a particular step of a stopped sequence by left clicking on that step.

Click the Run Continuously button to loop the entire assay if an assay is running or the sequence if only a sequence was started.

🔁 🖻 🗅 🗙 🕑 🛈 🧿 🚱 🚹 🖬 📼 🖬 📰 🔲 💷

Continuous Sequence Run

11.5. Serial Dilution Application Tab

This tab allows the user to perform serial dilutions (log10 & log2 fold). User can do a 1/10 or 1/2 dilution of the samples can be done with single-channel and 8-channel application.

The first dilution can be any fold. For example, if the original concentration of the compound is 1mM, the starting or first well can be any concentration either less than 1mM or the same. The user must select the first well from where the serial dilution starts and specify the concentration in that first well.

After which, the user can choose the type of dilution required (log10, log2, Log5) and specify the source position of the diluent which can be from a reservoir or reagent cooling block as shown in *Figure 11-6 VERSAware Serial Dilution Tab*.

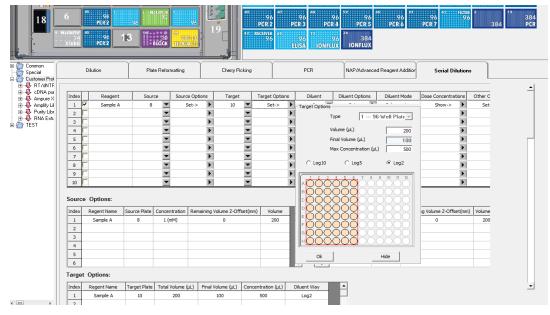


Figure 11-6 VERSAware Serial Dilution Tab

To perform a serial dilution user are to follow the steps below:

Step 1 – Drag and drop the plate or tube types to the correct positions on the deck layout interface segment (as shown in screen shot above).



If utilizing diluent from a source (reservoir or cooling block), drag and drop the diluent type onto the deck. With single channel mode the user can use the reagent cooler block for diluents; and the reservoir can be used for 8-channel mode.

Step 2 – Choose the selection mode for dilution – by row or by column only in single-channel mode.

Step 3 – Next proceed to select the position of the source. In this case, the 96-well plate is the source (as shown in screen shot above) located at position "2" on the deck. Highlight source wells.

Step 4 – Select the target position. This is the position where you would want the source to go. In this case, the 96-well plate is the source (as shown in screen shot above) located at position "3" on the deck. Highlight target wells

NOTE: Targets and sources need not be of the same type. Serial dilution can be performed from tubes to plate, plate to plate etc.

Step 5 – If using diluent from a source for e.g. reservoir or reagent cooling block, under diluent source (as in screen shot above), click onto the "reservoir position" field and select the position of the diluent source.

Step 6 – Proceed then to input a value for the concentration of the source sample. Here we have used 1uM as the sample concentration (as shown in the screen shot above).

Step 7 – Proceed to do the same input values for the original volume and final volume (μ L) for the target, along with the maximum concentration allowed. The software automatically calculates for the dilution volume needed.

Step 8 – Other options are also available which can be included in the sequence, for e.g. – Operators can choose to check off "mixing" and "delays" or even "tip disposal after ever

dispense". To erase all parameters, click the clear sequence setting \square icon.

Step 9 – Lastly, remember to save your created sequence by clicking on the LO icon. If this is an addition to an existing assay, highlight the assay name on the left of the screen and then proceed to click on the "add new sequence" icon. You would be given the option to enter the new sequence name. You can also rename after. If a new assay has not yet been created, then

proceed to first click on the icon, rename the assay, click "OK". After which, click on the "add new sequence" icon, rename the sequence and click "OK".

Step 10 – If making changes to an already loaded or existing sequence – load by highlighting and

<click> on the sequence you want to edit or change, make the changes, and the <click> the icon to save or update the new changes. New changes will then be applied to the sequence and system.



Step 11 - To run this sequence, <click> on the icon

11.6. Plate Reformatting Application Tab

This application allows users to format from e.g. a 96-well plate into a 384-well plate or one 96well plate to another type.

The ability to reformat from e.g. 6x8 tubes to a 96-well plate also exists but in single-channel mode only. Other options include dilution with buffer from the reservoir/ reagent cooling block, mixing of the diluted target sample, and delays before and after the application run. Advanced options include plate replication and reformatting from two source positions. Please follow the steps as shown below to reformat from 96 well plate to 384 well plate:

Step 1 - Configure your deck

Step 2 - Select your Source Plates from where you will aspirate liquid and assign the volume

Step 3 - Select the column on source plate (each source plate column will be the same)

Step 4 - Select your Target 384 well Plate (column will be alternate in 384 well plate)

Step 5- Add volume to be transferred to 394 well plate, select options to change tip or not to change tip

Step 6 - Assign an air gap volume (choose a higher volume for higher source volumes)

Step 7- Save the sequence under an assay

Step 6 - Click the Start Button

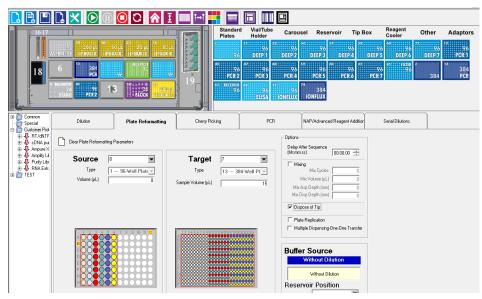


Figure 11-7 VERSAware Plate Reformatting Tab



If dilution is needed after reformatting is performed, drag and drop a diluent source (reservoir or cooling block) onto the deck interface, and select under "reservoir position" field, the position of the diluent source. A "final volume" field will appear under the target section which you will then input the final amount for each well.

| Source & Target Micro-plates | | | | | |
|------------------------------|-----------|--|--|--|--|
| 96-well | 384-well | | | | |
| 2 Columns | 1 Column | | | | |
| 4 Columns | 2 Columns | | | | |
| 6 Columns | 3 Columns | | | | |
| 8 Columns | 4 Columns | | | | |
| 10 Columns | 5 Columns | | | | |
| 12 Columns | 6 Columns | | | | |

Columns for 96 and 384 Source and Target Plates

Only one sequence is sufficient to reformat a single 96-well micro-plate with 12 columns. However, four 96-well plate sequences are needed to reformat an entire 384-well micro-plate with 24 columns.

Options which include mixing and delays after sequences can be selected if needed. The "dispose of tip" option, when enabled, changes the tip after each dispense. Multiple dispensing using same tip can also be opted when transferring small volumes which cannot be done using the multiple dispensing option.

| _ Options | |
|---|--------------------------|
| Delay After Sequence (hh:mm:ss) | 00:00:00 |
| Mixing | |
| Mix Cycles | 0 |
| Mix Volume (μL) | 0 |
| Mix Asp Depth (mm) | |
| Mix Disp Depth (mm) | 0 |
| Dispose of Tip | |
| Plate Replication | |
| Multiple Dispensing- | One-One Transfer |
| | |
| L | |
| | |
| Buffer Source | Ð |
| Buffer Source Without Di | |
| Without Di | lution |
| | lution |
| Without Di | lution |
| Without Di Without Di | lution |
| Without Di Without Di Reservoir Posit | lution lution |
| Without Di Without Di | lution |
| Without Di Without Di Reservoir Posit | lution lution tion |
| Without Di Without Di Reservoir Posit | lution lution |

Figure 11-8 VERSAware Plate Reformatting Tab Options



The plate replication option allows one to reformat from one source plate to 5 similar type of target plates as shown below in *Figure 11-9 VERSAware Plate Replication Option*.

| | A v3.6.4 - [Control Center] | | | | | | | | | | (Contrate |
|----------------------|---|----------------|-----------------------|--|---------------------|--------------------------------|--------------------|--------------------|--------------------|---------------------|---------------------|
| 🚰 File Run Res | tore Security Tools Help | | | | | | | | | | |
| | L 🗙 🖸 🛈 | 0 C 🏠 | <u>Ī</u> Ⅲ ĭ→ĭ | | | | | | | | |
| 1617 | | | | | Standard Plates | Vial/Tub Holder | e Carou | isel Res | ervoir 1 | Tip Box | Reagent Cooler |
| | 07 07 07 07 07 07 07 07 07 07 07 07 07 0 | | | | 1 96 | 96 DEEP 1 | 52 96 DEEP 2 | se 96 DEEP 3 | | 58. 96 DEEP 5 | •8: 96 DEEP:6 |
| | | | | | 71 1 96 | 7 7 76 | 451 96 | 96 | 48: | 592 | 96 PELP 6 |
| 18 | 96 96 | 96 96 | 26 | | DEEP.7 | PCR 1 | PCR 2 | PCR 3 | PCR 4 | | PCR:6 |
| | ** 98 PCR2 96 1 | 3 A AMBION | | | ⁰³ . 96 | i) FILTER 96 | 2 | ¹³ 384 | 42: RECEIVER 96 | ⁶⁹ 96 | ²³ |
| The i | | | | | PCR 7 | | 384 | PCR | | ELISA | IONFLUX |
| Common Special | Plate Reformatting | Cheny Picking | NAP/Advance | ed Reagent Addition | Normalization | | Plate Tra | nsport | | | |
| KAPA Stranc DEMO | Clear Plate Reformatting I | Parameters | | | Options | | | | | | |
| E-O DEMO | | | _ | Sample | Delay Af (hh:mm: | ter Sequence 18) | 00.00.00 | E | | | |
| | Source 6 | • | Target | Volume (µL) | ☐ [Moar | Mix Cycles | | - | | | |
| | Volume (µL) | 96-Well Plate | 7 | ▼ 15 | ь | Mix Lycle: fix Volume (µL | | 0 | | | |
| | | | 8 | 15 | | isp Depth (mm isp Depth (mm | | 0 | | | |
| | | | 9 | ▼ 15 | | ose of Tip | · 1 | | | | |
| | | | 10 | ▼ 15 ▼ 15 | | Replication | | | | | |
| | 123451 | 7 8 9 10 11 12 | 12 | ▼ 15 | | | pOne-One Tran | ster | | | |
| | | | | | | | | | | | |
| | | | | | T Repea | atCycles 2 | _ | | | | |
| | | | | | ☐ Same1 | Tips | | | | | |
| | | | | | | | | | | | |
| | | | | | | | | | | | |

Figure 11-9 VERSAware Plate Replication Option

NOTE: Source and target plates have to be of similar types to perform plate replication

11.7. NAP/Advanced Reagent Addition Application Tab

This tab allows user to set up the workstation for multi-dispensing reagents from reservoir/96 well plates to target plates. Configure the deck by dragging plates/reservoir to source & target positions. Select source position and target position, add volume to be transferred and select option to execute the commands.

Option"A" is for liquid handling options. Reagents can be aspirated from reservoirs, plates, bead mixer etc. and also from reagent drop to target plates. All the parameters required to perform accurate liquid handling can be used to dispose of tips for every well, reuse tips, mix before aspiration, mix after dispensing, distribute liquid in one to one way mode during multiple dispensing using same tip during bead distribution. Plate can be moved with and without liquid handling as shown below in figures *Figure 11-10 Advanced Reagent Addition Tab—Option A parameters* and *Figure 11-11 Advanced Reagent Addition Tab—Option "A" execution order*.

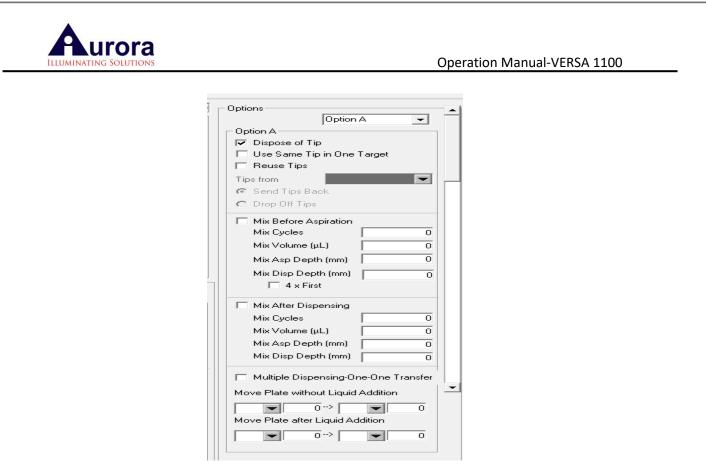


Figure 11-10 Advanced Reagent Addition Tab—Option A parameters

| Cherry Picking NAP/Advanced I | Reagent Addition | Normalization |
|---|--|---|
| Option A | After Sequence (hh:mm:ss) 00:00:00 - | Option A Option A ✓ Dispose of Tip Use Same Tip in One Target Reuse Tips Tips from ≪ Send Tips Back C Drop Off Tips ✓ Mix Before Aspiration Mix Cycles 1 Mix Volume (µL) 1000 Mix Asp Depth (mm) 10.85 |
| Option Execution Order: A • • • • Reset Order Option B 0:00:00 -> Direction Shaking Time 00:00:00 -> Direction Swing(step): 20000 Delay after Shaking: 0:00:00 -> Position 12 • Magnetic Stanby Time: Vacuum Delay: 00:00:00 -> Vacuum Delay: 0:00:00 -> Move to Mag Block 0> Move to Mag Block 0> Move back to Shaker: 0> 0 > 0 | Option C Set Temperature Plate Temperature Incubation Time Move Plate Before Incubation Incubation Time Incubation Incubation | Mix Disp Depth (mm) 10.85 ✓ 4 x First ✓ Mix After Dispensing Mix Cycles 1 Mix Volume (µL) 100 Mix Asp Depth (mm) 10.85 Mix Disp Depth (mm) 10.85 Multiple Dispensing-One-One Transfer Move Plate without Liquid Addition ✓ 0 -> 0 Move Plate after Liquid Addition ✓ 0 -> 0 |

Figure 11-11 Advanced Reagent Addition Tab—Option "A" execution order



Option "B" for shaking , set shaking direction (both directions, one direction, background mode) , speed (rpm), time, plate movement from shaker to magnetic block and back, delay time on magnetic block,

aspirator selection to remove waste using aspirator and vacuum time for aspirator as shown below in figure Figure 11-12 Advanced Reagent Addition Tab—Option B parameters and Figure 11-13 Advanced Reagent Addition Tab—Option "B" execution order.

| Option B Shaking Time Swing(step): Delay after Shaking: | 00:01:00 ÷ 20000 00:00:00 ÷ | Direction Speed(rpn Position | Both Directions O Both Directions 1 One Direction 2 Background 112 |
|---|----------------------------------|------------------------------------|--|
| ✓ Magnetic Stanby Tin ✓ Transfer Target with Position: | ne: 00:0 96-Channel Asp 11 | pirator 💌 | |
| Vacuum Delay: Move Plate To Shaker: Move to Mag.Block after shaking: Move back to Shaker: | 00:00:00 ÷ | | |

Figure 11-12 Advanced Reagent Addition Tab—Option B parameters

| Common Special NimbleGen Seg Cap | Cherry Picking | NAP/Advanced Reagent Addition | Normalization | |
|---|---|---|--|--|
| Andreaster Saq Cag Casa Yeep Jac Litray Prep [A Casa Yeep Ja | Volume (pL) 0 | Delay After Sequence (irkmmts) Volume (ul.) 31 Target 7 Auto Mode Oont Set Samele Reagent Drop Double Channels | Option A Option A Option A Option A Depose of Tp Use Same Toin One Target Rause Top Tips from C Send Tips Book. C Dop Off Type Mike Selece Appriation Mix Cycles Mix Cycles Mix Option public from Mix Option public from Object of the fore public from | |
| Bead Wath 2 (Autor: 20 Add Mon Buffer (Autor: 1) Transfer DNA Sample (Autor: 1) Transfer DNA Sample (Autor: 1) Annylly Sample (Assay LMPCR (| Option B ▼ ▼ Execution Order: B ▼ ▼ Option B 000100 → Decision Swing(step) 20000 Speedyn Delay after Shaking 100000 → Position IF Angretic Starby Time: 0000100 → Position: 11 Image: Vacuum Delay 000000 Vacuum Delay 000000 → Move Pate To Shake: Image: 0 → 0 → Move English Tabling: 11 Image: 0 → Move back to Shake: Image: 0 → 0 → | 12 Terroperature Incubation Time 00.00 Move Flate Batter Incubation Move Plate After Incubation 11 0 12 0 | Mix Volume (sl.) 0 0 Mix App Depth (rem) 0 00 Mix Oup Depth (rem) 0 00 The Oup Depth (rem) 0 00 Mix Note Depth (rem) 0 Mix Polace Without Liquid Addition Mix Polace Without Liquid Addition | |

Figure 11-13 Advanced Reagent Addition Tab—Option "B" execution order



Option "C" for incubations of the plate at different temperatures. Select the position to set the plate cooler/heater temperature, set temperature, set the duration of incubation. Temperature can be set in background mode too—this is the option which works in background mode to set the required temperature without interfering the protocol run e.g. if the temperature is required to be raised in the protocol but needed after 40 minutes/10th sequence, a sequence can be created earlier to set temperature in background mode so that by the time it reaches to that sequence, temperature will be almost set (can be read in this sequence). This saves time to raise the temperature during that sequence. Select all the parameters as shown below in *Figure 11-14 Advanced Reagent Addition Tab—Option "C" execution order*.

| Special | Cherry Picking NAP/Adva | nced Reagent Addition | Normalization |
|--|--|--|--|
| Nomblettern Seq Lap Nomblettern Seq Lap Normalization of samples [Au Normalization of samples [Au Norw used plate to position if Add Conditioning Sol [Autho Add Fragmentation MM [Autho | Clear Advanced Reagent Addition Parameters Diption A Source 6 Sample Volume (µL) | Delay After Sequence (hh:mm:ss) 00:00:00 34 Target 7 | Option A Option A |
| Lower temperature of position Move plate to 4 degree [Aut Add End Repair MM [Author | Volume (µL) 0 Auto Mode Reagent Drop I 1 2 3 4 5 6 7 8 9 10 11 12 | Don't Set Samole Number | Dispose of Tip Use Same Tip in One Target Reuse Tips |
| Add Seq Cap Adaptors [Auth Add Seq Cap Adaptors -2 Add Seq Cap Adaptors -2 Add Ligation MM [Author : 2 Seq Cap Adaptors -2 Add Ligation Cleanup- ac | | | Send Tips Back Drop Off Tips |
| Bead Wash 1 [Author : 20 Bead Wash 2 [Author : 20 Add Elution Buffer [Author : 20 Transfer DNA Sample [Author Add Beads-double sided size | | | Mix Before Aspiration Mix Cycles 0 Mix Volume (µL) 0 |
| Horizanti | P P P P P P P P P P P P P P P P P P P | | Mix Asp Depth (mm) 0 Mix Disp Depth (mm) 0 4 x First 0 |
| Add Elution Buffer [Author : : Transfer DNA Sample [Author Amplify Sample Library LM-PCR [Hybridize Sample & SeqCap EZ F | Execution Order: C | Option C Set Temperature Background Temperature | Mix After Dispensing Mix Cycles 0 |
| Wash & Recover Captured Multip Amplify Captured Multiplex DNA (KAPA Stranded RNA-Seq Kit with Ril KAPA Stranded RNA-Seq Kit with | | | Mix Volume (μL) 0 Mix Asp Depth (mm) 0 Mix Disp Depth (mm) 0 |
| ☐- ☐ TEST ☐- ↓ The assay created in 2016-05-0E ⊡ ↓ Move Plates [Author : 20 Las | Transfer Target with 96-Channel Aspirator 💌 | Move Plate Before Incubation | Multiple Dispensing-One-One Transfer Move Plate without Liquid Addition |
| | Move to Mag Block | Move Plate After Incubation 0 0 0 0 0 0 0 0 0 0 0 0 0 | Image: Weight of the state |

Figure 11-14 Advanced Reagent Addition Tab—Option "C" execution order

Options ABC : Using all the three options—liquid handling in option A, move plate to shaker after liquid handling, shake plate in option B, move plate before incubation in Option C. Select the execution order A, B, C as shown below in *Figure 11-15 Advanced Reagent Addition Tab—Using all three options ABC*. It can be any execution order—B,C,A etc. depending upon protocol requirements like shake, incubate and liquid handling etc.



Operation Manual-VERSA 1100

| Common Special NimbleGen Seg Can | Cherry Picking | NAP/Advanced Reagent Addition | Normalization | |
|--|---|--|--|--|
| NinbleSen Seq Cap Kapa Hyper Julus Library Prep [Al- Normalization of samples [Al- Add Fragmentation MM [Ault Continning Sol [Aution Add Fragmentation MM [Ault Lower temperature of position Add Seq Cap Adaptore [Ault Add Sea Vash 1 [Author: 20 Bead Vash 1 [Author: 20 Add Euton Buffer [Author: 21 Add Sea Capation Buffer [Author: | | Delay After Sequence (hhrmms) Volume (µL) 150 Target 7 Auto Mode Reagen Drop Double Chennels | Option A Image: Control of the sector of the s | |
| Add Beads double sided size Add Beads double sided size Add Beads double sided size Add Eads Add Mah 1 (Auhor : 20 Add Elution Buffer (Auhor : 20 Add Elution Buffer (Auhor : 2) Anold Sample Sacca Each Park Anold Sample Sacca Each Park Wash & Recover Captured Multip Add Extended RNA Sac Kit with Beads Add RNA Sac Kit with Beads Alark Standed RNA Sac Kit with Beads Beads Move Plates (Author : 20 Las | Uption Execution Order: A Ø bin B Ø binking Time Ø binking Time Swingtstep) 2000 Speedip Delay after Shaking Ø hange for Stanky Time: Ø 00100 ÷ Postal Move Flate To Shaker: Ø wve to Mag Block øfter shaking Ø wve to Ko Shaker: Ø wve | m): 2000 Plate 8 12 ▼ Temperature Incubation Time 00.10 Move Plate Before Incubation 112 ▼ 0→ 8 Move Plate After Incubation ▼ 0 ▼ 0 | Image: Second | |

Figure 11-15 Advanced Reagent Addition Tab—Using all three options ABC

Follow the steps below for a typical Nucleic Acid Prep protocol using magnetic beads.

1.Add sample (e.g. buccal swab) into a deep well 96 well plate on the shaker position # 12.

Save this sequence.

2.Add lysis buffer from reservoir to the sample, shake it for 3-5 min depending on the kit requirements. Save the sequence using options A and B

3.Add proteinase K from reservoir & magnetic beads (from bead mixer in single channel mode) to the sample plate, shake again, after shaking move the plate to magnetic block, delay for 1-2min, discard the waste to waste position by changing tips or use aspirator, move the plate back to shaker position

4.Add wash buffer 1 using reagent drop, shake again, after shaking move the plate to magnetic block, delay for 1-2min, discard the waste to waste position by changing tips, move the plate back to shaker position.

5.Repeat step 4 with wash buffer 2 & 3.

6.Add elution buffer, shake again, after shaking move the plate to magnetic block, delay for 1-2min, collect the sample to another plate by changing tips for each sample. Discard the bead plate.



11.8. Slide Tab

This tab allows user to set up sample transfer from source plate/tubes to 2X4 slides. Configure the deck by dragging source plate, slide to source & target positions. Select source position & target position, then ass sample volume. Save this sequence and run it, make multiple test run to adjust the offsets, please see figures below as samples:

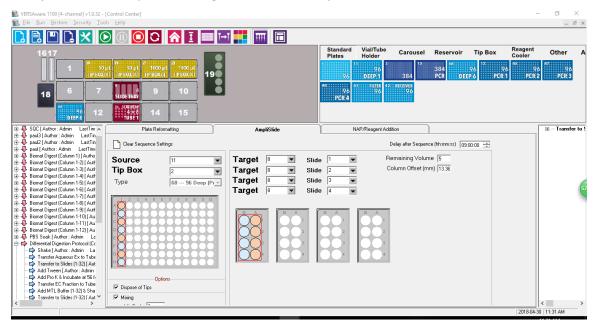


Figure 11-16 Slide Tab--Sequence settings-Protocol 1

Follow the steps below for a typical Slide Application.

1 Configure the deck according to protocol by dragging all required plate types, tip boxes etc.. Select sample source, target as well as slides, select sample and transfer target, input volume.

2 Select tip box location with black conductive tip, make sure LLS option in option manu is activated.

3 Once the sequence has been saved/updated, do multiple test runs to verify the aspiration offsets and dispense offsets, you can modify these offsets inside option manu.

4 You can also copy existing Slide sequence, modify and save for new applications.



12.UV/HEPA Hood

The bio-containment hood (*Figure 12-1 UV/HEPA Bio-Containment Hood*) is designed to provide sterile air quality for the assay sequence workspace by utilizing a high efficiency particulate air filter (HEPA). By performing filtration of the air within the workspace, the hood prevents contamination of the agents used during any given sequence. In addition, cross-contamination by harmful particulates or microbes in the air surrounding the workspace is reduced with the built in UV lamp.



Figure 12-1 UV/HEPA Bio-Containment Hood



Figure 12-2 UV/HEPA Bio-Containment Hood—Control Panel

1. Fan Switch – Turns on and off the containment hood's fan to draw external air inward.

With the fan running, air is filtered as it enters the hood.

2. Light Switch – Turns on and off the containment hood's fluorescent light, which allows for a brighter workspace environment.

3. UV Switch – Turns on and off the ultraviolet light source, which is used to

De-contaminate the workspace.

4. UV Timer Control – Along with the UV switch being turned on, the UV Timer Control is used to set the duration of the UV light source.



13.Workstation Maintenance

13.1. General Guidelines

It is important to follow the general guidelines and instructions described in this manual in order to maintain the proper function of the VERSA 1100 NAP/PCR Workstation:

Use only clean vessels such as micro plates, reservoirs, micro tubes, vials, beakers, flasks, tip boxes and reagent/cooler block

It is recommended to use sterile pipetting tips with filter barrier

Only use 20µL, 50µL and 200µL pipetting tips with the VERSA 1100NAP/PCR

Do not leave vessels exposed to dust and dirt overnight

13.2. Tubing

All tubes should be tightly connected to adapters and should not be twisted or bent. All tubing is made of durable Teflon which cannot be easily ruptured or bent. If aspirating or dispensing viscous liquids, adjust the aspiration/dispensing speeds in the software.

13.3. Waste Bottles

All tubing should be inserted into the bottles as described in Tubing and Bottles section of this manual.

It is very important that the waste liquid bottle does not over fill. Otherwise the waste liquid may fill the vacuum tube and cause damage to the vacuum pump.

| S/No | Description of Maintenance Program | Frequency | Good | No Good | Actions Taken / Remarks |
|------|--|--------------------|------|------------|-------------------------------|
| А. | Daily Maintenance Program | | | | |
| 1. | Inspect & clean any visible Reagent / Chemical Spillage on the instrument with Isopropyl Alcohol. | Begin / End day | | | |
| 2. | Do not leave test samples in tube plate stacker placed on Shaker or target plates on the VERSA 1100 when terminating / aborting the protocol operation. | 1x (End day) | | | |
| 3. | Remove & discard all the used tips in the collection tray / bags/ box. | 1x (End day) | | | |
| 4. | VERSA 1100 Module All tubes are correctly inserted into the System Fluid and waste bottles | 1x | | | |



| | Power Cord & USB cable/COM-Port connection | | | |
|----|---|--|--|--|
| | Verify critical teaching positions | | | |
| | Visual Inspection for any abnormality in function, misalignment / visible signs of damages: | | | |
| | Robotic Arm & Gripper | | | |
| | 8-channel Syringe Pump Unit | | | |
| | 5-channel Reagent Drop Unit | | | |
| | Shakers | | | |
| | Clean the Reagent Drop pins from outside with distilled water at the end of daily operation to prevent any salts depositing to pins | | | |
| 7. | Gripper | 1x | | |
| | Power Cord & USB/COM-Port cable connection | | | |
| | Verify gripper position | | | |
| В. | Weekly Maintenance Program | | | |
| 1. | Inspect the Wash Fluid – adequate level required for the operation and visual check | 1x per | | |
| | of contaminants and potential growth in the bottle. Recommendation – replace the Wash fluid every week. | week | | |
| 2. | of contaminants and potential growth in the bottle. Recommendation – replace the Wash | week 1x per week | | |
| 2. | of contaminants and potential growth in the bottle. Recommendation – replace the Wash fluid every week.General cleaning of the exterior instruments | 1x per | | |
| | of contaminants and potential growth in the bottle. Recommendation – replace the Wash fluid every week. General cleaning of the exterior instruments –particulates & stain. Removal of any trapped parts on the deck | 1x per week 1x per | | |
| 3. | of contaminants and potential growth in the bottle. Recommendation – replace the Wash fluid every week. General cleaning of the exterior instruments –particulates & stain. Removal of any trapped parts on the deck and below the deck. Perform routine check on individual hardware modules Visual Inspection for any abnormality in function, misalignment / | 1x per week 1x per week 1x per | | |
| 3. | of contaminants and potential growth in the bottle. Recommendation – replace the Wash fluid every week. General cleaning of the exterior instruments –particulates & stain. Removal of any trapped parts on the deck and below the deck. Perform routine check on individual hardware modules Visual Inspection for any abnormality in function, misalignment / visible signs of damages | 1x per week 1x per week 1x per | | |



| 1. | Discard the leftover Wash fluid, clean the bottle thoroughly and re-fill with the System fluid/ Wash fluid. | 1x per month |
|----|--|--|
| 2. | Clean the System Fluid/ Priming Waste / Waste / Reagent Bottles. | 1x per month |
| 3. | Visual inspect and replace any twisted or serious bent tubes (if any). | 1x per 6 months |
| 4. | Perform routine check on individual hardware modules - Visual Inspection for any abnormality in function, misalignment / visible signs of damages, worn out parts. VERSA 1100 Multi-dispensing RD Inspect and add lubricants: WD40/ grease at various critical mechanical moving parts. | 1x per month 1x per 6 months |
| 5. | Perform volume check & calibration VERSA1100: 8-channel Syringe Pump Unit VERSA1100: 5-channel Reagent Drop Unit | 1x per 4 months |

14. Troubleshooting

This section will discuss the following potential problems users might encounter with the VERSA1100 Workstation.

| VERSA1100 Troubleshooting | | | | | |
|---------------------------|---|--|--|--|--|
| Problem 1 | Power is off | | | | |
| Problem 2 | No communication with the VERSA | | | | |
| Problem 3 | Aurora Arm does not respond to operator's command | | | | |
| Problem 4 | Aurora Arm does not move to correct position | | | | |
| Problem 5 | Aurora Arm stops during application sequence run | | | | |
| Problem 6 | Syringe pumps do not respond to operator's command | | | | |
| Problem 7 | Syringe pumps do not aspirate or dispense accurate volume | | | | |
| Problem8 | Pipetting tips are damaged or bent | | | | |



| Problem 9 | Pressure and vacuum pumps are not working |
|------------|---|
| Problem 10 | While running the sequence, a hanging drop is formed outside of the tip |
| Problem 11 | The pipetting tip does not aspirate the master mix in the reagent block |
| Problem 12 | Pipetting tips do not dispense small volumes (1 - 5 μL) |
| Problem 13 | VERSA stops working suddenly or operation hangs midway |
| Problem 14 | During Multiple dispensing of any reagent, first well and last well volumes are not correct |

Trouble Shooting Problems

The VERSAware V1100 software provides advanced error messaging and a detailed log for both Aurora Arm and Syringe Pumps. Most common problems and solutions are discussed below.

Problem: Power is off

Solution: Please check if power cable is properly connected to the VERSA and AC outlet as discussed in the Wire and Cable Connections section. Make sure that the power switch is on. For additional information please refer to the Specifications section of this manual for the correct voltage settings.

Problem: No communication with the VERSA

Solution: Please ensure that USB cable is tightly connected to the VERSA and computer USB port as described in the Wire and Cable Connections section. Please check correct COM port configuration in MS Windows XP/2000.

Start \rightarrow Settings \rightarrow Control Panel \rightarrow System \rightarrow Hardware \rightarrow Device Manager \rightarrow Ports

Device status of COM ports should read: This device is working properly. All COM port numbers should not exceed 16. Please refer to the USB Driver Installation section of this manual for more information how to change the COM port number.

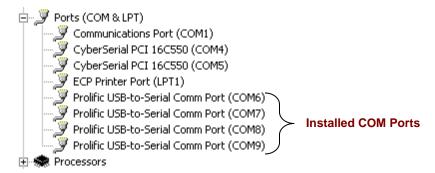


Figure 14-1 Correct COM Port Configuration in MS Windows XP/2000

If COM ports are not visible in Windows XP/2000 Device Manager, install the USB driver for the USB/Serial COM Port Converter contained within the VERSA as described in the USB Driver Installation chapter of this manual.

Problem: Aurora Arm does not respond to operator's command



Solution: Please ensure that the arm is initialized in Device Manager AS software. Make sure that the COM port settings are correct in the Device Manager AS software as explained in the Device Manager AS Settings chapter. If the problem still remains, try to shut down and restart the VERSA and initialize the robotic arm once again.

Problem: Aurora Arm does not move to correct position

Solution: Please refer to the Teaching Positions section to adjust or repeat the teaching procedure for all positions. If the problem still remains, try to initialize the robotic arm again.

Problem: Aurora Arm stops during application sequence run

Solution: Please refer to the Device Manager AS Settings section to decrease robotic arm speed and acceleration settings for every axis (X, Y, and Z). It is recommended to gradually reduce end speed by 500 or 1,000steps/sec. Acceleration should be reduced to 1 or 3 steps/sec2. Can start the sequence from the step it last stopped at by left clicking to resume.

Problem: Syringe pumps do not respond to operator's command

Solution: Please ensure that both syringe pumps are initialized in the Device Manager AS software. Make sure that the COM port settings are correct in the Device Manager AS software as explained in the Syringe Pump Settings and Calibration chapter. If the problem still remains, try to shut down and restart the VERSA IK software and initialize the syringe pumps one more time

Problem: Syringe pumps do not aspirate or dispense accurate volume

Solution: Please refer to the Syringe Pump Settings and Calibration section of this manual and perform new calibration procedures if necessary.

Problem: Pipetting tips are damaged or bent

Solution: In case of accidental tip damage, press the Home Aurora Arm button in the VERSAware 1100 software to initialize the robotic arm from home icon to disengage the damaged tip.



Figure 14-2 VERSAware Toolbar Arm Initialization and Tip Disengagement Icon from Home icon

Problem: Pressure and vacuum pumps are not working

Solution: Please contact Aurora Biomed Inc. to obtain new pressure and vacuum pumps, instructions on how to install them or request technical assistance.

Problem: While running the sequence, a hanging drop is formed outside of the tip

Solution: The engaged pupating tip is probably loose. Check the position of that tip box. After engagement, tip should be tightly fitted to the barrel.

Problem: The Pipetting tip does not aspirate the master mix in the reagent block



Solution: The pupating tip probably touches the bottom of the 7 mol vial. Please refer to the VERSAware 1100 Settings section of this manual to decrease the Master Mix Block Depth (mm). Or the pupating tip might be above the master mix volume level. Increase the Master Mix Block Depth (mm) in this case. Alternatively, click Pause when the tip goes to aspirate solution and subsequently check/fix the Z-Offset (calculate with Z-Offset calculator).

Problem: Pipetting tips do not dispense small volumes (1 - 5 μ L)

Solution: The pipetting tip should slightly touch the bottom of the micro plate. Please check the Z-offset in VERSAware Option for that particular plate type, to increase / decrease the plate's Z-Offset (mm) for any application tab.

Problem: VERSA1100 stops working suddenly or operation hangs midway

Solution: Hibernation, standby or sleep mode is enabled on system software. To change these settings, please refer to section 2 (power saving settings) of manual for more details. Try closing and reopening the software again. If problem persists, restart the PC and reopen the software.

14 During Multiple dispensing of any reagent-first and last well volumes are not correct

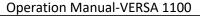
During multiple dispensing of any reagent--to ensure the volumes in first well and last well are correct, following settings need to be optimized.

Extra Aspiration/ Dispense back volume and backlash settings e.g. extra aspiration volume is set 10μ L, dispense back volume is 8μ L and backlash is set at 0-according to these settings, at the end after dispensing in all wells--theoretically, there should be 2μ L (10-8) left in the tip (which can be dispensed back at source) but due to backlash of the pump--it can be more or less--if more--decrease the difference

in Asp/Disp.---10/9/0 and if still more then set backlash too-10/9/2 depending upon how much left in the tip and if less then increase the difference--10/7/0, 10/6/0

First volume correct--dispense back volume settings- 10/8/0 or 12/10/0

Last well Volume correct--difference in the Asp/Disp.--10/7/0 (If left less), 10/9/0 (if left OK), 10/9/2 (if left more). Please check *Figure 14-3 Extra aspiration/dispense back volume settings*.





| ringe Pump Tip Boxes | Plate Types Reagent Drop Other General VarF | ef Arm Movem | ents Pump Spe | eds Arm Spe |
|------------------------|---|----------------|-----------------|---------------|
| | | 250µL | 8×250μL | |
| | Tip Volume | | | |
| | Max. Volume (μL) | 300 | 300 | |
| | Switch Volume (μL) | 300 | 300 | |
| | Extra Volume | | | |
| | Extra Aspiration Volume (μL) | 15 | 15 | |
| | Extra Dispensing Volume (μL) | 10 | 10 | |
| | Backlash Volume (μL) | 8 | | |
| | Delay | | _ | |
| | Delay After Aspiration (s) | 0 | 0 | |
| | Delay After Dispensing (s) | 0 | 0 | |
| | Priming | | | |
| | Priming Cycles | 0 | 0 | |
| | Back Aspiration Volume (µL) | 0 🖸 | 0 | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |

Figure 14-3 Extra aspiration/dispense back volume settings

To add these settings in the sequence—open that particular sequence--open OPTIONS--Syringe PUMP--change the settings for extra Aspiration/Dispense back and if required backlash too and then update the sequence. These setting will come in the steps--can be confirmed by checking steps as shown in the *Figure 14-4 Extra aspiration/dispense back volume showing in the steps*.



Operation Manual-VERSA 1100

| | 11 12 | 13 | 14 200 µL | | | | | | | | | | |
|---------------------------------------|--|-----------------------|-----------------------------------|------------------|----------------------------------|----------------|------------------------------|--|--|--|--|--|--|
| Common Prepare I B- D Assay cri | Dilution | Plate Reformatting | Cherry Picking | PCR | NAP/Advanced Reagent Addition | Serial Di | lutions | | =AS01} Move Arm To Saf | iety Z-Offset (| 5-12-01 14:34:26 [Author: 20 La 1 [Arm ID] 120 [Safety Z-Offset]) psition] -20 [Safety Z-Offset] 0 [Number c | | |
| ☆ NAP ☆ NAP ☆ NAP | Clear Advance | ed Reagent Addition P | arameters | Delay After S | equence (hh:mm:ss) 00:0 | 0.00 🛨 | Options | Dotion A | = <mark>AS01} Pump Aspirating (</mark> =AS01} Move Arm To Saf | 3 [Pump ID] iety Z-Offset (| 1 [Action] 2228 [Steps] 20 [Volume]) 1 [Arm ID] 120 [Safety Z-Offset]) ID] 8 [Position] 4 [Plate_Tupe] 2 [Arm Iv | | |
| Customer Prc | Source 8 | • | Sample Volume (µL) | 20 Ta | rget 🤋 | • | - Option A- | | =AS01} Pump Aspirating (| 3 [Pump ID] | 1 [Action] 10281 [Steps] 90 [Volume]] | | |
| Customer Pro | Volume (µL) | 🔲 Auto Mor | Auto Mode Don't Set Samole Number | | nber | Dispose of Tip | | ASO1) Pump Dispensing (3 [Pump ID] 2 [Action] 936 [Steps] 8 [Vol me]] ASO1) Move Arm To Salety Z-Offset (1 [Arm ID] 120 [Safety Z Diffset] 1 ASO1) Move Arm To Postion (1 [Arm ID] 9 [Position] 1 [Plate Type] 2 [Arm | | | | | |
| | 1 2 3 4 | 5 6 7 8 9 | 10 11 12 | 1 2 3 4 | <u>5678</u> 9101 | 12 | 🔲 Reuse t | tips | AS01) Pump Dispensing | (3 [Pump ID] | 2 [Action] 2228 [Steps] 20 [Volume]] | | |
| | | | | | | | Tips from | | =AS01} Move in the Z wa =AS01} Move Arm To Por | | -25.85 [Zoffset]) ID] 9 [Position] 1 [Plate Type] 2 [Arm Iv | | |
| | | | | | | | 🕼 Send Ti | | AS01) Pump Dispensing | (3 [Pump ID] |] 2 [Action] 2228 [Steps] 20 [Volume]] | | |
| | A | | | | | | C Drop Of | | =AS01} Move in the Z wa | | -25.85 [Zoffset]) ID] 9 [Position] 1 [Plate Type] 2 [Arm Iv | | |
| | | | | | | | 🖂 Mix Befr | | | | 2 [Action] 2228 [Steps] 20 [Volume] | | |
| | | | | | | | Mix C | | =AS01} Move in the Z wa | | -25.85 [Zoffset]) ID] 9 [Position] 1 [Plate Type] 2 [Arm 1+ | | |
| | | | | HÖÖÖC | | | MixV | | | | 2 [Action] 2228 [Steps] 20 [Volume] | | |
| | Sequence] NAP/Advanced Reagent Addition created on 2015-12-01 14:34:26 | | | | | | | | | AS01) Move Arm To Safety Z-Offset (1 [Arm ID] 120 [Safety Z-Offset]) 8 [Position] 4 [Plate Type] 2 [Arm 1 | | | |
| | | | 🔚 [Sequ | ence] NAP/Advan | ced Reagent Addition c | reated on 2 | 015-12-01 14 | :34:26 | and the second second | | [8 [Position] 4 [Plate Type] 2 [Arm M [2 [Action] 2446 [Steps] 22 [Volume]] | | |
| | Option Execution Order | | | ap Settings | | | 1 - 1 | | | | Arm ID] 120 [Safety Z-Offset]) Pin Group] 1 [Use Safety ZOffset]) | | |
| | Option B | | | Pump Tip Boxes | Plate Types Reagent | Drop Uthe | r General \ | VarHet Arm Movi | ements Pump Speeds | Arm Speed | Finicioup) i (ose salely zonsel) i | | |
| | 🗆 Shaking Time | | | | | | | 250µL | 8×250μL | | | | |
| | Swing(: | tep): 20000 | Speed | | | | Tip Volum | | | | | | |
| | Delay after Sha | king: 00:00:00 ÷ | Posil | | | | x. Volume (µ | ' | | | | | |
| | Magnetic Sta | nby Time: 00: | 00:00 ÷ | | | | h Volume (μ | , | 300 | | | | |
| | Transfer Tar | et with | | | _ | | xtra Volum | | | | | | |
| | | 1 | | | | | n Volume (µ | ' | | | | | |
| | | | | | Extra | | g Volume (µl h Volume (µl | ' | | | | | |
| | | | | | | Dackias | n volume (µ Dela | ~/ | U | | | | |
| | | | | | | | Dela | iy . | | | | | |

Figure 14-4 Extra aspiration/dispense back volume showing in the steps

Note: If using filter tips—set the Maximum volume in OPTIONS—Tip Box as— 20μ L as 10μ L, 50μ L — 45μ L, 200μ L - 180μ L and 1000μ L-- 900μ L

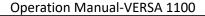
15.Specifications

Weight : 90 kg without hood

Deck Positions : 15 Deck positions

Head : Dual Head Configuration - 8 Channel Tip

Changer & Single Channel





| D: 550 mm W: 930 mm | н: | 790 mm |
|---|----|--------|
| PWM Pump (Reagent Drop) Pressure : 15 psi Max. Dispensing Volume : 10ml | | |
| 250μL Syringe Asp/Dispensing Volume Range : 1 - 250 μL | | |

1,000 μL SyringeAsp/Dispensing Volume Range :2- 1000 μL

| Voltage | : | 100 ~ 120 Volts |
|-----------|---|-----------------|
| Current | : | 5 A, Fuse: 10 A |
| Frequency | : | 50 – 60 Hz |

16.System Requirements

This section will provide minimum system requirements to successfully operate the VERSA1100Workstation.

One dedicated IBM compatible personal computer with Pentium 4 processor, 1.5 GHz or higher

1GB RAM (64-bit) or 2GB RAM (32-bit)

100 GB of hard drive space



US version of Microsoft Windows 2000 Professional (Service Pack 4 or greater),

Microsoft Windows XP Professional (Service Pack 1 or greater),

Microsoft Windows Vista or Window 7

SVGA display (1024 x 768 true color)

PS2 mouse

At least 1 USB 2.0 port

1 CD-ROM drive

System and Computer Requirements

17.Product Service and Customer Support

Aurora Biomed Inc. offers a full range of services to ensure your success. From our original factory warranty through a comprehensive line of customer support plans, Aurora Biomed Inc. offers Field Service Engineers and in-house Specialists who are dedicated to supporting your hardware, software and application development needs.

Aurora Biomed Inc. 1001 East Pender St., Vancouver, BC

Canada V6A 1W2

Tel. 1-604-215-8700

Tel. 1-800-883-2918 (Toll free in North America only)

Fax 1-604-215-9700

E-mail info@aurorabiomed.com

www.aurorabiomed.com

Oakland Police Department Criminalistics Laboratory DNA Instrumentation and Analysis Software Biometric Technology Use Policy September 2020

1. Purpose

The Oakland Police Department (OPD) Criminalistics Laboratory's (Crime Lab) Forensic Biology/DNA unit utilizes specialized DNA collection and analysis instrumentation and software to perform forensic DNA testing. During this lengthy and complicated process, one step removes and purifies DNA from cells (digestion/extraction), another quantitates how much DNA is present and lastly, by amplifying and analyzing Short Tandem Repeats (STR) in the DNA using Polymerase Chain Reaction (PCR) and separated by Capillary Electrophoresis (CE), forensic DNA profiles are generated. Software is involved in the following processes: (i) collection and processing of STR DNA fragment data; (ii) interpretation of DNA data into DNA profiles used for comparison purposes. At the end of all processes, a determination can be made as to whether a DNA sample collected from a crime scene can be associated with a known individual through a comparison of evidentiary (crime scene) and known reference DNA profiles. Statistical weight is provided for all inclusion comparisons.

The technology within the scope of this Biometric Technology Use Policy includes:

Digestion / Extraction

- **Aurora Biomed**: Versa 1100 liquid handler instrument and VERSAware software for automated cell digestion and microscope slide preparation.
- **Qiagen:** EZ1 Advanced XL instrument and EZ1 Advanced XL Investigator Protocol Card (Software) for extraction and purification of DNA.

DNA Quantitation

- **Qiagen:** QIAgility Liquid Handler Robots and computers for rapid, high-precision automated PCR setup (also used for Normalization/Amplification and DNA Typing).
- **Applied Biosystems**: 7500 Real Time PCR systems and 7500 System Detection Software for determination of quantity and quality (degradation level) for a DNA sample.

DNA Normalization / Amplification – STR (autosomal and Y)

- **ThermoFisher Scientific**: SpeedVac DNA Concentrator for concentrating low quantity DNA samples.
- **ThermoFisher Scientific**: 9700 and ProFlex Thermalcyclers for PCR amplification of STR DNA fragments.

DNA Typing – STR (autosomal and Y)

• **ThermoFisher Scientific**: Applied Biosystems 3130 (current technology in use) and 3500 (similar technology undergoing validation to replace 3130) Series Genetic Analyzer and Data Collection Software is designed for data collection in human identification (HID) applications. The Crime Laboratory uses/intends to use this software to collect STR DNA data from amplified samples. This software normalizes genetic data and creates "hid" files to be used by data processing (GMIDX or FaSTR) and interpretation (ArmedXpert, STRmix) software.

DNA Interpretation – STR (autosomal and Y)

- **Applied Biosystems**: GeneMapper ID-X Software is used for review and evaluation of sizing and genotyping data generated from the genetic analyzers. This analysis software can be configured to set analysis parameters, edit raw data, and aids to prepare data for further interpretation into DNA profiles.
- NicheVision: FaSTR software is used for review and evaluation of sizing and genotyping data generated from the genetic analyzers. This analysis software can be configured to set analysis parameters, edit raw data, and aids to prepare data for further interpretation into DNA profiles.
- NicheVision: ArmedXpert Analysis Software is used for streamlined DNA typing interpretation resulting in reduced time spent on DNA mixture interpretation. It also uses published and validated population DNA allele frequencies to calculate DNA profile frequency estimates to aid in providing the weight of any inclusion comparison drawn between an evidence sample and a known reference.
- NicheVision: STRmix[™] software combines established and validated biological modelling and complex mathematical processes to use a continuous model to interpret a wide range of complex DNA profiles. It can compare these DNA profiles to a reference profile and calculate the weight of the comparison using well established Likelihood Ratio statistics.

DNA Databasing

• **HP**: Server for the Combined DNA Index System (CODIS) and peripheral computers used to enter and search evidence DNA profiles against legally obtained reference samples (Convicted Offenders, Arrestees, Missing Persons) and other evidence profiles.

The forensic evidence analyzed by the Forensic Biology Unit develops biometric data, however, the Department does not use it in a surveillance capacity (prospectively), it uses it to solve crimes that have already occurred (retrospectively).

2. Authorized Use

The DNA instrumentation and analysis software described above shall be used primarily on evidence or reference samples submitted by law enforcement and collected pursuant to a search warrant, other legal means, or by documented consent. The DNA instrumentation and analysis software shall be used solely for aiding in criminal or civil investigations; for validating new methods and for special projects designed to evaluate improvements to the forensic DNA collection and analysis process, collecting data for statistical studies or lecture presentations; and for quality assurance purposes. To the latter, reference samples from Crime Laboratory staff members, interns, and law enforcement personnel who have access to evidence or the operational areas of the Forensic Biology/DNA unit may be processed using the DNA instrumentation and analysis software as a part of the chain of processes used to

develop DNA profiles to measure or detect a contamination event in the unit, should it occur. All other uses are prohibited. The DNA instrumentation and analysis software shall not be used for personal, non-law-enforcement-related purposes; and shall not be used to surveil, harass, intimidate, or discriminate against any individual or group.

3. Data Collection

The data collected attests to the purity or amount of the DNA and usually also contains genetic information, specifically STR DNA marker alleles (types) that collectively constitute a forensic DNA profile that has the potential to characterize or identify a single individual. (Note: identical twins typically have identical forensic DNA profiles, since they are derived from a single fertilized egg, or zygote).

4. Data Access

Criminalists and Forensic Technicians with duties in the Forensic Biology/DNA unit shall be the only Crime Laboratory personnel authorized to use the DNA instrumentation and analysis software in casework, and only after completing a comprehensive training program and qualifying test, at which time, with the Supervisor's recommendation, the Crime Laboratory Manager issues a written authorization. No one else shall have the authority to grant access to use the DNA purification instrument or software in casework. Criminalists and Forensic Technicians are granted access to one another's cases only for the purpose of discovery or CPRA requests, documenting quality checks, verifications or peer review. Interns also are authorized to use the DNA instrumentation and analysis software for special projects, not casework, and only after receiving necessary training and under the supervision of a qualified Criminalist.

5. Data Protection

All data generated using the DNA instrumentation and analysis software shall be securely maintained at all times in a limited access location, or on a secure server. To evaluate and interpret the DNA analytical data, authorized personnel shall only use computers on secure network drives.

6. Data Retention

Data are retained indefinitely on secure server or network drives. Hard copies of case files containing the laboratory report, notes, and instrument printouts are similarly retained indefinitely in the casefile held in under Crime Lab control with secure, limited-access areas, or at a Departmentally approved Records Retention facility. Retained data may be used if questions pertaining to the case in question arise, or if an investigation into a quality issue arises and is documented in Incident Response.

7. Public Access

Members of the public shall have no direct access to the DNA instrument data generated. If requested under the California Public Records Act (CPRA), the Crime Lab shall deny the request on the ground that such data is exempt from disclosure under the investigative exemption (Government Code section 6254(f), (k) and 6255), Evidence Code Section 1040 and perhaps other exemptions, unless and until they are made publicly available in criminal proceedings. If such a CPRA request is made or if a subpoena or court order is issued for such DNA instrumentation and analysis data, the data shall be made public or deemed exempt from public disclosure pursuant to state or federal law, after consultation with the Oakland City Attorney's Office as needed.

8. Third-Party Data-Sharing

Following the completion and review of a specific case, the case file and data are disseminated only to the law enforcement customer and/or City Attorney and/or prosecuting attorney and assisting staff and shall be subject to discovery in criminal or civil proceedings. The case file and data (including copies) shall not be shared with anyone else without a court order. In addition, crime scene samples that qualify for search in the California State DNA Index System (SDIS) and National DNA Index System (NDIS) (components of the Combined Index System or CODIS database), are uploaded to SDIS according to the NDIS Operational Procedures Manual (<u>https://www.fbi.gov/file-repository/ndis-operational-procedures-manual.pdf/view</u>). Suspect DNA profiles that qualify for search are uploaded to SDIS pursuant to California Penal Code 297.

9. Training

Forensic Technicians and Criminalists in the Forensic Biology/DNA unit shall complete a comprehensive training program and shall not embark on any casework with the DNA instrumentation and analysis software until they have successfully taken a relevant qualifying test. Once qualified, they shall take proficiency tests bi-annually. Interns shall be authorized to use the DNA instrumentation and analysis software for special projects, and not casework, only after receiving necessary training and under the supervision of a qualified Criminalist. Criminalists, Forensic Technicians, and interns in the Forensic Biology/DNA unit shall be provided with a copy of the DNA instrumentation and analysis software and Criminalist IIIs are responsible for providing oversight of the training program, ensuring comprehension of policies and documenting adherence.

10. Auditing and Oversight

The Forensic Biology/DNA unit is overseen by two supervisors and by Crime Laboratory upper management (Crime Laboratory Manager and Quality Supervisor), all of whom shall oversee compliance with this Biometric Technology Use Policy and Standard Operating

Procedures via Administrative and Quality Reviews of casework, policy updates and annual Internal Audits. Additionally, the Crime Lab is accredited by the American National Standards Institute (ANSI) National Accreditation Board (ANAB), which provides oversight to the operation of the Forensic Biology Unit. The Crime Lab is assessed by ANAB on an annual basis. Moreover, the Forensic Biology/DNA unit complies with the Federal Bureau of Investigation (FBI)'s Quality Assurance Standards (QAS) for Forensic DNA Testing Laboratories. The Forensic Biology unit is audited to the FBI's QAS annually, alternating internal and external audits.

11. Maintenance

The mechanism to ensure the security and integrity of the tools, instrumentation and data are insured by oversight provided by the Forensic Biology/DNA unit Supervisors and upper management as defined in the "Auditing and Oversight" section above.

ITEM 7

Last updated 9-25-20

Chapter 9.64 - REGULATIONS ON CITY'S ACQUISITION AND USE OF SURVEILLANCE TECHNOLOGY

Sections:

9.64.010 - Definitions.

The following definitions apply to this Chapter.

1. "Annual Surveillance Report" means a written report concerning a specific surveillance technology that includes all the following:

A. A description of how the surveillance technology was used, including the type and quantity of data gathered or analyzed by the technology;

B. Whether and how often data acquired through the use of the surveillance technology was <u>directly</u> shared with outside entities, the name of any recipient entity, the type(s) of data disclosed, under what legal standard(s) the information was disclosed, and the justification for the disclosure(s);

C. Where applicable, a breakdown of what physical objects the surveillance technology hardware was installed upon; using general descriptive terms so as not to reveal the specific location of such hardware; for surveillance technology software, a breakdown of what data sources the surveillance technology was applied to;

D. Where applicable, a breakdown of where the surveillance technology was deployed geographically, by each police area in the relevant year;

E. A summary of community complaints or concerns about the surveillance technology, and an analysis of the technology's adopted use policy and whether it is adequate in protecting civil rights and civil liberties. The analysis shall identify the race of each person that was subject to the technology's use. The Privacy Advisory Commission may determine, on an individual policy basis, to waive the obligation to identify the race of each person if the probative value is outweighed by the administrative burden and potential greater invasiveness in capturing such data. If the Privacy Advisory Commission makes such a determination, written findings in support of the determination shall be included in the annual report submitted for City Council review.

F. The results of any internal audits, any information about violations or potential violations of the Surveillance Use Policy, and any actions taken in response unless the release of such information is prohibited by law, including but not limited to confidential personnel file information.

Formatted: Not Highlight

G. Information about any data breaches or other unauthorized access to the data collected by the surveillance technology, including information about the scope of the breach and the actions taken in response;

H. Information, including crime statistics, that helps the community assess whether the surveillance technology has been effective at achieving its identified purposes;

I. Statistics and information about public records act requests regarding the relevant subject surveillance technology, including response rates;

J. Total annual costs for the surveillance technology, including personnel and other ongoing costs, and what source of funding will fund the technology in the coming year; and

K. Any requested modifications to the Surveillance Use Policy and a detailed basis for the request.

2. "Biometric Surveillance Technology" means any computer software that uses Face Recognition Technology or Other Remote Biometric Recognition in real time or on a recording or photograph.

3. "City" means any department, agency, bureau, and/or subordinate division of the City of Oakland as provided by Chapter 2.29 of the Oakland Municipal Code.

4. "City Staff" means City personnel authorized by the City Administrator or designee to seek City Council approval of surveillance technology in conformance with this Chapter.

5. "Continuing Agreement" means an agreement that automatically renews unless terminated by one (1) party.

6. "Exigent Circumstances" means a law enforcement agency's good faith belief that an emergency involving danger of, or imminent threat of the destruction of evidence regarding, death or serious physical injury to any person requires the use of surveillance technology or the information it provides.

7. "Face Recognition Technology" means an automated or semi-automated process that: (A) assists in identifying or verifying an individual based on an individual's face; or (B) identifies or logs characteristics of an individual's face, head, or body to infer emotion, associations, expressions, or the location of an individual.

8. "Large-Scale Event" means an event attracting ten thousand (10,000) or more people with the potential to attract national media attention that provides a reasonable basis to anticipate that exigent circumstances may occur.

<u>9.</u> "Other Remote Biometric Recognition" means (A) an automated or semi-automated process that (i) assists in identifying an individual, capturing information about an individual, or otherwise generating or assisting in generating information about an individual based on

Formatted: Not Highlight

Formatted: Space After: 0 pt

Formatted: Not Highlight

physiological, biological, or behavioral characteristics ascertained from a distance; (ii) uses voice recognition technology; or (iii) identifies or logs such characteristics to infer emotion, associations, activities, or the location of an individual, and (B) does not include identification based on fingerprints or palm prints that have been manually obtained during the course of a criminal investigation or detention.

10. "Personal Communication Device" means a mobile telephone, a personal digital assistant, a wireless capable tablet and a similar wireless two-way communications and/or portable internet accessing devices, whether procured or subsidized by a city entity or personally owned, that is used in the regular course of city business.

11. "Predictive Policing Technology" means computer algorithms that use preexisting data to forecast or predict places or times that have a high risk of crime, or individuals or groups who are likely to commit a crime. This definition does not include computer algorithms used solely to visualize, chart, or map past criminal activity (e.g. heat maps).

12. "Police Area" refers to each of the geographic districts assigned to a police commander and as such districts are amended from time to time.

13. "Surveillance" or "Surveil" means to observe or analyze the movements, behavior, data, or actions of individuals. Individuals include those whose identity can be revealed by license plate data when combined with any other record.

14. "Surveillance Technology" means any software, electronic device, system utilizing an electronic device, or similar <u>technological tool</u> used, designed, or primarily intended to collect, retain, analyze, process, or share audio, electronic, visual, location, thermal, olfactory, biometric, or similar information specifically associated with, or capable of being associated with, any individual or group. Examples of surveillance technology include, but is not limited to the following: cell site simulators (Stingrays); automatic license plate readers; gunshot detectors (ShotSpotter); facial recognition software; thermal imaging systems; body-worn cameras; social media analytics software; gait analysis software; video cameras that record audio or video, and transmit or can be remotely accessed. It also includes software designed to monitor social media services or forecast criminal activity or criminality, biometric identification hardware or software.

"Surveillance technology" does not include the following devices or hardware, unless they have been equipped with, or are modified to become or include, a surveillance technology as defined above:

A. Routine office hardware, such as televisions, computers, credit card machines, badge readers, copy machines, and printers, that is in widespread use and will not be used for any surveillance or law enforcement functions;

B. Parking Ticket Devices (PTDs);

Formatted: Not Highlight

C. Manually-operated, non-wearable, handheld digital cameras, audio recorders, and video recorders that are not designed to be used surreptitiously and whose functionality is limited to manually capturing and manually downloading video and/or audio recordings;

D. Surveillance devices that cannot record or transmit audio or video or be remotely accessed, such as image stabilizing binoculars or night vision goggles;

E. Manually-operated technological devices used primarily for internal municipal entity communications and are not designed to surreptitiously collect surveillance data, such as radios and email systems;

F. City databases that do not contain any data or other information collected, captured, recorded, retained, processed, intercepted, or analyzed by surveillance technology, including payroll, accounting, or other fiscal databases.

G. Medical equipment used to diagnose, treat, or prevent disease or injury.

H. Police department interview room cameras.

I. Police department case management and records management systems-, including computer aided dispatch systems, and field-based reporting systems.

J. Police department early warning systems.

K. Personal communication devices that have not been modified beyond stock manufacturer capabilities in a manner described above, provided that any bundled face recognition technology is only used for the sole purpose of user authentication in the regular course of conducting City business.

15. "Surveillance Impact Report" means a publicly-released written report including at a minimum the following:

A. Description: information describing the surveillance technology and how it works, including product descriptions and manuals from manufacturers;

B. Purpose: information on the proposed purposes(s) for the surveillance technology;

C. Location: the location(s) it may be deployed, using general descriptive terms, and crime statistics for any location(s);

D. Impact: an assessment of the technology's adopted use policy and whether it is adequate in protecting civil rights and liberties and whether the surveillance technology was used or deployed, intentionally or inadvertently, in a manner that is discriminatory, viewpoint-based, or biased via algorithm;

E. Mitigations: identify specific, affirmative technical and procedural measures that will be implemented to safeguard the public from each such impacts;

F. Data Types and Sources: a list of all types and sources of data to be collected, analyzed, or processed by the surveillance technology, including "open source" data, scores, reports, logic or algorithm used, and any additional information derived therefrom;

G. Data Security: information about the steps that will be taken to ensure that adequate security measures are used to safeguard the data collected or generated by the technology from unauthorized access or disclosure;

H. Fiscal Cost: the fiscal costs for the surveillance technology, including initial purchase, personnel and other ongoing costs, <u>the operative or proposed contract</u>, and any current or potential sources of funding;

I. Third Party Dependence: whether use or maintenance of the technology will require data gathered by the technology to be handled or stored by a third-party vendor on an ongoing basis;

J. Alternatives: a summary of all alternative methods (whether involving the use of a new technology or not) considered before deciding to use the proposed surveillance technology, including the costs and benefits associated with each alternative and an explanation of the reasons why each alternative is inadequate; and,

K. Track Record: a summary of the experience (if any) other entities, especially government entities, have had with the proposed technology, including, if available, quantitative information about the effectiveness of the proposed technology in achieving its stated purpose in other jurisdictions, and any known adverse information about the technology (such as unanticipated costs, failures, or civil rights and civil liberties abuses).

16. "Surveillance Use Policy" means a publicly-released and legally enforceable policy for use of the surveillance technology that at a minimum specifies the following:

A. Purpose: the specific purpose(s) that the surveillance technology is intended to advance;

B. Authorized Use: the specific uses that are authorized, and the rules and processes required prior to such use;

C. Data Collection: the information that can be collected by the surveillance technology. Where applicable, list any data sources the technology will rely upon, including "open source" data;

D. Data Access: the category of individuals who can access or use the collected information, and the rules and processes required prior to access or use of the information;

E. Data Protection: the safeguards that protect information from unauthorized access, including encryption and access control mechanisms;

F. Data Retention: the time period, if any, for which information collected by the surveillance technology will be routinely retained, the reason such retention period is appropriate to further

the purpose(s), the process by which the information is regularly deleted after that period lapses, and the specific conditions that must be met to retain information beyond that period;

G. Public Access: how collected information can be accessed or used by members of the public, including criminal defendants;

H. Third Party Data Sharing: if and how other city departments, bureaus, divisions, or non-city entities can access or use the information, including any required justification or legal standard necessary to do so and any obligations imposed on the recipient of the information;

L______, Training: the training required for any individual authorized to use the surveillance technology or to access information collected by the surveillance technology, <u>and the category of staff that</u> will provide the training;

J. Auditing and Oversight: the mechanisms to ensure that the Surveillance Use Policy is followed, including internal personnel assigned to ensure compliance with the policy, internal recordkeeping of the use of the technology or access to information collected by the technology, technical measures to monitor for misuse, any independent person or entity with oversight authority, and the legally enforceable sanctions for violations of the policy; and

K. Maintenance: The mechanisms and procedures to ensure that the security and integrity of the surveillance technology and collected information will be maintained.

17. "Voice Recognition Technology" means the automated or semi-automated process that assists in identifying or verifying an individual based on the characteristics of an individual's voice.

(Ord. No. 13563, § 3, 9-17-2019; Ord. No. 13489, § 2, 5-15-2018)

9.64.020 - Privacy Advisory Commission (PAC) notification and review requirements.

1. PAC Notification Required Prior to City Solicitation of Funds and Proposals for Surveillance Technology.

A. City staff shall notify the Chair of the Privacy Advisory Commission prior to:

1. Seeking or soliciting funds for <u>new</u> surveillance technology <u>or to replace existing</u> surveillance technology that has not been previously approved by the City Council pursuant to the requirements of this Chapter, including but not limited to applying for a grant; or,

2. Soliciting proposals with a non-city entity to acquire, share or otherwise use surveillance technology or the information it provides.

B. Upon notification by city staff, the Chair of the Privacy Advisory Commission shall place the item on the agenda at the next Privacy Advisory Commission meeting for discussion and possible action. At this meeting, city staff shall inform the Privacy Advisory Commission of the need for the funds or equipment, or shall otherwise justify the action city staff will seek Council

Formatted: Font: 11 pt Formatted: Font: 11 pt, Not Highlight

approval for pursuant to 9.64.030. The Privacy Advisory Commission may make a recommendation to the City Council by voting its approval to proceed, object to the proposal, recommend that the city staff modify the proposal, or take no action.

C. Should the Privacy Advisory Commission not make a recommendation pursuant to 9.64.020 1.B., City staff may proceed and seek Council approval of the proposed surveillance technology initiative pursuant to the requirements of Section 9.64.030.

2. PAC Review Required for New Surveillance Technology Before City Council Approval.

A. Prior to seeking City Council approval under Section 9.64.030, city staff shall submit a surveillance impact report and a surveillance use policy for the proposed new surveillance technology initiative to the Privacy Advisory Commission for its review at a regularly noticed meeting. The surveillance impact report and surveillance use policy must address the specific subject matter specified for such reports as defined under 9.64.010.

B. The Privacy Advisory Commission shall recommend that the City Council adopt, modify, or reject the proposed surveillance use policy. If the Privacy Advisory Commission proposes that the Surveillance Use Policy be modified, the Privacy Advisory Commission shall propose such modifications to city staff. City staff shall present such modifications to City Council when seeking City Council approval under Section 9.64.030.

C. Failure by the Privacy Advisory Commission to make its recommendation on the item within ninety (90) days of submission shall enable the city entity to proceed to the City Council for approval of the item.

3. PAC Review Requirements for Existing Surveillance Technology Before City Council Approval.

A. Prior to seeking City Council approval for existing city surveillance technology under Section 9.64.030 city staff shall submit a surveillance impact report and surveillance use policy to the Privacy Advisory Commission for its review at a regularly noticed meeting. The surveillance impact report and surveillance use policy must address the specific subject matter specified for such reports as defined under 9.64.010.

B. Prior to submitting the surveillance impact report and proposed surveillance use policy as described above, city staff shall present to the Privacy Advisory Commission a list of surveillance technology possessed and/or used by the city.

C. The Privacy Advisory Commission shall rank the items in order of potential impact to civil liberties.

D. Within sixty (60) days of the Privacy Advisory Commission's action in 9.64.020 1.C., city staff shall submit at least one (1) surveillance impact report and proposed surveillance use policy per month to the Privacy Advisory Commission for review, beginning with the highest-

ranking items as determined by the Privacy Advisory Commission, and continuing thereafter each month until a policy has been submitted for each item on the list.

E. Failure by the Privacy Advisory Commission to make its recommendation on any item within ninety (90) days of submission shall enable city staff to proceed to the City Council for approval of the item pursuant to Section 9.64.030.

(Ord. No. 13489, § 2, 5-15-2018)

9.64.030. - City Council approval requirements for new and existing surveillance technology.

1. City staff must obtain City Council approval prior to any of the following:

A. Accepting state or federal funds or in-kind or other donations for surveillance technology. <u>except for surveillance technology that has a City Council approved corresponding use policy in</u> <u>effect;</u>

B. Acquiring new surveillance technology, <u>or replacing existing surveillance technology that</u> <u>has not been previously approved by the City Council pursuant to the requirements of this</u> <u>Chapter</u>, including but not limited to procuring such technology without the exchange of monies or consideration;

C. Using new surveillance technology, or using existing surveillance technology or the information it provides for a purpose, in a manner, or in a location not previously approved by the City Council pursuant to the requirements of this Chapter, except that for surveillance technology that has been acquired or is in use prior to enactment of this ordinance, such use may continue until the City Council votes to approve or reject the surveillance technology's corresponding use policy; or

D. Entering into a continuing agreement or written agreement with a non-city entity to acquire, share or otherwise use surveillance technology or the information it provides, including data sharing agreements.

E. Notwithstanding any other provision of this Section, nothing herein shall be construed to prevent, restrict or interfere with any person providing evidence or information derived from surveillance technology to a law enforcement agency for the purposes of conducting a criminal investigation or the law enforcement agency from receiving such evidence or information.

2. City Council Approval Process.

I

A. After the PAC notification and review requirements in Section 9.64.020 have been met, city staff seeking City Council approval shall schedule for City Council consideration and approval of the proposed surveillance impact report and proposed surveillance use policy, and include Privacy Advisory Commission recommendations at least fifteen (15) days prior to a mandatory,

properly-noticed, germane public hearing. Approval may only occur at a public hearing. <u>City</u> <u>staff shall not unreasonably delay scheduling any item for City Council consideration at the next</u> earliest opportunity.

B. The City Council shall only approve any action as provided in this Article after first considering the recommendation of the Privacy Advisory Commission, and subsequently making a determination that the benefits to the community of the surveillance technology outweigh the costs; that the proposal will safeguard civil liberties and civil rights; and that, in the City Council's judgment, no alternative with a lesser economic cost or impact on civil rights or civil liberties would be as effective.

C. For approval of existing surveillance technology for which the Privacy Advisory Commission failed to make its recommendation within ninety (90) days of review as provided for under 9.64.020 3.E, if the City Council has not reviewed and approved such item within four (4) City Council meetings from when the item was initially scheduled for City Council consideration, the city shall cease its use of the surveillance technology until such review and approval occurs.

3. Surveillance Impact Reports and Surveillance Use Policies are Public Records. City staff shall make the Surveillance Impact Report and Surveillance Use Policy, as updated from time to time, available to the public as long as the city uses the surveillance technology in accordance with its request pursuant to Section 9.64.020 A.1.

(Ord. No. 13489, § 2, 5-15-2018)

9.64.035 - Use of unapproved technology during exigent circumstances or large-scale event.

1. City staff may temporarily acquire or use surveillance technology and the data derived from that use in a manner not expressly allowed by a surveillance use policy in two (2) types of circumstances without following the provisions of Section 9.64.030: (A) exigent circumstances, and (B) a large-scale event.

2. If city staff acquires or uses a surveillance technology in the two (2) circumstances pursuant to subdivision 1., the city staff shall:

A. Use the surveillance technology to solely respond to the exigent circumstances or largescale event.

B. Cease using the surveillance technology when the exigent circumstances or large scale event ends.

C. Only keep and maintain data related to the exigent circumstances and dispose of any data that is not relevant to an ongoing investigation.

D. Following the end of the exigent circumstances or large-scale event, report that acquisition or use to the PAC at their next respective meetings for discussion and/or possible

recommendation to the City Council in accordance with the Sunshine Ordinance, the Brown Act, and City Administrator deadlines.

3. Any technology temporarily acquired in exigent circumstances or during a large-scale event shall be returned within seven (7) days following its acquisition, or when the exigent circumstances end, whichever is sooner, unless the technology is submitted to the City Council for approval pursuant to Section 9.64.030 and is approved. If the agency is unable to comply with the seven-day timeline, the agency shall notify the City Council, who may grant an extension.

(Ord. No. 13489, § 2, 5-15-2018)

9.64.040 - Oversight following City Council approval.

1. On March 30th March 15th of each year, or at the next closest regularly scheduled Privacy Advisory Commission meeting, city staff must present a written annual surveillance report for Privacy Advisory Commission review for each approved surveillance technology item. If city staff is unable to meet the deadline, city staff shall notify the Privacy Advisory Commission in writing of staff's request to extend this period, and the reasons for that request. The Privacy Advisory Commission may grant a single extension of up to sixty (60) days to comply with this provision.

A. After review by the Privacy Advisory Commission, city staff shall submit the annual surveillance report to the City Council.

B. The Privacy Advisory Commission shall recommend to the City Council that the benefits to the community of the surveillance technology outweigh the costs and that civil liberties and civil rights are safeguarded; that use of the surveillance technology cease; or propose modifications to the corresponding surveillance use policy that will resolve the concerns.

C. Failure by the Privacy Advisory Commission to make its recommendation on the item within ninety (90) days of submission shall enable the city entity to proceed to the City Council for approval of the annual surveillance report.

2. Based upon information provided in city staff's Annual Surveillance Report and after considering the recommendation of the Privacy Advisory Commission, the City Council shall revisit its "cost benefit" analysis as provided in Section 9.64.030 2.B. and either uphold or set aside the previous determination. Should the City Council set aside its previous determination, the city's use of the surveillance technology must cease. Alternatively, City Council may require modifications to the Surveillance Use Policy that will resolve any deficiencies.

(Ord. No. 13489, § 2, 5-15-2018)

Formatted: Font: 11 pt, Font color: Auto

Formatted: Superscript

9.64.045 - Prohibition on City's acquisition and<u>/or use of (i) biometric surveillance technology, or</u> (ii) predictive policing technology.

A. Notwithstanding any other provision of this Chapter (9.64), it shall be unlawful for the City or any City staff to obtain, retain, request, access, or use:

Biometric surveillance technology; or

2. Predictive policing technology; or

3. Information obtained from either biometric surveillance technology or predictive policing technology.

B. City staff's inadvertent or unintentional receipt, access of, or use of any information obtained from <u>biometric surveillance technology or predictive policing technology shall not be</u> a violation of this Section 9.64.045 provided that:

1. City staff did not request or solicit the receipt, access of, or use of such information; and

2. <u>City staff shall immediately destroy all copies of the information upon its discovery and</u> shall not use the information for any purpose, <u>unless retention or use of exculpatory evidence is</u> required by law; and

3. <u>City staff logs such receipt, access, or use in a written report provided at the next closest</u> regularly scheduled meeting after discovery of the use, to the Privacy Advisory Commission for discussion and possible recommendation to the City Council. Such a report shall not include any personally identifiable information or other information the release of which is prohibited by law. In its report, <u>City staff shall identify specific measures taken by the City to prevent the</u> further transmission or use of any information inadvertently or unintentionally obtained through the use of such technologies; and

4. After review by the Privacy Advisory Commission, city staff shall submit the report to the City Council.

(Ord. No. 13563, § 3, 9-17-2019)

9.64.050 - Enforcement.

1. Violations of this Article are subject to the following remedies:

A. Any violation of this Article, or of a surveillance use policy promulgated under this Article, constitutes an injury and any person may institute proceedings for injunctive relief, declaratory relief, or writ of mandate in the Superior Court of the State of California to enforce this Article. An action instituted under this paragraph shall be brought against the respective city department, and the City of Oakland, and, if necessary to effectuate compliance with this Article or a surveillance use policy (including to expunge information unlawfully collected, retained, or

shared thereunder), any other governmental agency with possession, custody, or control of data subject to this Article, to the extent permitted by law.

B. Any person who has been subjected to a surveillance technology in violation of this Article, or about whom information has been obtained, retained, accessed, shared, or used in violation of this Article or of a surveillance use policy promulgated under this Article, may institute proceedings in the Superior Court of the State of California against the City of Oakland and shall be entitled to recover actual damages (but not less than liquidated damages of one thousand dollars (\$1,000.00) or one hundred dollars (\$100.00) per day for each day of violation, whichever is greater).

C. A court shall award costs and reasonable attorneys' fees to the plaintiff who is the prevailing party in an action brought under paragraphs A. or B.

D. Violations of this Article by a city employee shall result in consequences that may include retraining, suspension, or termination, subject to due process requirements and in accordance with any memorandums of understanding with employee bargaining units.

(Ord. No. 13489, § 2, 5-15-2018)

9.64.060 - Secrecy of surveillance technology.

It shall be unlawful for the city to enter into any surveillance-related contract or other agreement that conflicts with the provisions of this Article, and any conflicting provisions in such future contracts or agreements, including but not limited to non-disclosure agreements, shall be deemed void and legally unenforceable.

To the extent permitted by law, the city shall publicly disclose all of its surveillance-related contracts, including any and all related non-disclosure agreements, if any, regardless of any contract terms to the contrary.

(Ord. No. 13489, § 2, 5-15-2018)

9.64.070 - Whistleblower protections.

1. Neither the city nor anyone acting on behalf of the city may take or fail to take, or threaten to take or fail to take, a personnel action with respect to any employee or applicant for employment, including but not limited to discriminating with respect to compensation, terms and conditions of employment, access to information, restrictions on due process rights, or civil or criminal liability, because:

A. The employee or applicant was perceived to, about to, or assisted in any lawful disclosure of information concerning the funding, acquisition, or use of a surveillance technology or surveillance data based upon a good faith belief that the disclosure evidenced a violation of this Article; or

B. The employee or applicant was perceived to, about to, or assisted or participated in any proceeding or action to carry out the purposes of this Article.

2. It shall be grounds for disciplinary action for a city employee or anyone else acting on behalf of the city to retaliate against another city employee or applicant who makes a good-faith complaint that there has been a failure to comply with any surveillance use policy or administrative instruction promulgated under this Article.

3. Any employee or applicant who is injured by a violation of this Section may institute a proceeding for monetary damages and injunctive relief against the city in any court of competent jurisdiction.

(Ord. No. 13489, § 2, 5-15-2018)

1

Chapter 9.64 - REGULATIONS ON CITY'S ACQUISITION AND USE OF SURVEILLANCE TECHNOLOGY

Sections:

9.64.010 - Definitions.

The following definitions apply to this Chapter.

1. "Annual Surveillance Report" means a written report concerning a specific surveillance technology that includes all the following:

A. A description of how the surveillance technology was used, including the type and quantity of data gathered or analyzed by the technology;

B. Whether and how often data acquired through the use of the surveillance technology was shared with outside entities-<u>if known and if practicable</u>, the name of any recipient entity <u>if known and if practicable</u>, the type(s) of data disclosed, under what legal standard(s) the information was disclosed, and the justification for the disclosure(s);

C. Where applicable, a breakdown of what physical objects the surveillance technology hardware was installed upon; using general descriptive terms so as not to reveal the specific location of such hardware; for surveillance technology software, a breakdown of what data sources the surveillance technology was applied to;

D. Where applicable, a breakdown of where the surveillance technology was deployed geographically, by each police area in the relevant year;

E. A summary of community complaints or concerns about the surveillance technology, and an analysis of the technology's adopted use policy and whether it is adequate in protecting civil rights and civil liberties. The analysis shall identify the race of each person that was subject to the technology's use. The Privacy Advisory Commission may determine, on an individual policy basis, to waive the obligation to identify the race of each person if the probative value is outweighed by the administrative burden and potential greater invasiveness in capturing such data. If the Privacy Advisory Commission makes such a determination, written findings in support of the determination shall be included in the annual report submitted for City Council review.

F. The results of any internal audits, any information about violations or potential violations of the Surveillance Use Policy, and any actions taken in response unless the release of such information is prohibited by law, including but not limited to confidential personnel file information.

Commented [BS1]: Officers may legitimately share records with other local depts. Same with a TRAK flyer. OPD would need to institute new policies and systems to require tracking every time any officer shares any leads acquired through any technology with anyone from another department (e.g. OPD may share an ALPR jpeg that contains data such as car color...through an email – this could not be tracked per standard ways OPD works with other departments).

Commented [BS2]: OPD appreciates this revised version for considering the administrative burden and potential greater invasiveness.

Commented [JB3R2]: While OPD tracks formal citizen complaints, the PAC would be more likely to receive general "complaints or concerns" about surveillance technology. Doesn't the PAC hold itself out as the proper forum for such complaints and concerns? OPD believes that the PAC may well be better situated to provide this summary. Similarly, the PAC was set up in order to assess OPD's use policies and "whether [they are] adequate in protecting civil rights and civil liberties." Again, this seems like an assessment the PAC is better situated than OPD to provide to the general public.

G. Information about any data breaches or other unauthorized access to the data collected by the surveillance technology, including information about the scope of the breach and the actions taken in response;

H. Information, including crime statistics, that helps the community assess whether the surveillance technology has been effective at achieving its identified purposes;

I. Statistics and information about public records act requests regarding the relevant subject surveillance technology, including response rates;

J. Total annual costs for the surveillance technology, including personnel and other ongoing costs, and what source of funding will fund the technology in the coming year; and

K. Any requested modifications to the Surveillance Use Policy and a detailed basis for the request.

 "Biometric Surveillance Technology" means any computer software that uses Face Recognition Technology or Other Remote Biometric Recognition in real time or on a recording or photograph.

3. "City" means any department, agency, bureau, and/or subordinate division of the City of Oakland as provided by Chapter 2.29 of the Oakland Municipal Code.

4. "City Staff" means City personnel authorized by the City Administrator or designee to seek City Council approval of surveillance technology in conformance with this Chapter.

5. "Continuing Agreement" means an agreement that automatically renews unless terminated by one (1) party.

6. "Exigent Circumstances" means a law enforcement agency's good faith belief that an emergency involving danger of, or imminent threat of the destruction of evidence regarding, death or serious physical injury to any person requires the use of surveillance technology or the information it provides.

7. "Face Recognition Technology" means (A) an automated or semi-automated process that assists in identifying or verifying an individual based on an individual's face; or (B) logs characteristics of an individual's face, head, or body to infer emotion, associations, expressions, or the location of an individual.

8. "Large-Scale Event" means an event attracting ten thousand (10,000) or more people with the potential to attract national media attention that provides a reasonable basis to anticipate that exigent circumstances may occur.

9. "Other Remote Biometric Recognition" means (A) an automated or semi-automated process that (i) assists in identifying an individual, capturing information about an individual, or otherwise generating or assisting in generating information about an individual based on

Commented [BS4]: Do all modifications to a Use Policy post-approval need to go to PAC and back to Council?

Commented [JB5]: This is confusing because it appears to be a definition of Biometric Surveillance Technology. But this definition does not include many technologies that the PAC deems biometric surveillance technology, such as equipment used by the Crime Lab for DNA analysis.

This should be removed or renamed. There is no need for the disjunction. The PAC can still ban "Other Remote Biometric Recognition Technology", which is defined in 9 below.

physiological, biological, or behavioral characteristics ascertained from a distance; (ii) uses voice recognition technology; or (iii) logs such characteristics to infer emotion, associations, activities, or the location of an individual, and (B) does not include identification based on fingerprints or palm prints that have been manually obtained during the course of a criminal investigation or detention.

10. "Personal Communication Device" means a mobile telephone, a personal digital assistant, a wireless capable tablet and a similar wireless two-way communications and/or portable internet accessing devices, whether procured or subsidized by a city entity or personally owned, that is used in the regular course of city business.

11. "Predictive Policing Technology" means computer algorithms that use preexisting data to forecast or predict places or times that have a high risk of crime, or individuals or groups who are likely to commit a crime. This definition does not include computer algorithms used solely to visualize, chart, or map past criminal activity (e.g. heat maps).

12. "Police Area" refers to each of the geographic districts assigned to a police commander and as such districts are amended from time to time.

13. "Surveillance" or "Surveil" means to observe or analyze the movements, behavior, data, or actions of individuals. Individuals include those whose identity can be revealed by license plate data when combined with any other record.

14. "Surveillance Technology" means any software, electronic device, system utilizing an electronic device, or similar technological tool used, designed, or primarily intended to collect, retain, analyze, process, or share audio, electronic, visual, location, thermal, olfactory, biometric, or similar information specifically associated with, or capable of being associated with, any individual or group. Examples of surveillance technology include, but is not limited to the following: cell site simulators (Stingrays); automatic license plate readers; gunshot detectors (ShotSpotter); facial recognition software; thermal imaging systems; body-worn cameras; social media analytics software; gait analysis software; video cameras that record audio or video, and transmit or can be remotely accessed. It also includes software designed to monitor social media services or forecast criminal activity or criminality, biometric identification hardware or software.

"Surveillance technology" does not include the following devices or hardware, unless they have been equipped with, or are modified to become or include, a surveillance technology as defined above:

A. Routine office hardware, such as televisions, computers, credit card machines, badge readers, copy machines, and printers, that is in widespread use and will not be used for any surveillance or law enforcement functions;

B. Parking Ticket Devices (PTDs);

Commented [BS6]: OPD appreciates this revised definition. Changing to "predict specific places or specific times" may still offer a more focused definition. C. Manually-operated, non-wearable, handheld digital cameras, audio recorders, and video recorders that are not designed to be used surreptitiously and whose functionality is limited to manually capturing and manually downloading video and/or audio recordings;

D. Surveillance devices that cannot record or transmit audio or video or be remotely accessed, such as image stabilizing binoculars or night vision goggles;

E. Manually-operated technological devices used primarily for internal municipal entity communications and are not designed to surreptitiously collect surveillance data, such as radios and email systems;

F. City databases that do not contain any data or other information collected, captured, recorded, retained, processed, intercepted, or analyzed by surveillance technology, including payroll, accounting, or other fiscal databases.

G. Medical equipment used to diagnose, treat, or prevent disease or injury.

- H. Police department interview room cameras.
 - Police department case management and records management systems, including computer aided dispatch systems, and field-based reporting systems.
- J. Police department early warning systems.

K. Personal communication devices that have not been modified beyond stock manufacturer capabilities in a manner described above.

- L. Forensic instrumentation, equipment, reagents and standards that are used by the Oakland Police Department Criminalistics Laboratory (Crime Lab) as of August 2020 to analyze evidence samples collected in the course of an investigation, that upon analysis by the Crime Lab, may result in the identification of individual persons. A list of specific items is in Appendix A.
- i. Like for like substitutions necessitated by improvements to current methodology, instrumentation failures or maintaining compliance with Federal Law will also be excluded.

ii. Entirely new biometric methodology outside the current scope of accreditation of the laboratory would require the laboratory to seek permission from the accreditation agency. This would also precipitate involvement of the Privacy Commission.

M. Live Scan machines (owned by the Alameda County Sheriff's Department but operated by OPD personnel).

15. "Surveillance Impact Report" means a publicly-released written report including at a minimum the following:

Commented [7]: Need more info from OPD re their proposed amendment to include records management systems, CAD, and field based reporting systems. AB 953

 $\label{eq:commented_based} \begin{array}{c} \mbox{Commented [BS8R7]: } \mbox{PAC}-\mbox{are we clear on reasons} \\ \mbox{for this addition?} \end{array}$

Commented [BS9]: This addition is requested by the OPD Crime Lab Manager. OPD is arguing that these specific tools can be considered "biometric" per definition above of "surveillance technology." But in this case not everything that is "biometric" is surveillance. Perhaps a different form of exemption could be for forensic technology that is NOT used in real time or in the immediate presence of an individual or person. Crime Lab perspective - the technology is always used with a nexus of an actual crime - no prospective use of this biometric technology. We are trying to draw a balance between what is "surveillance" and simply forensic analysis. Staff think that the administrative burden of collating data for 270+ types of equipment into one or more Use Policies and then annual reports far exceeds the informational value achieved.

Commented [BJJ10]: OPD personnel use these stationary machines to conduct sex registrant fingerprinting, court bookings, juvenile in-custody fingerprinting, and applicant fingerprinting.

A. Description: information describing the surveillance technology and how it works, including product descriptions and manuals (as attachments, if publicly available and current) from manufacturers;

B. Purpose: information on the proposed purposes(s) for the surveillance technology;

C. Location: the location(s) it may be deployed, using general descriptive terms, and crime statistics for any location(s);

D. Impact: an assessment of the technology's adopted use policy and whether it is adequate in protecting civil rights and liberties and whether the surveillance technology was used or deployed, intentionally or inadvertently, in a manner that is discriminatory, viewpoint-based, or biased via algorithm;

E. Mitigations: identify specific, affirmative technical and procedural measures that will be implemented to safeguard the public from each such impacts;

F. Data Types and Sources: a list of all types and sources of data to be collected, analyzed, or processed by the surveillance technology, including "open source" data, scores, reports, logic or algorithm used, and any additional information derived therefrom;

G. Data Security: information about the steps that will be taken to ensure that adequate security measures are used to safeguard the data collected or generated by the technology from unauthorized access or disclosure;

H. Fiscal Cost: the fiscal costs for the surveillance technology, including initial purchase, personnel and other ongoing costs, the operative or proposed contract <u>if available</u> - or past <u>contract if available</u>, and any current or potential sources of funding;

I. Third Party Dependence: whether use or maintenance of the technology will require data gathered by the technology to be handled or stored by a third-party vendor on an ongoing basis;

J. Alternatives: a summary of all alternative methods (whether involving the use of a new technology or not) considered before deciding to use the proposed surveillance technology, including the costs and benefits associated with each alternative and an explanation of the reasons why each alternative is inadequate; and,

K. Track Record: a summary of the experience (if any) other entities, especially government entities, have had with the proposed technology, including, if available, quantitative information about the effectiveness of the proposed technology in achieving its stated purpose in other jurisdictions, and any known adverse information about the technology (such as unanticipated costs, failures, or civil rights and civil liberties abuses).

16. "Surveillance Use Policy" means a publicly-released and legally enforceable policy for use of the surveillance technology that at a minimum specifies the following:

Commented [BS11]: As long as there IS a manual and it is not very outdated, staff can comply.

Commented [BS12]: Staff may pursue a Use Policy as in drone/UAS before even having a final plan to purchase, or a choice of vendor. Even a proposed contract may not be available. A. Purpose: the specific purpose(s) that the surveillance technology is intended to advance;

B. Authorized Use: the specific uses that are authorized, and the rules and processes required prior to such use;

C. Data Collection: the information that can be collected by the surveillance technology. Where applicable, list any data sources the technology will rely upon, including "open source" data;

D. Data Access: the category of individuals who can access or use the collected information, and the rules and processes required prior to access or use of the information;

E. Data Protection: the safeguards that protect information from unauthorized access, including encryption and access control mechanisms;

F. Data Retention: the time period, if any, for which information collected by the surveillance technology will be routinely retained, the reason such retention period is appropriate to further the purpose(s), the process by which the information is regularly deleted after that period lapses, and the specific conditions that must be met to retain information beyond that period;

G. Public Access: how collected information can be accessed or used by members of the public, including criminal defendants;

H. Third Party Data Sharing: if and how other city departments, bureaus, divisions, or non-city entities can access or use the information, including any required justification or legal standard necessary to do so and any obligations imposed on the recipient of the information;

I. Training: the training required for any individual authorized to use the surveillance technology or to access information collected by the surveillance technology, and the category of staff that will provide the training;

J. Auditing and Oversight: the mechanisms to ensure that the Surveillance Use Policy is followed, including internal personnel assigned to ensure compliance with the policy, internal recordkeeping of the use of the technology or access to information collected by the technology, technical measures to monitor for misuse, any independent person or entity with oversight authority, and the legally enforceable sanctions for violations of the policy; and

K. Maintenance: The mechanisms and procedures to ensure that the security and integrity of the surveillance technology and collected information will be maintained.

L. Reporting: Any modifications to the required elements of the Annual Surveillance Report for this particular technology.

17. "Voice Recognition Technology" means the automated or semi-automated process that assists in identifying or verifying an individual based on the characteristics of an individual's voice.

(Ord. No. 13563, § 3, 9-17-2019; Ord. No. 13489, § 2, 5-15-2018)

Commented [BS13]: For PAC: OPD cannot commit to a permanent decision as to who or what type of staff will produce the training. OPD will ensure that the proper training occurs and that such training is required per Use Policy.

Commented [BS14]: May not be necessary now given PAC change to 9.64.010.E

Commented [JB15R14]: This is still necessary to allow flexibility. "Not applicable" will occasionally suffice, but it is important to have the flexibility to exempt certain technologies from certain reporting requirements.

9.64.020 - Privacy Advisory Commission (PAC) notification and review requirements.

1. PAC Notification Required Prior to City Solicitation of Funds and Proposals for Surveillance Technology.

A. City staff shall notify the Chair of the Privacy Advisory Commission prior to:

1. Seeking or soliciting funds for surveillance technology, including but not limited to applying for a grant; or,

2. Soliciting proposals with a non-city entity to acquire, share or otherwise use surveillance technology or the information it provides.

B. Upon notification by city staff, the Chair of the Privacy Advisory Commission shall place the item on the agenda at the next Privacy Advisory Commission meeting for discussion and possible action. At this meeting, city staff shall inform the Privacy Advisory Commission of the need for the funds or equipment, or shall otherwise justify the action city staff will seek Council approval for pursuant to 9.64.030. The Privacy Advisory Commission may make a recommendation to the City Council by voting its approval to proceed, object to the proposal, recommend that the city staff modify the proposal, or take no action.

C. Should the Privacy Advisory Commission not make a recommendation pursuant to 9.64.020 1.B., City staff may proceed and seek Council approval of the proposed surveillance technology initiative pursuant to the requirements of Section 9.64.030.

2. PAC Review Required for New Surveillance Technology Before City Council Approval.

A. Prior to seeking City Council approval under Section 9.64.030, city staff shall submit a surveillance impact report and a surveillance use policy for the proposed new surveillance technology initiative to the Privacy Advisory Commission for its review at a regularly noticed meeting. The surveillance impact report and surveillance use policy must address the specific subject matter specified for such reports as defined under 9.64.010.

B. The Privacy Advisory Commission shall recommend that the City Council adopt, modify, or reject the proposed surveillance use policy. If the Privacy Advisory Commission proposes that the Surveillance Use Policy be modified, the Privacy Advisory Commission shall propose such modifications to city staff. City staff shall present such modifications to City Council when seeking City Council approval under Section 9.64.030.

C. Failure by the Privacy Advisory Commission to make its recommendation on the item within ninety (90) days of submission shall enable the city entity to proceed to the City Council for approval of the item.

3. PAC Review Requirements for Existing Surveillance Technology Before City Council Approval.

A. Prior to seeking City Council approval for existing city surveillance technology under Section 9.64.030 city staff shall submit a surveillance impact report and surveillance use policy to the Privacy Advisory Commission for its review at a regularly noticed meeting. The surveillance impact report and surveillance use policy must address the specific subject matter specified for such reports as defined under 9.64.010.

B. Prior to submitting the surveillance impact report and proposed surveillance use policy as described above, city staff shall present to the Privacy Advisory Commission a list of surveillance technology possessed and/or used by the city.

C. The Privacy Advisory Commission shall rank the items in order of potential impact to civil liberties.

D. Within sixty (60) days of the Privacy Advisory Commission's action in 9.64.020 1.C., city staff shall submit at least one (1) surveillance impact report and proposed surveillance use policy per month, after the PAC completes a recommendation for a different surveillance technology, to the Privacy Advisory Commission for review, beginning with the highest-ranking items as determined by both the Privacy Advisory Commission and staff, and continuing thereafter each month until a policy has been submitted for each item on the list.

E. Failure by the Privacy Advisory Commission to make its recommendation on any item within ninety (90) days of submission shall enable city staff to proceed to the City Council for approval of the item pursuant to Section 9.64.030.

(Ord. No. 13489, § 2, 5-15-2018)

9.64.030. - City Council approval requirements for new and existing surveillance technology.

1. City staff must obtain City Council approval prior to any of the following:

A. Accepting state or federal funds or in-kind or other donations for surveillance technology;

B. Acquiring new surveillance technology, or replacing existing surveillance technology that has not been previously approved by the City Council pursuant to the requirements of this Chapter, including but not limited to procuring such technology without the exchange of monies or consideration;

C. Using new surveillance technology, or using <u>Council-approved-</u>existing surveillance technology or the information it provides for a purpose, in a manner, or in a location not previously approved by the City Council pursuant to the requirements of this Chapter; or

Commented [BS16]: This one technology per-month pace is not realistic, given the nature of the scrutiny and review and related staff time – as well as PAC capacity. We need a different standard - see addition in track changes.

Commented [BS17]: Departments might accept without a fully developed spending plan, or may need to change plans

Commented [BS18]: This phrase looks good to solve issue in next comment.

Commented [BS19]: This phrase can be interpreted to mean that city departments are in violation of this section for every piece of "existing surveillance technology" until the surveillance use policy is approved – a process that already takes years for OPD

Commented [BS20]: This intent of this revision is to clarify that PAC/Council must approve use of all tech and the way it is used, but deal with problem in comment above.

E. Entering into a continuing agreement or written agreement with a non-city entity to acquire, share or otherwise use surveillance technology or the information it provides, including data sharing agreements.

F. Notwithstanding any other provision of this Section, nothing herein shall be construed to prevent, restrict or interfere with any person providing evidence or information derived from surveillance technology to a law enforcement agency for the purposes of conducting a criminal investigation or the law enforcement agency from receiving such evidence or information.

2. City Council Approval Process.

A. After the PAC notification and review requirements in Section 9.64.020 have been met, city staff seeking City Council approval shall schedule for City Council consideration and approval of the proposed surveillance impact report and proposed surveillance use policy, and include Privacy Advisory Commission recommendations at least fifteen (15) days prior to a mandatory, properly-noticed, germane public hearing. Approval may only occur at a public hearing. <u>City</u> staff shall not unreasonably delay scheduling any item for City Council consideration.

B. The City Council shall only approve any action as provided in this Article after first considering the recommendation of the Privacy Advisory Commission, and subsequently making a determination that the benefits to the community of the surveillance technology outweigh the costs; that the proposal will safeguard civil liberties and civil rights; and that, in the City Council's judgment, no alternative with a lesser economic cost or impact on civil rights or civil liberties would be as effective.

C. For approval of existing surveillance technology for which the Privacy Advisory Commission failed to make its recommendation within ninety (90) days of review as provided for under 9.64.020 3.E, if the City Council has not reviewed and approved such item within four (4) City Council meetings from when the item was initially scheduled for City Council consideration, the city shall cease its use of the surveillance technology until such review and approval occurs.

3. Surveillance Impact Reports and Surveillance Use Policies are Public Records. City staff shall make the Surveillance Impact Report and Surveillance Use Policy, as updated from time to time, available to the public as long as the city uses the surveillance technology in accordance with its request pursuant to Section 9.64.020 A.1.

(Ord. No. 13489, § 2, 5-15-2018)

9.64.035 - Use of unapproved technology during exigent circumstances or large-scale event.

1. City staff may temporarily acquire or use surveillance technology and the data derived from that use in a manner not expressly allowed by a surveillance use policy in two (2) types of

Commented [21]: Make sure OPD understands this does not pertain to prohibited tech in Section 9.64.045

Commented [JB22]: For City Attorney: Does this provision require all changes to a Use Policy to go back to the City Council for approval? And would this override those use policies (e.g., the BWC/PDRD policy) that are overseen by the IMT and the Police Commission?

Commented [BS23]: Public hearing? Goal is to not have on closed session, does not need to be "public hearing." Review with OCA.

circumstances without following the provisions of Section 9.64.030: (A) exigent circumstances, and (B) a large-scale event.

2. If city staff acquires or uses a surveillance technology in the two (2) circumstances pursuant to subdivision 1., the city staff shall:

A. Use the surveillance technology to solely respond to the exigent circumstances or largescale event.

B. Cease using the surveillance technology when the exigent circumstances or large scale event ends.

C. Only keep and maintain data related to the exigent circumstances and dispose of any data that is not relevant to an ongoing investigation.

D. Following the end of the exigent circumstances or large-scale event, report that acquisition or use to the PAC at their next respective meetings for discussion and/or possible recommendation to the City Council in accordance with the Sunshine Ordinance, the Brown Act, and City Administrator deadlines.

3. Any technology temporarily acquired in exigent circumstances or during a large-scale event shall be returned within seven (7) days following its acquisition, or when the exigent circumstances end, whichever is sooner, unless the technology is submitted to the City Council for approval pursuant to Section 9.64.030 and is approved. If the agency is unable to comply with the seven-day timeline, the agency shall notify the City Council, who may grant an extension.

(Ord. No. 13489, § 2, 5-15-2018)

9.64.040 - Oversight following City Council approval.

1. For each approved surveillance technology item, city staff must present a written annual surveillance report for Privacy Advisory Commission review by April 30 of the following year a year from the date that the corresponding use policy was approved by the City Council, and annually thereafter as long as the technology is in use. If city staff is unable to meet the deadline, city staff shall notify the Privacy Advisory Commission in writing of staff's request to extend this period, and the reasons for that request. The Privacy Advisory Commission may grant a single extension of up to sixty (60) days to comply with this provision.

A. After review by the Privacy Advisory Commission, city staff shall submit the annual surveillance report to the City Council.

B. The Privacy Advisory Commission shall recommend to the City Council that the benefits to the community of the surveillance technology outweigh the costs and that civil liberties and civil

rights are safeguarded; that use of the surveillance technology cease; or propose modifications to the corresponding surveillance use policy that will resolve the concerns.

C. Failure by the Privacy Advisory Commission to make its recommendation on the item within ninety (90) days of submission shall enable the city entity to proceed to the City Council for approval of the annual surveillance report.

2. Based upon information provided in city staff's Annual Surveillance Report and after considering the recommendation of the Privacy Advisory Commission, the City Council shall revisit its "cost benefit" analysis as provided in Section 9.64.030 2.B. and either uphold or set aside the previous determination. Should the City Council set aside its previous determination, the city's use of the surveillance technology must cease. Alternatively, City Council may require modifications to the Surveillance Use Policy that will resolve any deficiencies.

(Ord. No. 13489, § 2, 5-15-2018)

9.64.045 - Prohibition on City's acquisition and/or use of (i) biometric surveillance technology, or (ii) predictive policing technology

A. Notwithstanding any other provision of this Chapter (9.64), it shall be unlawful for the City or any City staff to obtain, retain, request, access, or use:

1. Biometric surveillance technology; or

Predictive policing technology; or

 Information obtained from either biometric surveillance technology or predictive policing technology.

B. City staff's inadvertent or unintentional receipt, access of, or use of any information obtained from biometric surveillance technology or predictive policing technology shall not be a violation of this Section 9.64.045 provided that:

1. City staff did not request or solicit the receipt, access of, or use of such information; and

2. City staff shall immediately destroy all copies of the information upon its discovery and shall not use the information for any purpose, unless required by law; and

3. City staff logs such receipt, access, or use in a written report provided at the next closest regularly scheduled meeting after discovery of the use, to the Privacy Advisory Commission for discussion and possible recommendation to the City Council. Such a report shall not include any personally identifiable information or other information the release of which is prohibited by law. In its report, City staff shall identify specific measures taken by the City to prevent the

Commented [JB24]: See above comments about the definition.

Commented [BS25]: Should suffice staff need to keep exculpatory evidence.

further transmission or use of any information inadvertently or unintentionally obtained through the use of such technologies; and

4. After review by the Privacy Advisory Commission, city staff shall submit the report to the City Council.

(Ord. No. 13563, § 3, 9-17-2019)

9.64.050 - Enforcement.

1. Violations of this Article are subject to the following remedies:

A. Any violation of this Article, or of a surveillance use policy promulgated under this Article, constitutes an injury and any person may institute proceedings for injunctive relief, declaratory relief, or writ of mandate in the Superior Court of the State of California to enforce this Article. An action instituted under this paragraph shall be brought against the respective city department, and the City of Oakland, and, if necessary to effectuate compliance with this Article or a surveillance use policy (including to expunge information unlawfully collected, retained, or shared thereunder), any other governmental agency with possession, custody, or control of data subject to this Article, to the extent permitted by law.

B. Any person who has been subjected to a surveillance technology in violation of this Article, or about whom information has been obtained, retained, accessed, shared, or used in violation of this Article or of a surveillance use policy promulgated under this Article, may institute proceedings in the Superior Court of the State of California against the City of Oakland and shall be entitled to recover actual damages (but not less than liquidated damages of one thousand dollars (\$1,000.00) or one hundred dollars (\$100.00) per day for each day of violation, whichever is greater).

C. A court shall award costs and reasonable attorneys' fees to the plaintiff who is the prevailing party in an action brought under paragraphs A. or B.

D. Violations of this Article by a city employee shall result in consequences that may include retraining, suspension, or termination, subject to due process requirements and in accordance with any memorandums of understanding with employee bargaining units.

(Ord. No. 13489, § 2, 5-15-2018)

9.64.060 - Secrecy of surveillance technology.

It shall be unlawful for the city to enter into any surveillance-related contract or other agreement that conflicts with the provisions of this Article, and any conflicting provisions in such future

contracts or agreements, including but not limited to non-disclosure agreements, shall be deemed void and legally unenforceable.

To the extent permitted by law, the city shall publicly disclose all of its surveillance-related contracts, including any and all related non-disclosure agreements, if any, regardless of any contract terms to the contrary.

(Ord. No. 13489, § 2, 5-15-2018)

9.64.070 - Whistleblower protections.

1. Neither the city nor anyone acting on behalf of the city may take or fail to take, or threaten to take or fail to take, a personnel action with respect to any employee or applicant for employment, including but not limited to discriminating with respect to compensation, terms and conditions of employment, access to information, restrictions on due process rights, or civil or criminal liability, because:

A. The employee or applicant was perceived to, about to, or assisted in any lawful disclosure of information concerning the funding, acquisition, or use of a surveillance technology or surveillance data based upon a good faith belief that the disclosure evidenced a violation of this Article; or

B. The employee or applicant was perceived to, about to, or assisted or participated in any proceeding or action to carry out the purposes of this Article.

2. It shall be grounds for disciplinary action for a city employee or anyone else acting on behalf of the city to retaliate against another city employee or applicant who makes a good-faith complaint that there has been a failure to comply with any surveillance use policy or administrative instruction promulgated under this Article.

3. Any employee or applicant who is injured by a violation of this Section may institute a proceeding for monetary damages and injunctive relief against the city in any court of competent jurisdiction.

(Ord. No. 13489, § 2, 5-15-2018)